

PRACTICAL STATISTICS #5

Hunter + Dog paradox

Bayes + Frequentism, contd
2 more Bayes examples
Frequentist approach

See
#4

Feldman - Cousins

Ordering rule

Flip - flop

Gaussian + Poisson examples

✓ oscillations

Systematics

Shift method

Profile χ^2

Bayes

Frequentist

Mixed: Cousins + Highland

Multivariate analysis

Neural networks

BLUE combination technique

LOUIS LYONS
CDF

FELDMAN - COUSINS

WANT TO AVOID EMPTY CLASSICAL INTERVALS $\Rightarrow$

USE " $\mathcal{L}$ RATIO ORDERING PRINCIPLE"

TO RESOLVE AMBIGUITY ABOUT "WHICH 90%
REGION?" $\Rightarrow$

[NEYMAN-PEARSON SAY $\mathcal{L}$ RATIO IS BEST
FOR HYPOTHESIS TESTING]

NO FLIP-FLOP PROBLEM $\Rightarrow$

90% classical interval for Gaussian

$$\sigma = 1$$

$$\mu \geq 0$$

e.g. $m^2(\nu_e)$

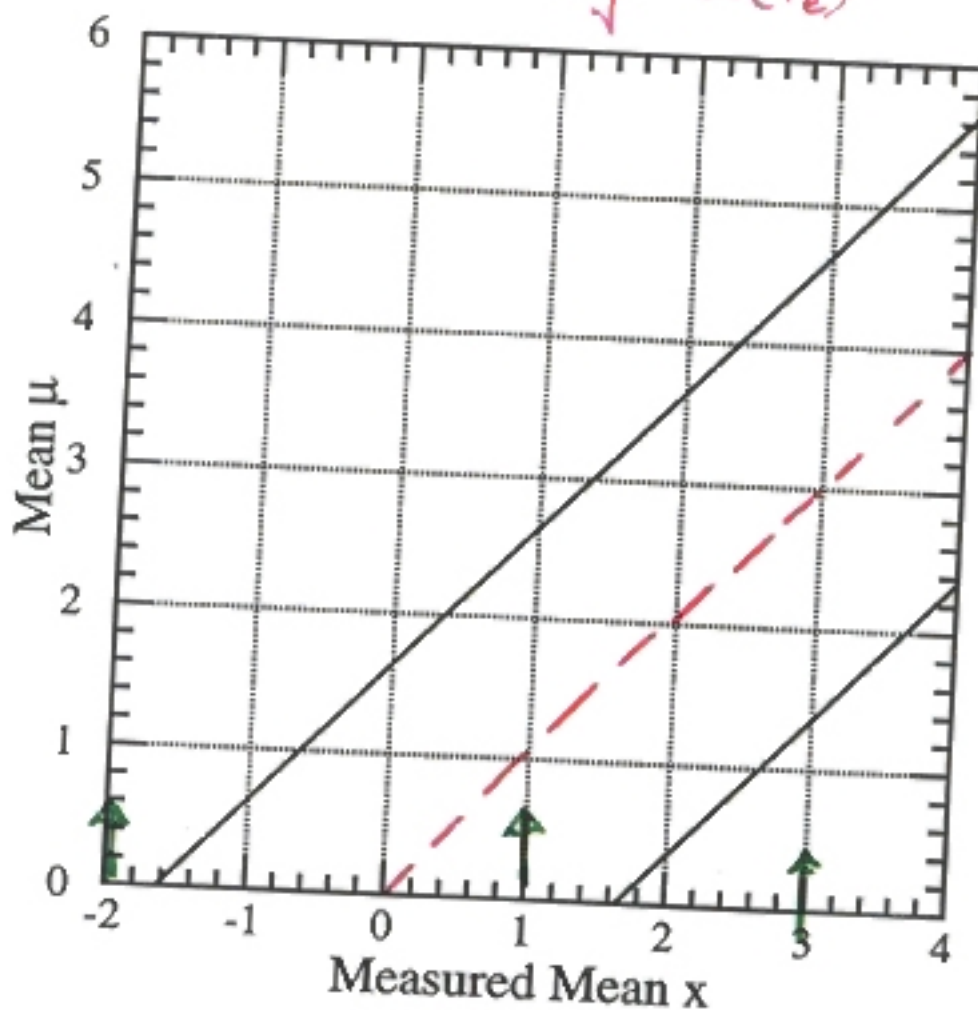


FIG. 3. Standard confidence belt for 90% C.L. central confidence intervals for the mean of a Gaussian, in units of the rms deviation.

