

# --Hyper K-- Calibration Source Deployment System

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On behalf of  
The Calibration WG



# Key Points

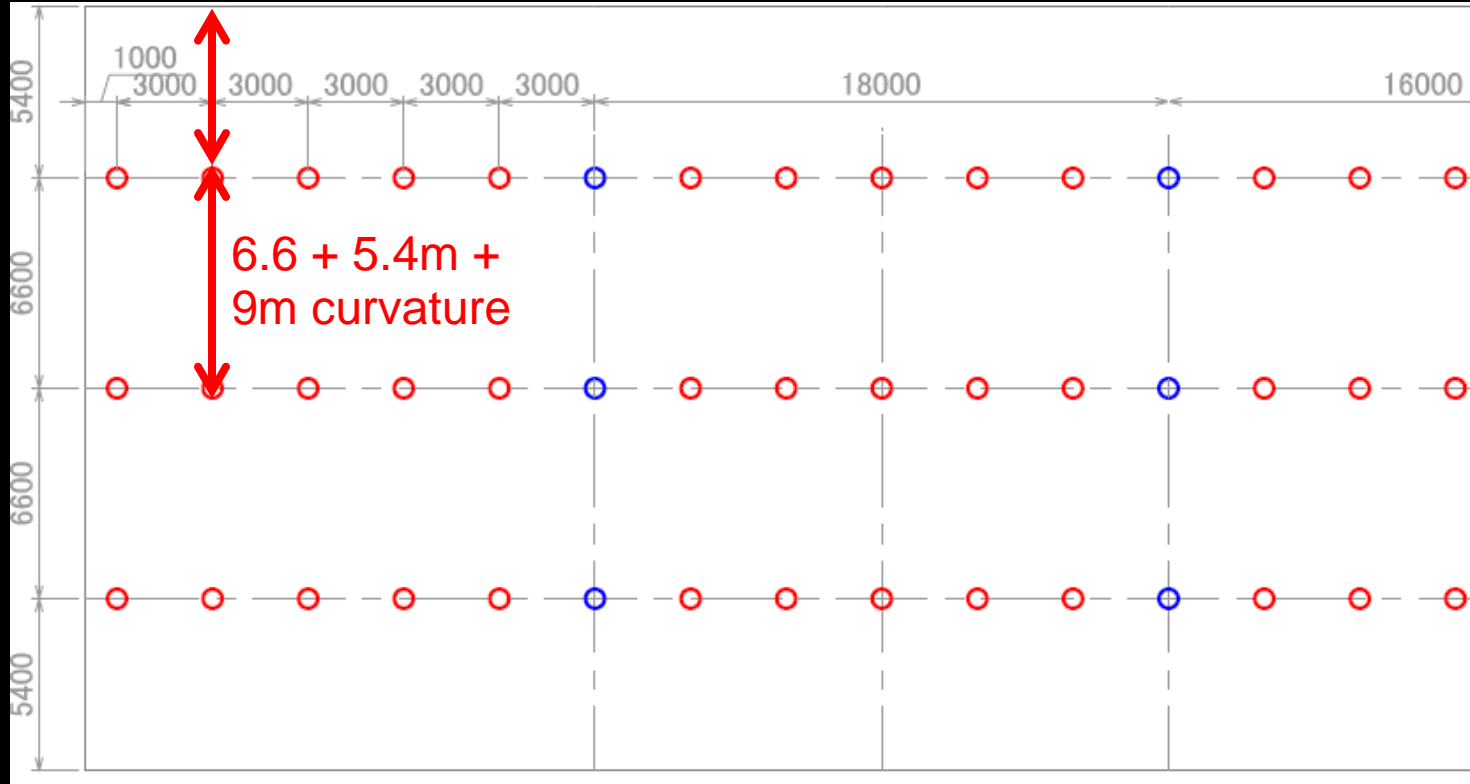
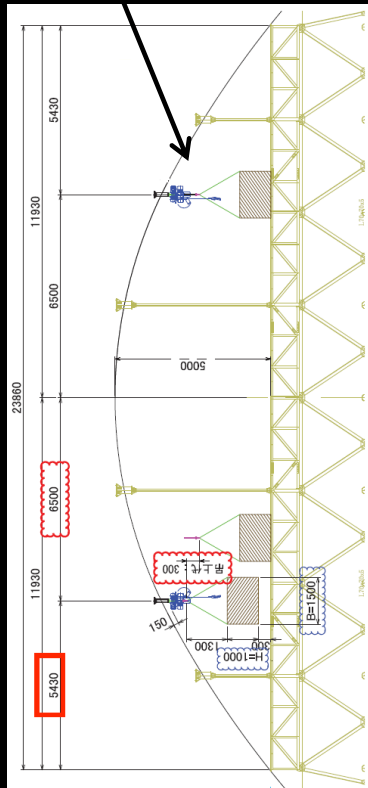
- Hyper-Kamiokande layout constraints
- Existing deployment systems
- System requirements
  - Geometric Coverage
  - Positional Accuracy
  - Interchangeability of sources
  - Robustness and automation
  - Geometric, weight and cost constraints
- Source positioning system

# HK Design Review

Crane: only  
6.6m off-center  
5.4m+9m more

Rod max. length:  
Only about 5 m  
Above the deck

“Deuterium-Tritium  
neutron Generator”  
Expensive (one ?)