$$x_{obs} = 3$$

Two sided limit

$$x_{obs} = 1$$

Upper limit

$$x_{obs} = -2$$

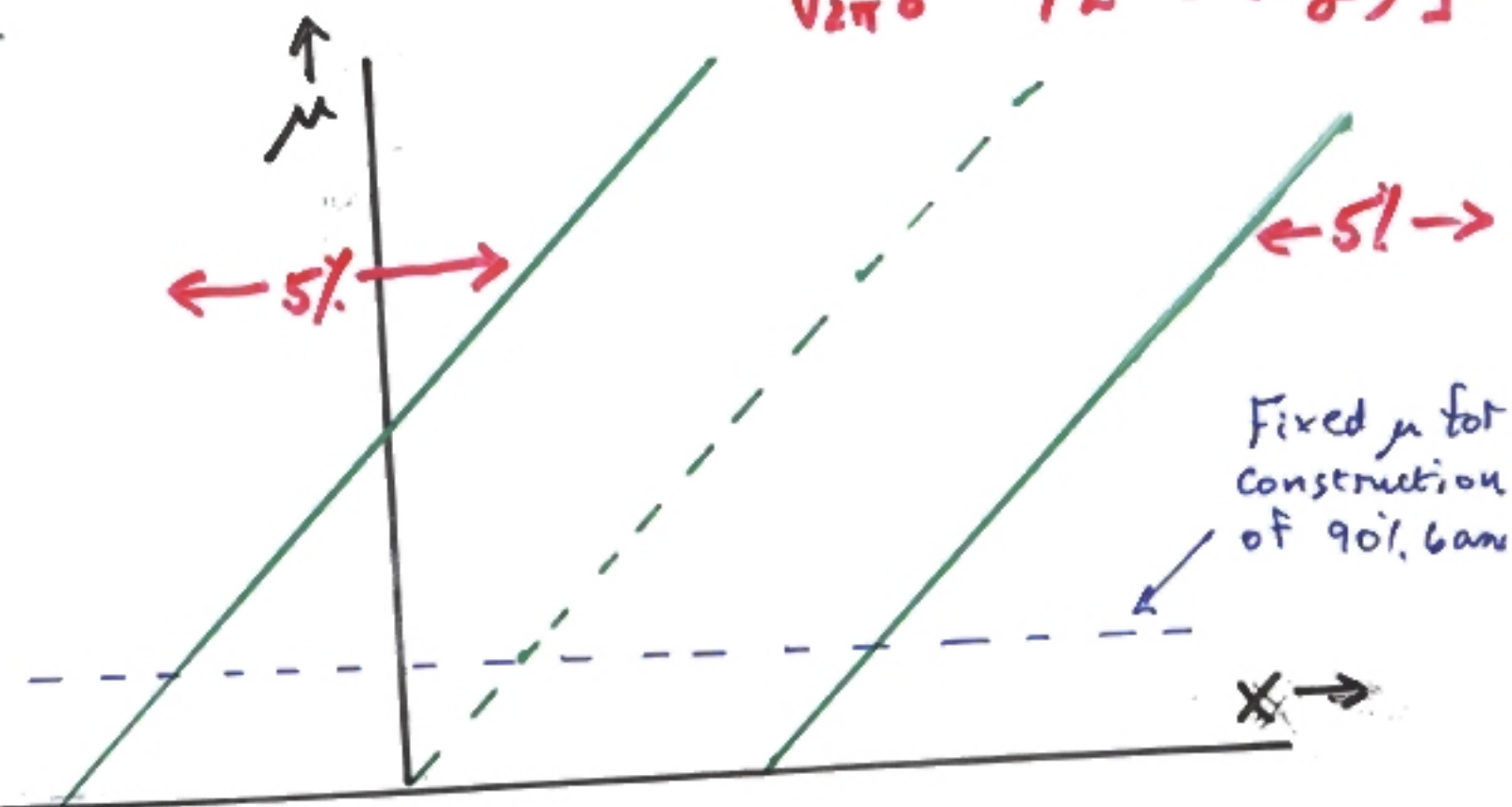
No region for μ

FELDMAN - COUSINS ORDERING RULE

$$R = p(x, \mu) / p(x, \mu_{\text{best}}) \quad [\text{Likelihood ratio ordering}]$$

Gaussian example $p(x, \mu) = G(x, \mu, \sigma)$

$$= \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right]$$

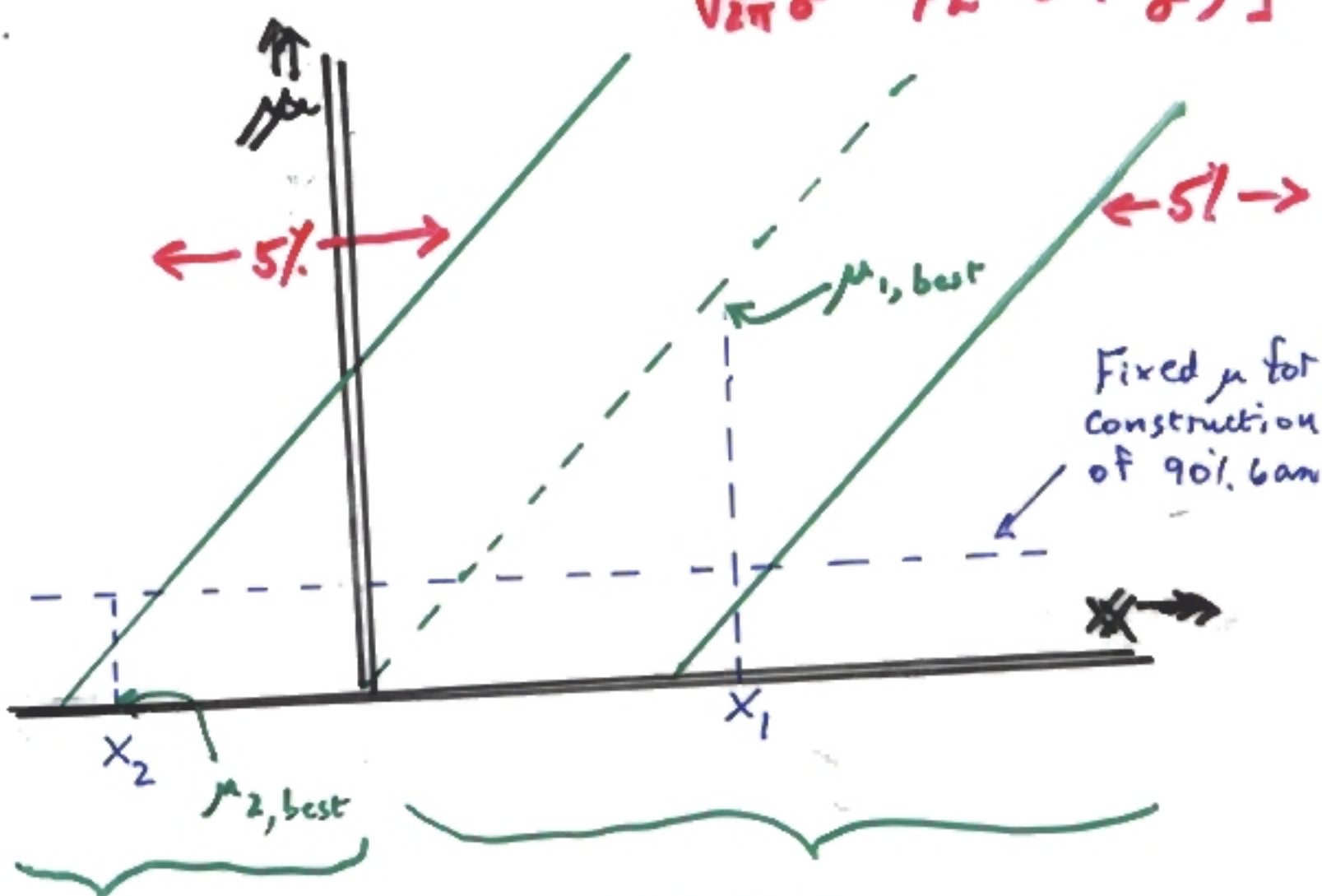


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$$\mu_{\text{best}} = 0$$

$$p(x, \mu_b) = \frac{1}{\sqrt{2\pi}\sigma} e^{-x^2}$$

$$p(x_1, \mu) > p(x_2, \mu)$$

BUT $R(x_2, \mu) > R(x_1, \mu)$

$$\mu_{\text{best}} = x$$

$$p(x, \mu_b) = \frac{1}{\sqrt{2\pi}\sigma} = \text{const}$$

Standard: Select x_1 before x_2

F.C: Select x_2 before x_1

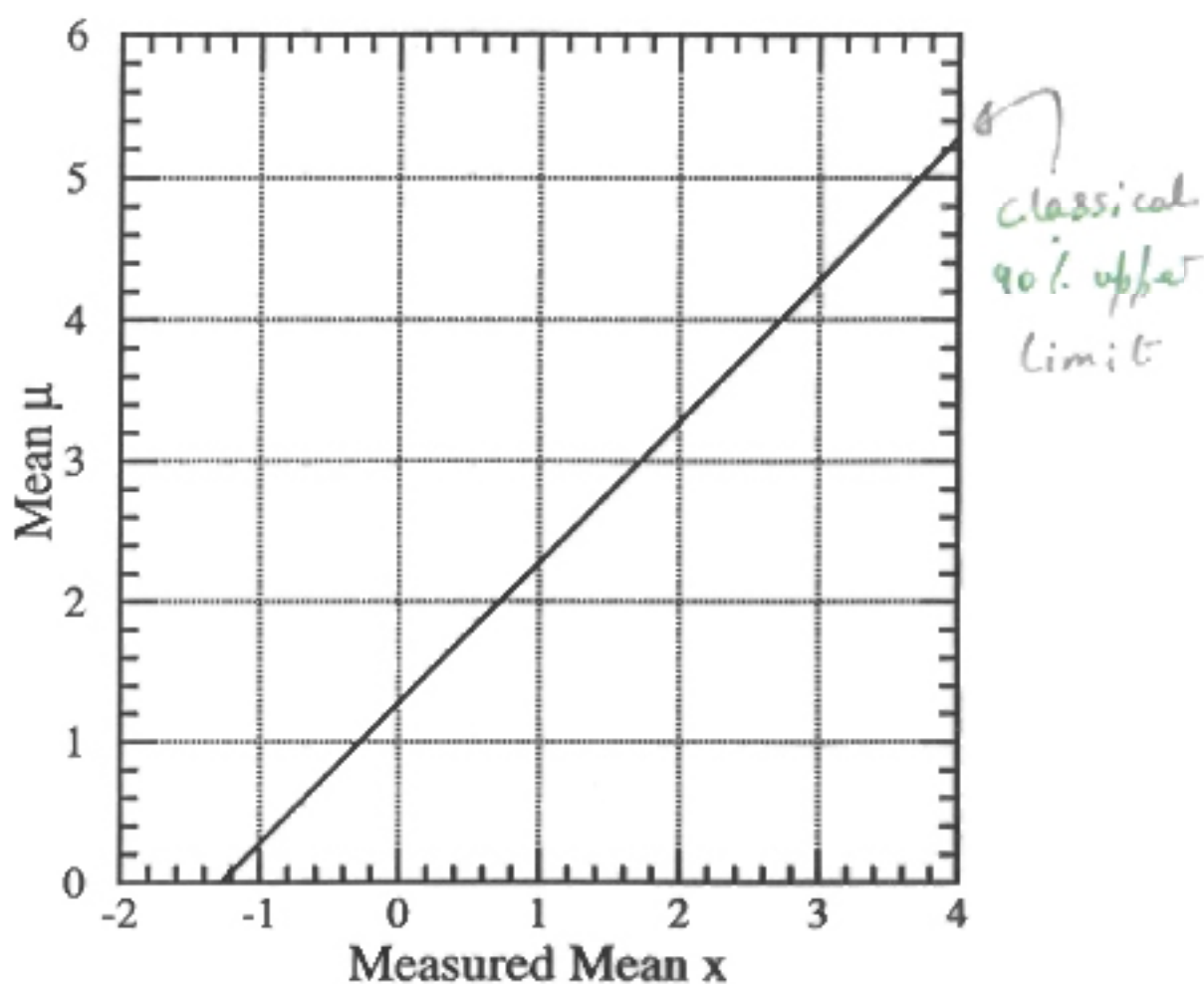


FIG. 2. Standard confidence belt for 90% C.L. upper limits for the mean of a Gaussian, in units of the rms deviation. The second line in the belt is at $x = +\infty$.