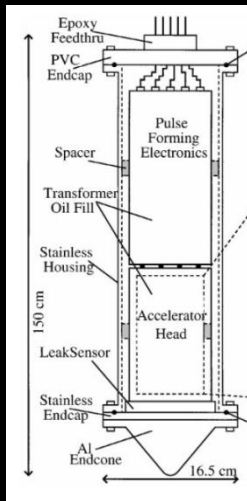
Multiple ports  
Significantly away  
From each other

Maximum weight  
100 kg/m<sup>2</sup> and  
1000 kg/m<sup>2</sup>

# Calibration Sources

- DTnG:

- Absolute gain calibr.



Thermo Scientific:

- A-211 no longer available
    - Possibly we can use the following:
      - MP-320 or
      - API-120

- Optical Sources:

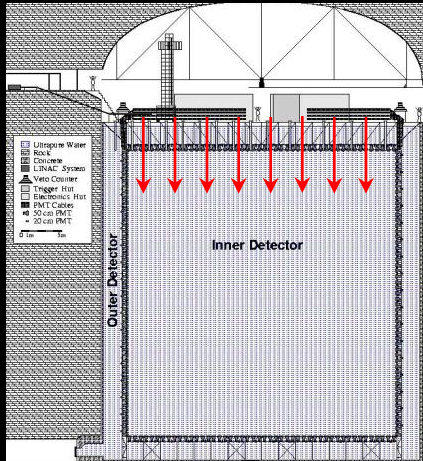
- Diffuser Ball
    - relative gain calibration
    - charge linearity calibration
    - timing calibration
  - Scintillation Ball
    - HV determination
    - CCD positioning LED

- SK Nickel source

- No plans for LINAC

# Current Deployment Systems

Super-K

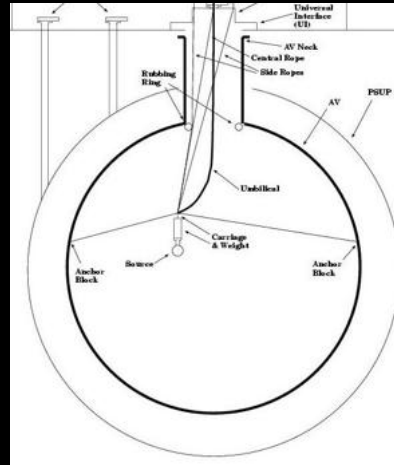


Cylindrical and Symmetric

1D calibration  
System (manual)

Volume Calibrated:  
 $\sim 50\text{k m}^3$

SNO

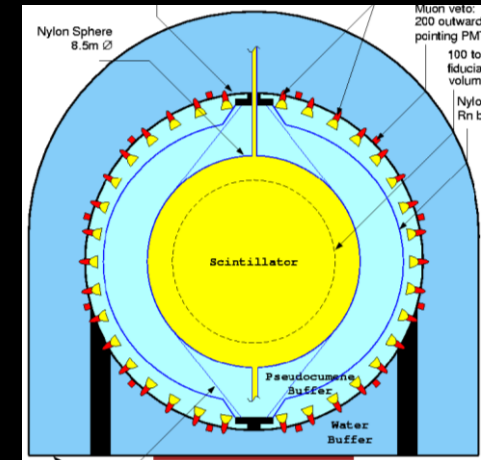


Spherically Symmetric

2D calibration  
System (manual)

Volume Calibrated:  
 $\sim 1\text{k m}^3$

Borexino



Spherically Symmetric

3D calibration  
System (manual)

Volume Calibrated:  
 $\sim 0.3\text{k m}^3$

# Towards HK

Super-Kamiokande



- Geometric Coverage
- Positional Accuracy
- Interchangeability of sources
- Robustness and automation
- Geometric, weight and cost constraints

# Towards HK

SNO



- Geometric Coverage
- Positional Accuracy
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# Towards HK

Borexino



- Geometric Coverage
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# Towards HK

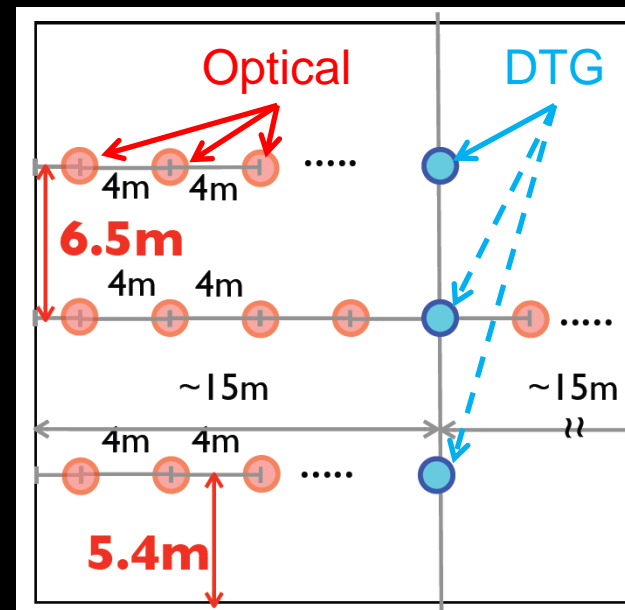
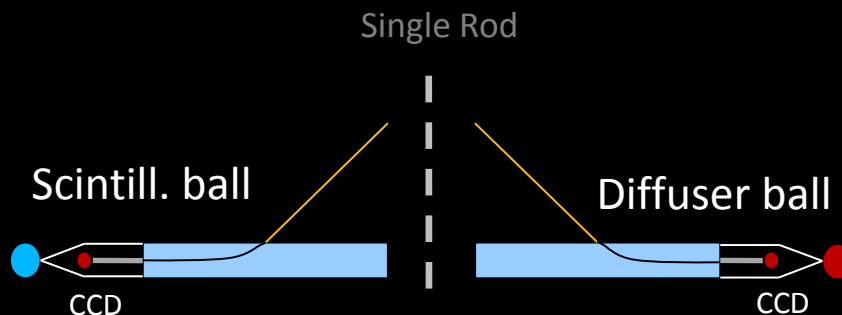
What do we need to achieve  
and  
HOW ?