Feldman-
Gousins
90% Conf
interval

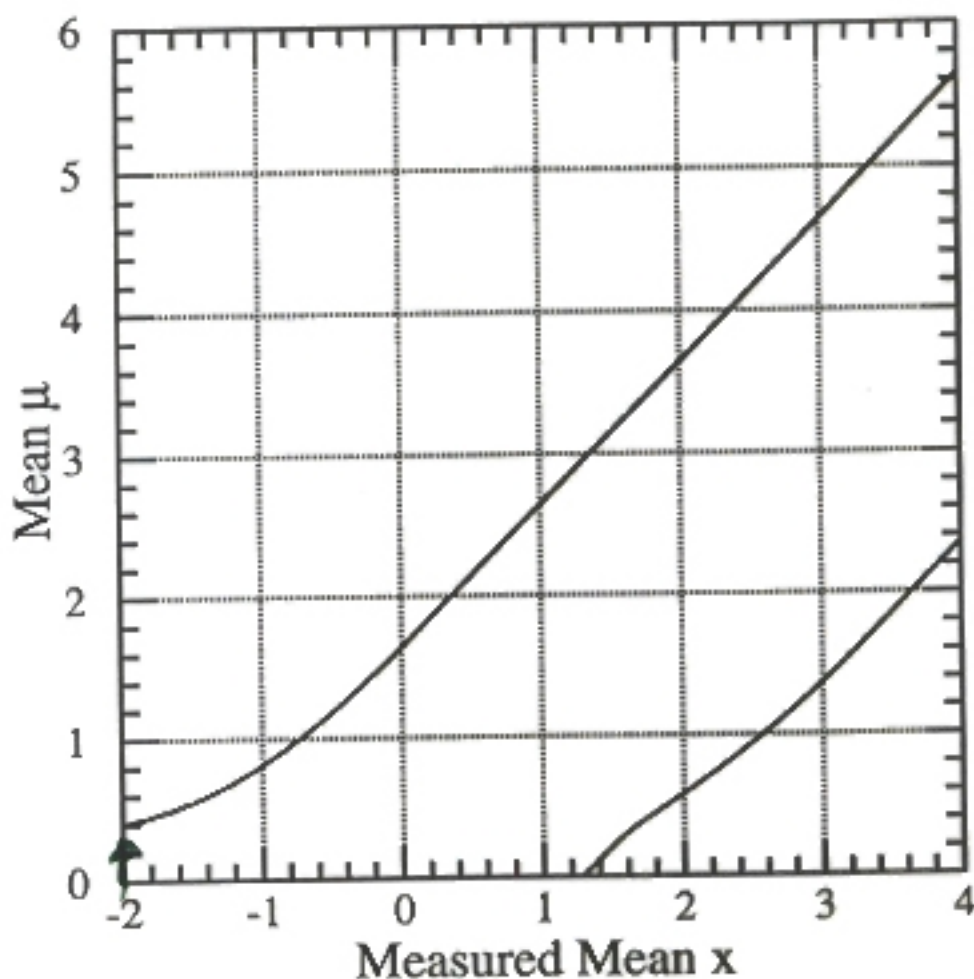


FIG. 10. Plot of our 90% confidence intervals for mean of a Gaussian, constrained to be non-negative, described in the text.

$$x_{\text{obs}} = -2$$

Now gives upper limit

FLIP - FLOP

90% upper limit for $x_{obs} \leq 3$

90% 2-sided interval for $x_{obs} > 3$

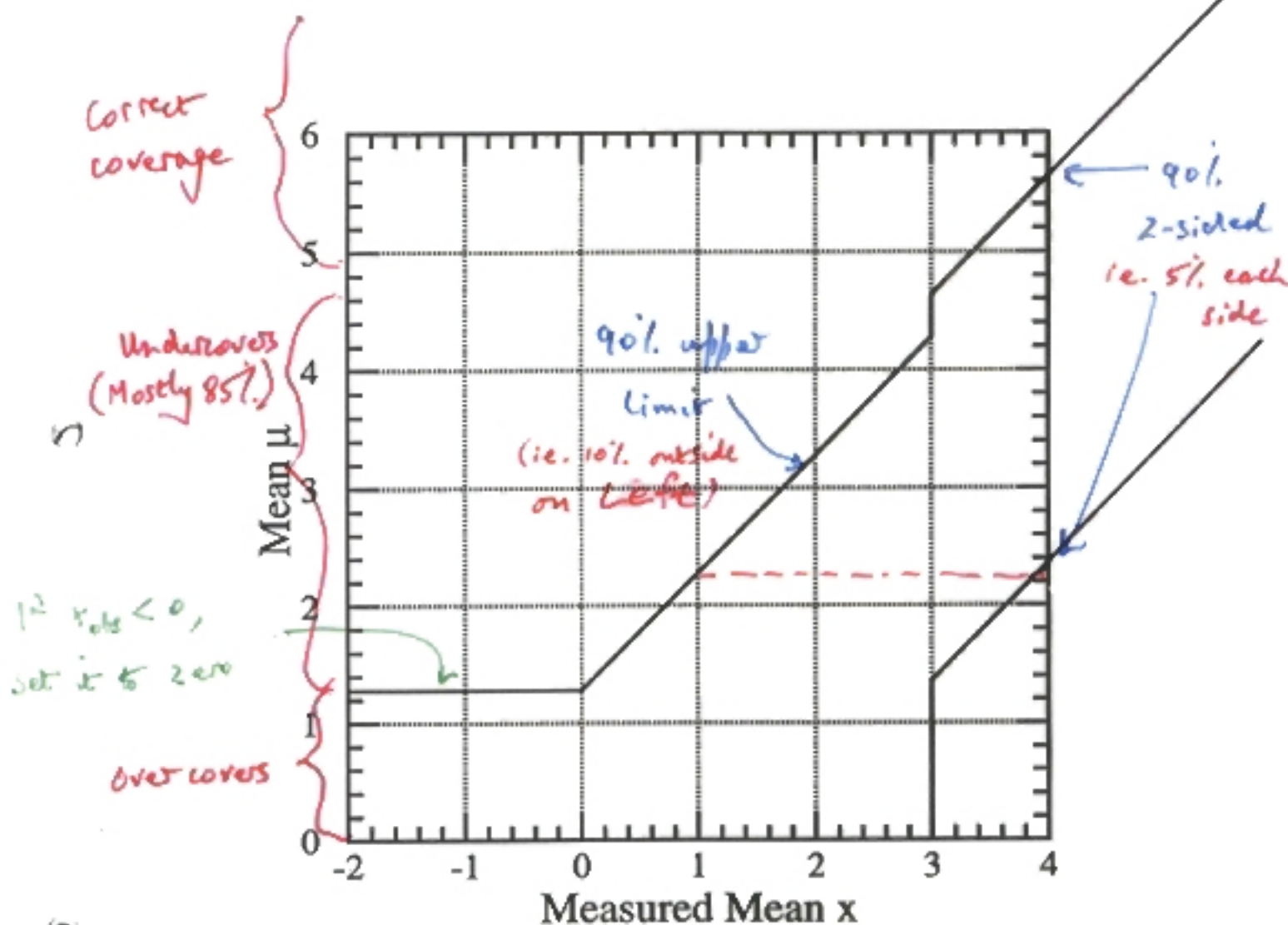


FIG. 4. Plot of confidence belts implicitly used for 90% C.L. confidence intervals (vertical intervals between the belts) quoted by flip-flopping Physicist X, described in the text. They are not valid confidence belts, since they can cover the true value at a frequency less than the stated confidence level. For $1.36 < \mu < 4.28$, the coverage (probability contained in the horizontal acceptance interval) is 85%.

Not good to let x_{obs} determine how result will be presented

F-C goes smoothly from 1-sided $\rightarrow$ 2-sided

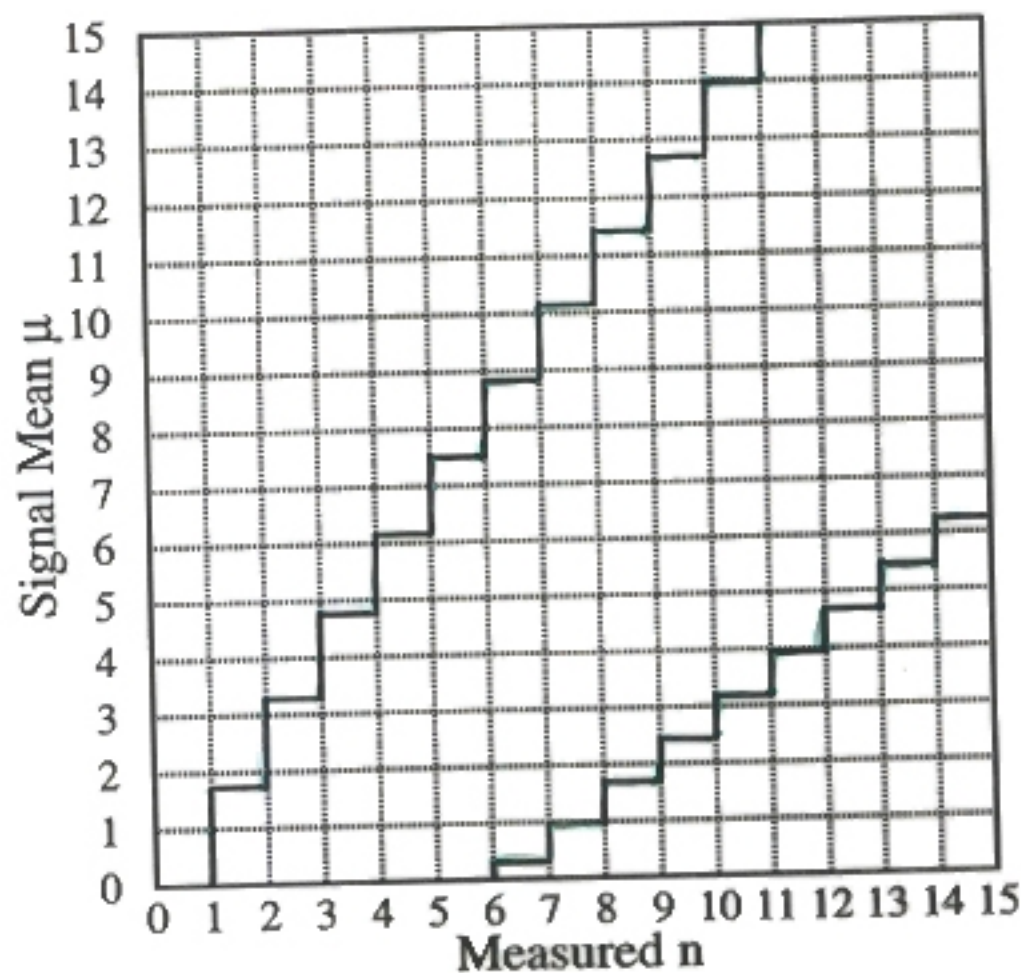


FIG. 6. Standard confidence belt for 90% C.L. central confidence intervals, for unknown Poisson signal mean μ in the presence of Poisson background with known mean $b = 3.0$.