- **Robustness and automation**
  - The system must be personnel-independent due to its size and geometry
  - Use of the CCDs will give real time position information
- **Interchangeability of sources**
  - Correlated with the above statement
- **Weight and cost constraints**
  - Top deck can handle only certain  $\text{kg/m}^2$

# Towards HK

An Idea

- Construct multiple light-weight systems with all the optical sources already mounted
- The heavier neutron source (DTnG) could be made portable on a crane (# of detectors and its dimensions)



# Towards HK

- The Daya-Bay automatic deployment system

Neutron source (Am-C)  
+ Gamma source (Co-60)

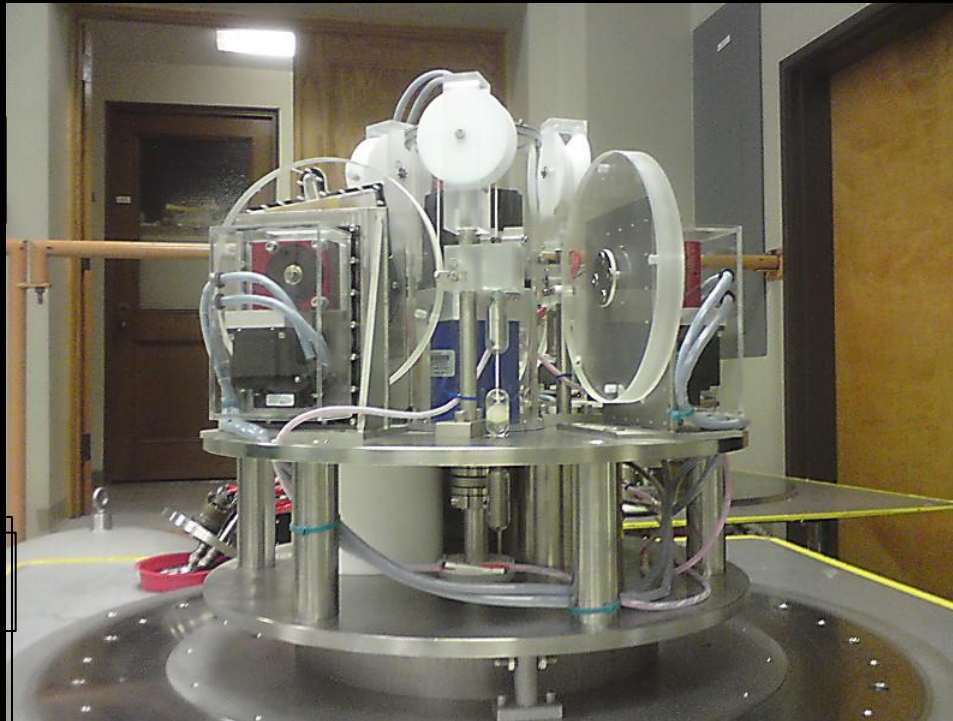
Limit switch:  
Limits the range of  
source motion

Gamma source (Ge-68)

Load cell: Monitors  
tension in the cable

Stepper motor with  
worm gear box

LED (~430 nm)  
with diffuser ball



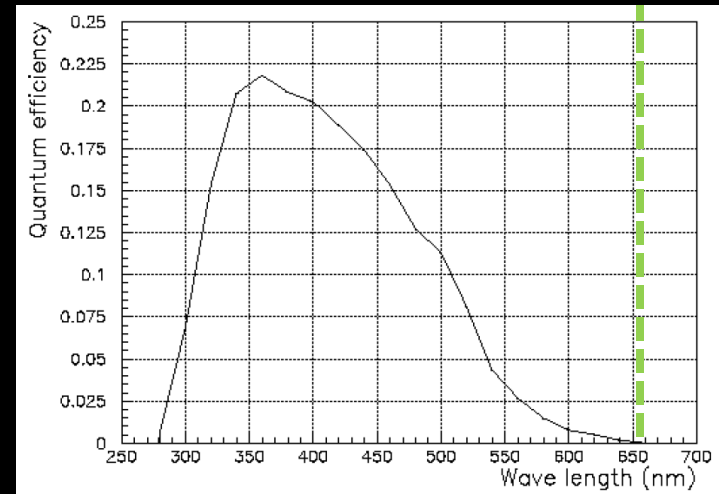
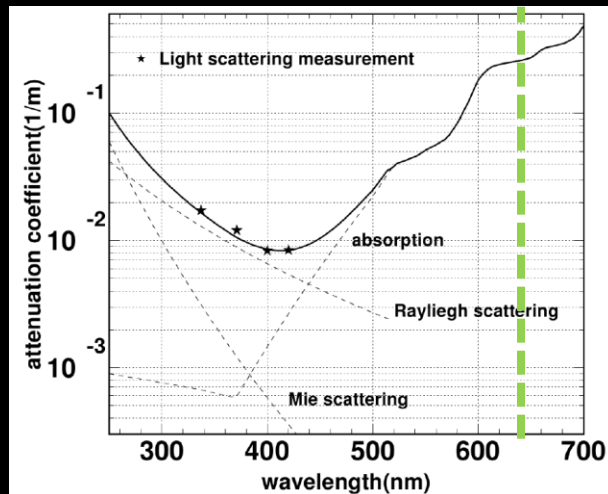
Camera with  
IR LEDs:  
mounted on  
the inside of  
the bell jar

Borated-Polyethylene  
neutron shield

Stainless gamma  
shield

# Source Positioning

- Adopted from Borexino, CCD cameras will be implemented, the remaining problem is the long distances in HK:  
up to **25 meters (curvature 9m + 5.4m)**  
This eliminates the possibility to go IR in H<sub>2</sub>O:



# Source Positioning

- Adopted from Borexino, CCD cameras will be implemented, the remaining problem is the long distances in HK:

up to **25 meters (curvature 9m + 5.4m)**

This eliminates the possibility to go IR in H<sub>2</sub>O:

660nm used in BX  
Should give enough  
Light for the CCD

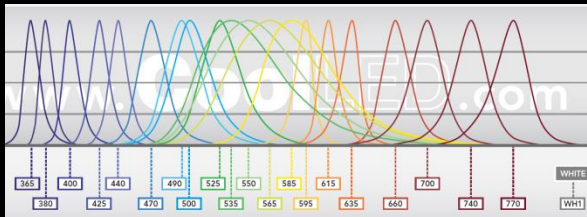
Anything > 700nm  
Would require  
High Watt LEDs

		Wv[nm]	CCD	PMT
			25m	25m
BX	{	600	15.619%	0.558%
		800	2.873%	0.001%
HK	{	600	0.472%	0.017%
		800	0%	0%

# Light Sources

- As for the source of light, we can choose between regular LEDs or an automatic leds driver (PicoQuant), both computer controlled:

## 1) LEDs:



- No fiber required
- Needs custom control
- Cost ~ mainly manpower

## 2) PicoQuant:



- Flexibility with WaveL
- Drives up to 8 heads
- Cost ~ \$35k

# Key Issues

- How to reach **14.4m** into the edge of the FV
  - Perhaps:  $-2\text{m}(\text{FV}) - 2\text{m}(\text{at } z=10\text{m}) = 14.4 - 4 = \text{10.4m}$
- What to do with the heavy-weight sources
  - Nickel: on an independent deployment system
  - DTnG: perhaps the SNO solution with CO<sub>2</sub> carrier  
([arXiv:nucl-ex/0109011](https://arxiv.org/abs/nucl-ex/0109011))
- How to achieve full automation
  - Either a deployment system with all the sources on, or
  - The Daya-Bay –like autonomous system.

# Summary

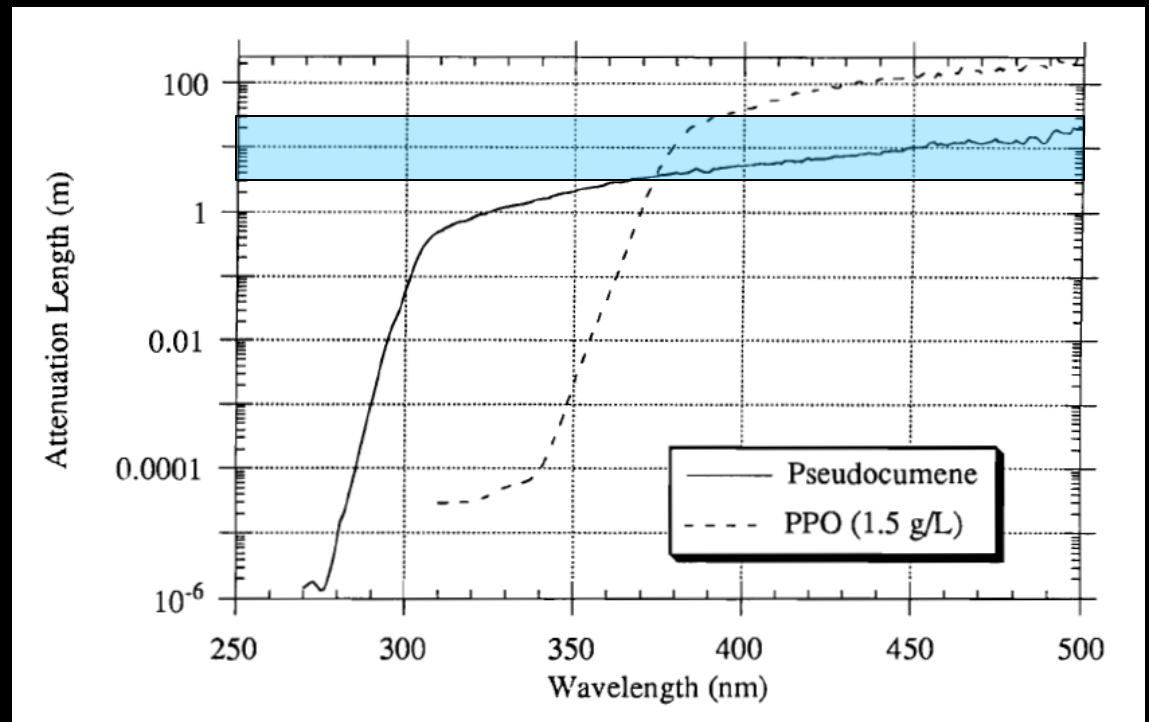
- Identified pros and cons of the existing calibration systems (SK, SNO, Bx, Daya-Bay)
- Identified minimal requirements for the HK calibration system
- Work in progress on a conceptual design
- Closely collaborate with the physics WG:
  - determine new requirements for HK
  - adapt conceptual design to that