Standard Frequentist
for Poisson mean μ

FELDMAN & COUSINS FOR

POISSON MEAN μ

90% Conf

$b = 3.0$

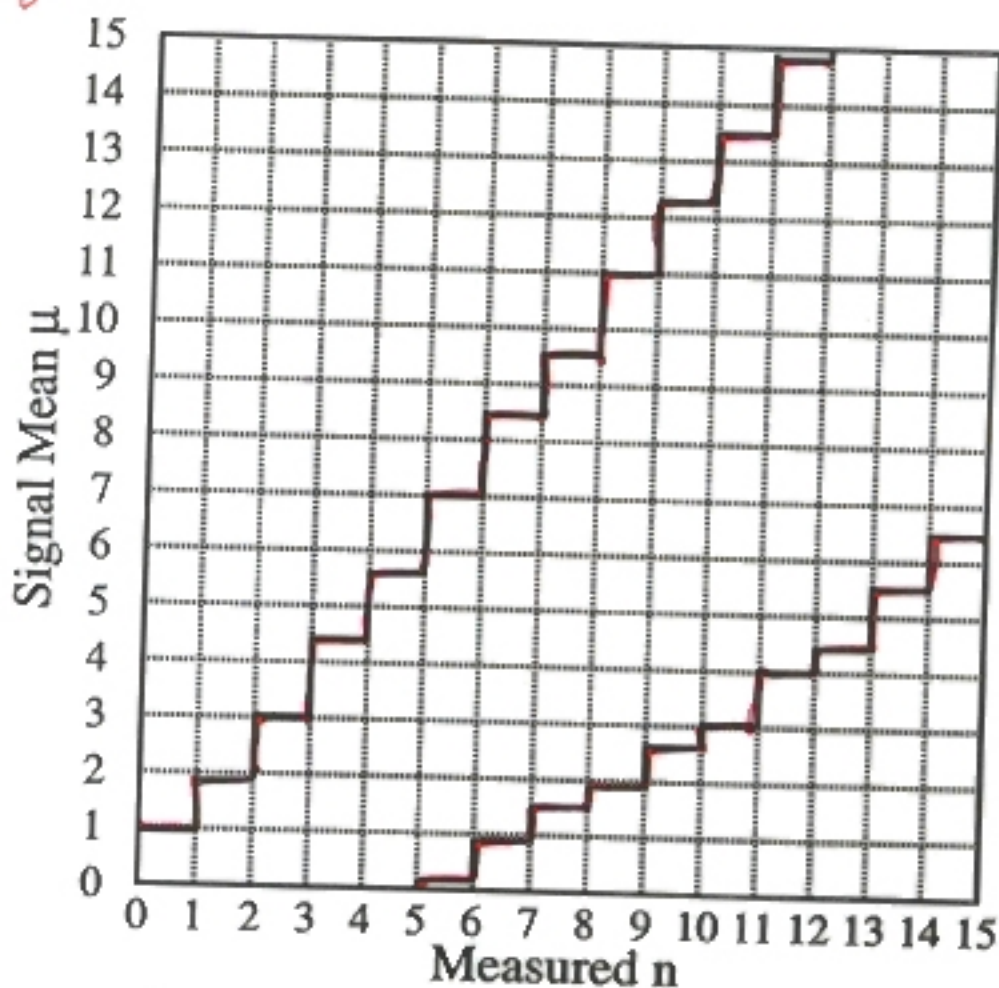


FIG. 7. Confidence belt based on our ordering principle, for 90% C.L. confidence intervals for unknown Poisson signal mean μ in the presence of Poisson background with known mean $b = 3.0$.

FREQVENTIST

POISSON

C.B. CONSTAN.

TABLES

TABLE I. Illustrative calculations in the confidence belt construction for signal mean μ in the presence of known mean background $b = 3.0$. Here we find the acceptance interval for $\mu = 0.5$.

n	$P(n \mu)$	μ_{best}	$P(n \mu_{\text{best}})$	R	rank	U.L.	central
0	0.030	0.	0.050	0.607	6		
1	0.106	0.	0.149	0.708	5		
2	0.185	0.	0.224	0.826	3		
3	0.216	0.	0.224	0.963	2		
4	0.189	1.	0.195	0.966	1		
5	0.132	2.	0.175	0.753	4		
6	0.077	3.	0.161	0.480	7		
7	0.039	4.	0.149	0.259			
8	0.017	5.	0.140	0.121			
9	0.007	6.	0.132	0.050			
10	0.002	7.	0.125	0.018			
11	0.001	8.	0.119	0.006			

FERDMAN - COUSINS



<10%

<5%

Prob
ordering5
3
1
2
4
6
7

<5%

FEATURES OF F+C

REDUCES EMPTY INTERVALS
 { UNIFIED 1-SIDED & 2-SIDED INTERVALS
 ELIMINATES FLIP-FLOP
 NO ARBITRARINESS OF INTERVAL
 'READILY' EXTENDS TO SEVERAL
 DIMENSIONS



LESS OVERCOVERAGE THAN
 "5% AT ENDS"

MAY PROB DENSITY?
 5% AT ENDS?

NEYMAN CONSTRUCTION $\Rightarrow$ CPU-INTENSIVE
 (ESP IN SEVERAL DIMENSIONS)

MINOR PATHOLOGIES: DISTANT INTERVALS

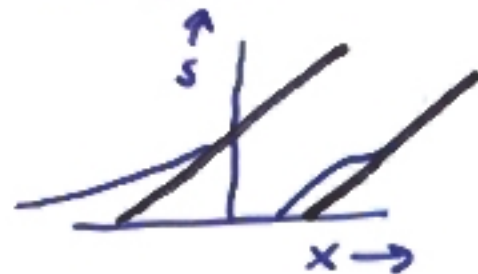
WROTE BEHAVIOUR WRT BGD

TIGHT LIMITS FOR
 $b > n_{obs}$

e.g. {

n_{obs}	$b_{90\%}$	90% Limit
0	3.0	1.08
0	0	2.44

UNIFIED $\Rightarrow$ QUICKER EXCLUSION OF $S=0$

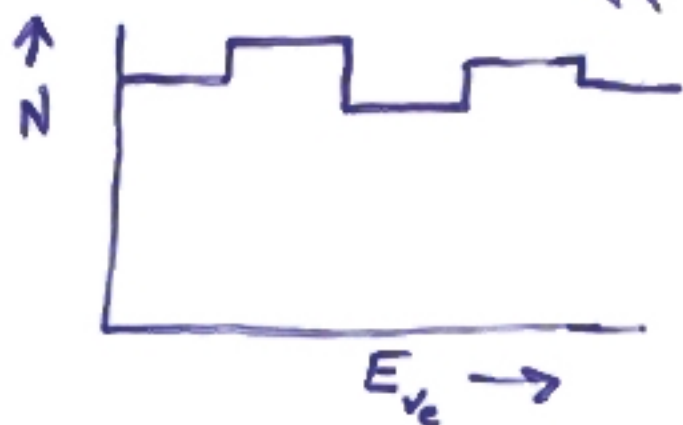


NEUTRINO OSCILLATIONS

$$P(\nu_\mu \rightarrow \nu_e) = \sin^2 2\theta \sin^2 \left[\frac{1.27 \Delta m^2 L}{E} \right]$$

$\nwarrow$ eV $\uparrow$ 6 eV $\uparrow$ km

Data = " ν_e " energy spectrum



$B_{\text{gd}} = 100 \text{ ev/bin}$
 $\text{Signal} = 10,000 \text{ ev/bin}$
 if $P = 1$

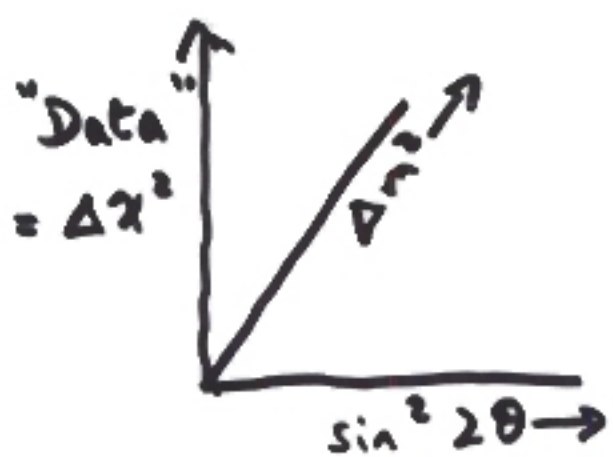
Compare data & prediction via

$$\Delta\chi^2 = \sum \left(\frac{n_i - b_i - \mu_i}{\sigma_i} \right)^2 - \left(\frac{n_i - b_i - (\mu_{\text{best}})_i}{\sigma_i} \right)^2$$

$$\text{OR } 2 \sum \left\{ \mu_i - (\mu_{\text{best}})_i + n_i \frac{\mu_{\text{best},i} + b_i}{\mu_i + b_i} \right\}$$

($\ln$ [Likelihood ratio])

N.B. $\Delta\chi^2$ is more than just one piece of data



FIND ACCEPTANCE
REGION FOR "DATA" BY M.C.
i.e. HOW BIG SHOULD $\Delta\chi^2_{\text{cut}}$
BE FOR 90% ACCEPTANCE?

[NOT STANDARD 4.61 for χ^2

BECAUSE a) EFFECT OF BOUNDARIES

b) WRONG OVERALL MINIMUM

c) POISSON $\neq$ GAUSSIAN

d) $\Delta\chi^2 \neq \chi^2$

e) '1-D' REGIONS AT LOW Δm^2
[$P \sim \sin^2 2\theta \cdot (\Delta m^2)^2$]

$$\Delta\chi^2_{\text{cut}} = 2.4 - 6.6$$

FINALLY, USE DATA $\Rightarrow \Delta\chi^2$ AT EACH

$(\sin^2 2\theta, \Delta m^2)$ + COMPARE WITH $\Delta\chi^2_{\text{cut}}(\sin^2 2\theta, \Delta m^2)$

TO FIND ACCEPTABLE REGION IN $(\sin^2 2\theta, \Delta m^2)$

VERY MUCH BETTER THAN "RASTER SCAN"