# Backup

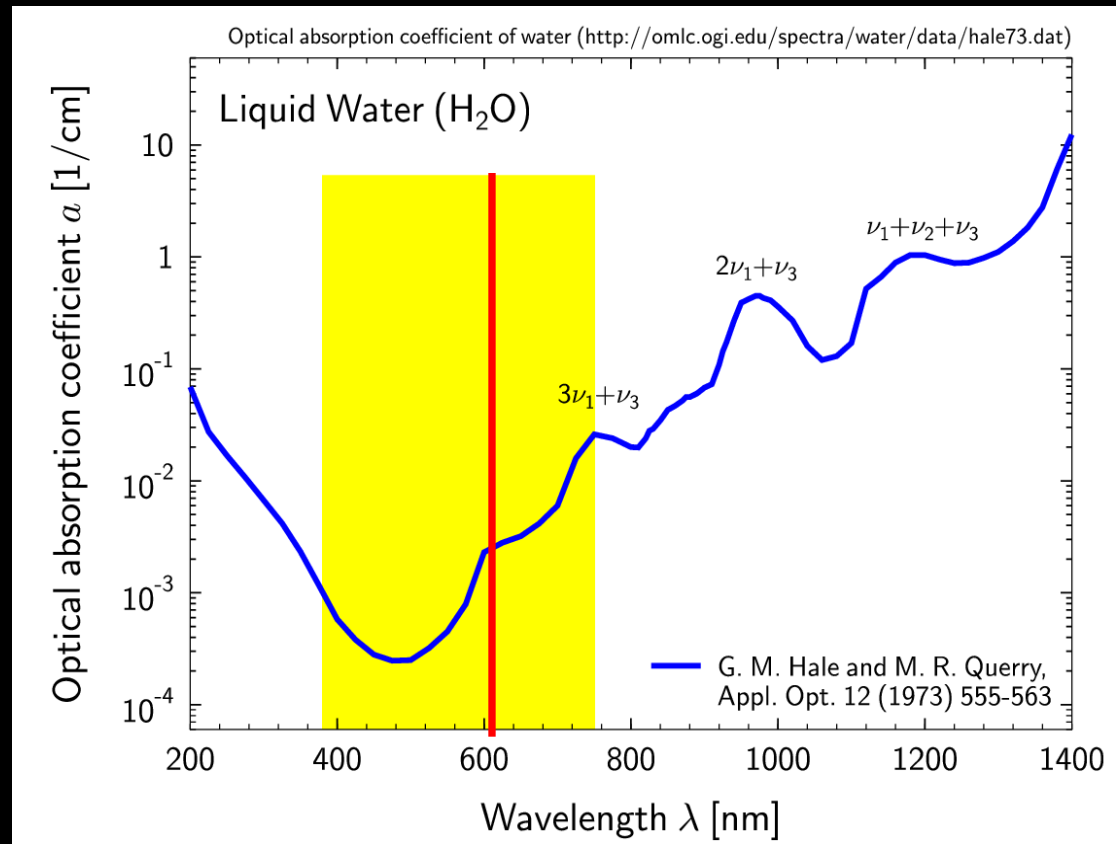
# Borexino CCD

- Laser wavelength: 635nm (visible red)
- Intensity: 500mW (about  $1.6 \times 10^{18}$  photons/sec)
- Pulse: 150ms
- 30% of light visible at distances of  $\sim 10$ m
- No need to turn PMTs OFF



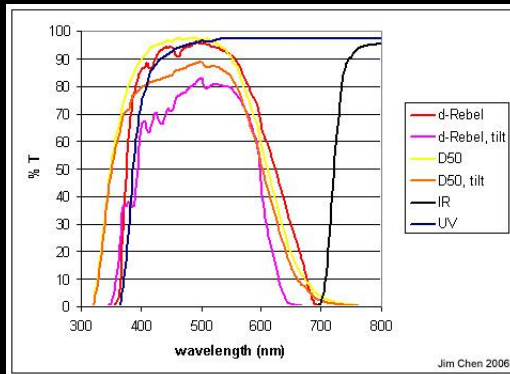
# Hyper-K Cameras

- Absorption coefficient increases rapidly with wv. in water
  - At 500nm  
 $\sim 3 \times 10^{-4}$  [1/cm]
  - At 600nm  
 $\sim 2 \times 10^{-3}$  [1/cm]
  - At 700nm  
 $\sim 4 \times 10^{-3}$  [1/cm]
  - At 800nm  
 $\sim 2 \times 10^{-2}$  [1/cm]

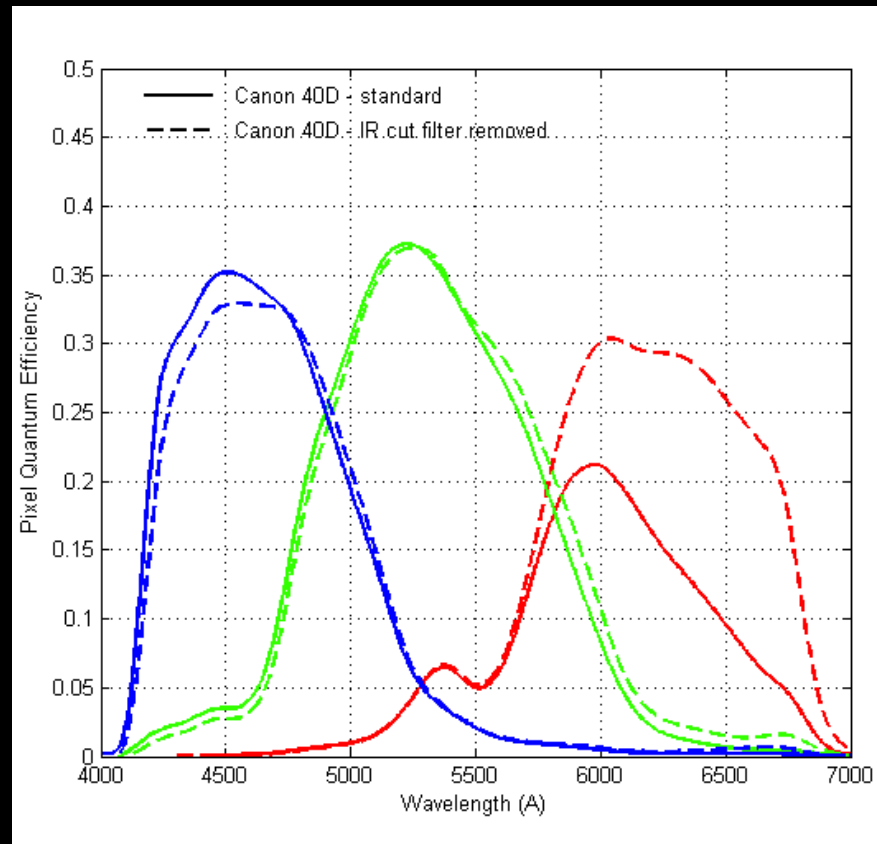


# Hyper-K Cameras

- CCD Quantum Efficiency (commercial CCD)
- Non-modified Trans.

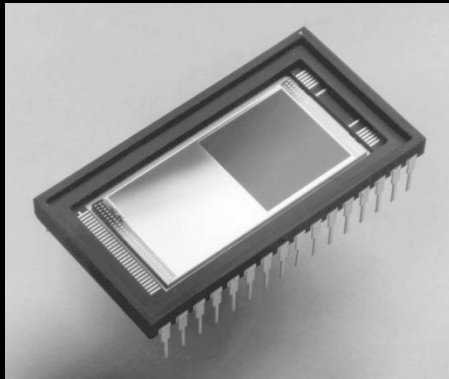


- Modified Filter:  
QE on the order of  
20-30%

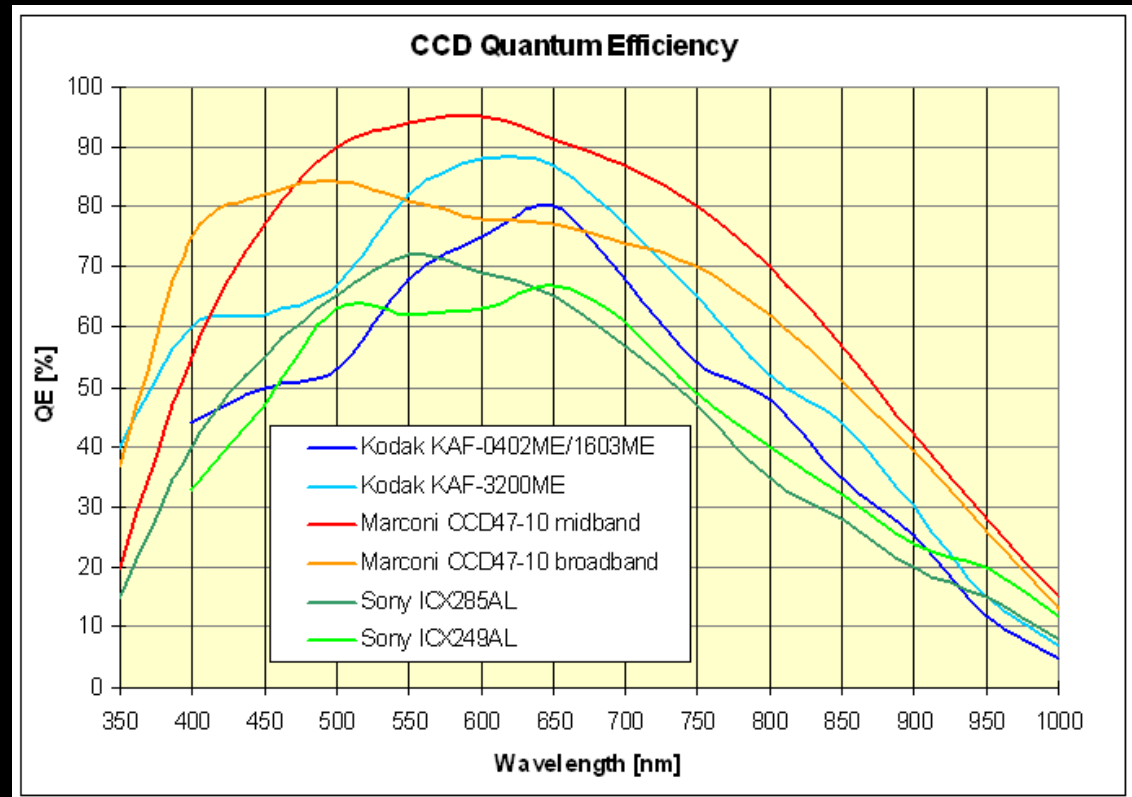


# Hyper-K Cameras

- CCD Quantum Efficiency (professional CCD)



- QE even at 60-90%



# Hyper-K Cameras

- Light intensity loss assuming certain intensity of the laser
  - Comparison for PC and Water at distance 0 and 25m

		Wv[nm]	CCD	PMT	CCD	PMT
			0m	0m	25m	25m
BX	{	600	70%	2.5%	15.619%	0.558%
		800	35%	0.01%	2.873%	0.001%
HK	{	600	70%	2.5%	0.472%	0.017%
		800	35%	0.01%	0%	0%

- At 600nm the remaining amount of light should be still sufficient for the CCD Camera

# Laser Diode

Light source

- PicoQuant *ns* or *ps* diode laser drivers

Modular system, drives up to 6 laser heads

Various operation modes: Synchronous, delayed, sequential

Repetition rate from single shot to 40 MHz (optional 64 or 80 MHz)

Laser power adjustable via individual driver units

Laser heads for wavelengths between 375 nm and 1990 nm

\$18k head drive and basic rack

+

x \$3k  
each drive

+

x \$5k  
each head



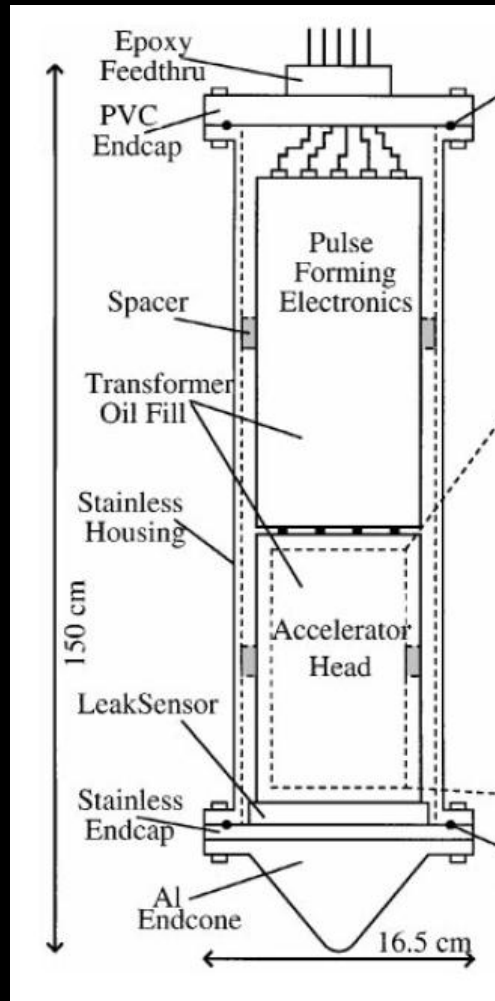
# Calibration Sources

## Requirements

- Gain calibration
  - HV determination (scintillation ball)
  - Absolute gain calibration (20 - 150cm neutron source)
  - Relative gain calibration (diffuser ball- N<sub>2</sub> laser)
- Charge linearity calibration (diffuser ball -off-center)
- Timing calibration (diffuser ball)
- OD calibration
- Water transparency measurement
  - Light scattering using a laser (light injection from the top)
  - Using cosmic ray muons (no hardware needed)
- Energy scale (LINAC or DT for ~10MeV range)



# DTG neutron Generator



Currently used in SK

Thermo Scientific

Custom MF Physics M A-211

Original Cost: ~ \$80k (From B. Svoboda: "Part of the cost was to repackage the electronics to be operated remotely (the pulser had to be located at the source rather than with the control panel)")

**A-211 no longer available from Thermo-Sc**

14MeV neutrons

An ultrasonic water sensor prevents operation of the generator when not in detector.

# DTG- MP 320



## Specifications

Yield	1.0E+08n/s (Neutron)
Neutron Energy	14MeV
Duty Factor	5% to 100%
Voltage	90kV (Maximum Accelerator)
Current	60μamps (Beam)
Power Supply	Integral
Neutron Module	4.75 x 22.5 in. ( 12.07 x 57.15cm)
Module	Integral, digital (Control)

## Safety Features

Keylock: on/off

Emergency: on/off

Normal-open and normal-closed interlocks

Pressure switch

Remote Control	RS-232/RS-485
Weight [ENGLISH]	12kg
Weight [METRIC]	26.46 lb.

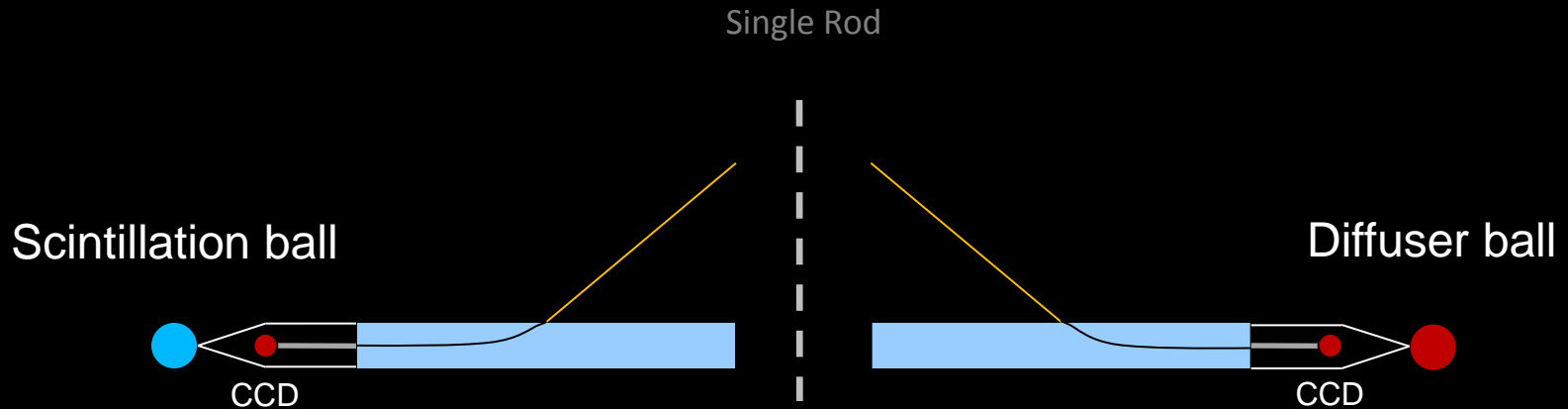
# DTG- API 120



## Specifications

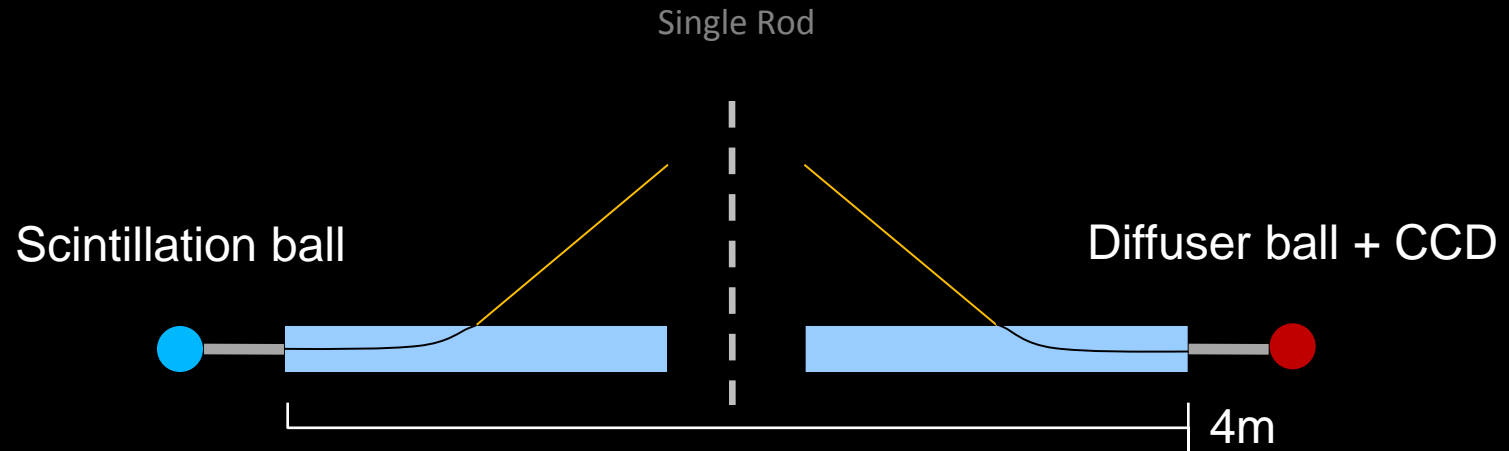
Neutron Yield	2.0E+07n/s
Neutron Energy	14MeV
Subtended Neutron Angle	~60 degrees, others available
Typical Lifetime	1200 hours @ 1 x 10cn/s
Operating Mode	Continuous only
Maximum Accelerator Voltage	90kV
Maximum Beam Current	50μA
Power Supply	Integral
Neutron Module Size	3 in. (7.62cm) diameter
Control Module	Integral, digital Keylock: on/off  Emergency: on/off
Safety Features	Normal-open and normal-closed contacts  Pressure switch
Remote Control	RS-232/RS-422 (optional)
Total Weight	33 lb. (15kg)
Software	Open source text or GUI
Electronics	Radiation tested to 80,000+ hours
Configuration	OEM-type available

# Calibration Design I



- DB + CCD-LED and SB + CCD-LED
  - Individual fibers for the Scintillation and Diffuser balls
  - Separate Diffusers for two CCD positioning sources
- Advantage
  - Precise 3D position determination

# Calibration Design II



- DB/SB + CCD-LED
  - Scintillation ball for the Xe lamp only
  - Diffuser ball shares the fiber for CCD and calibration lasers
- Advantage
  - Simplified hardware