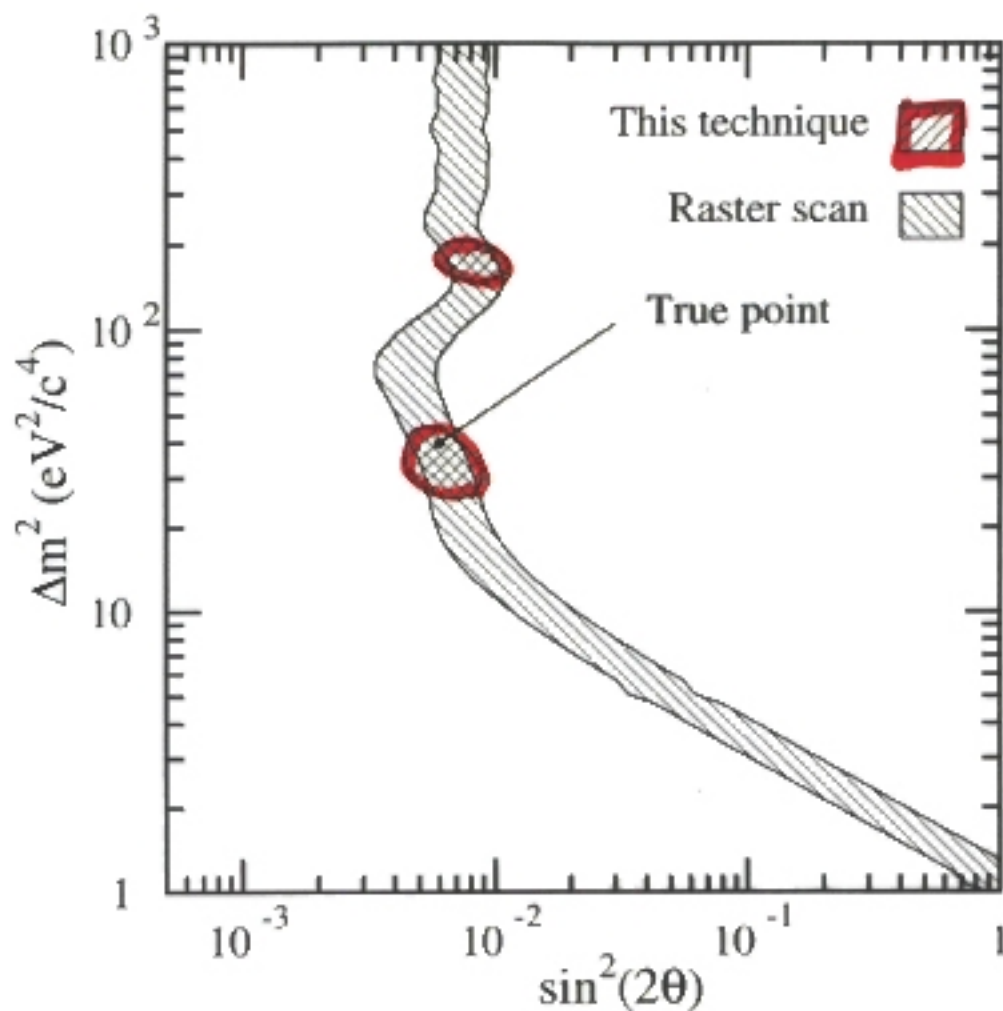


FIG. 12. Calculation of the confidence regions for an example of the toy model in which $\Delta m^2 = 40 \text{ (eV}^2/\text{c}^4)$ and $\sin^2(2\theta) = 0.006$, as evaluated by the proposed technique and the Raster Scan.

i.e. FELDMAN - COUSINS IS
MUCH BETTER THAN RASTER
SCAN
(cf $B - \bar{B}$ OSCILLATIONS)

SENSITIVITY

(indep of actual data)

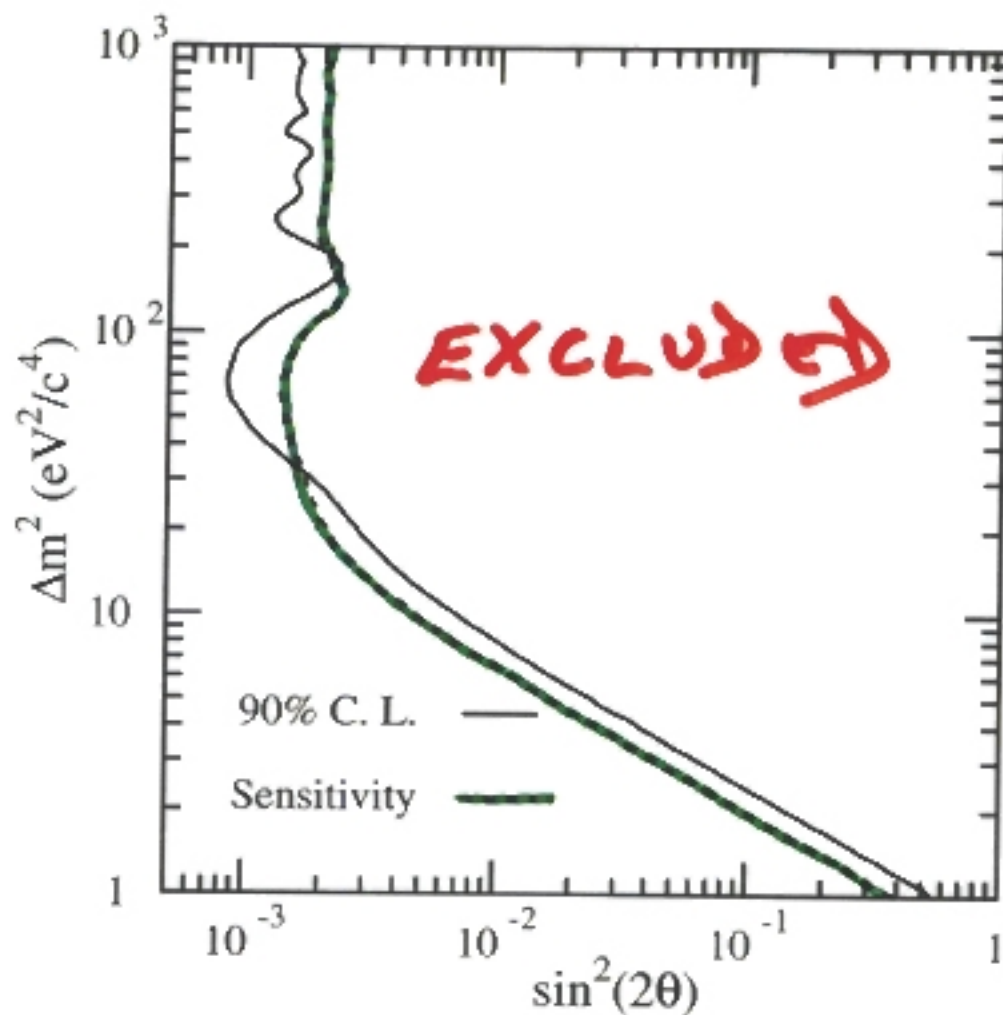


FIG. 15. Comparison of the confidence region for an example of the toy model in which $\sin^2(2\theta) = 0$ and the sensitivity of the experiment, as defined in the text.

1-D Poisson

PARAM

λ

DATA

n

ORDERING
RULE

$\ln [\mathcal{L}(\text{ratio})]$

HOW MANY?

At each λ ,
 $\sum P(n|\lambda) = 0.9$

ACCEPTANCE
REGION

USE OBSERVED n

$\Rightarrow \lambda \text{ RATIO}$

[REGION WHERE $\lambda \approx n$]



NU OSCILLATIONS

$\sin^2 2\theta, \Delta m^2$

$n_i (E_\nu)$

$\ln [\mathcal{L}(\text{ratio})] \sim \Delta\chi^2$

At each $(\sin^2 2\theta, \Delta m^2)$,
include first 90% of $\Delta\chi^2$

USE OBSERVED $n_i (E_\nu) \Rightarrow$

$\Delta\chi^2 (\sin^2 2\theta, \Delta m^2)$

$\Rightarrow (\sin^2 2\theta, \Delta m^2)$ REGION

[REGION WHERE

$n_i \approx \text{prediction for } (\sin^2 2\theta, \Delta m^2)$



SYSTEMATICS

For example

$$N_{\text{events}} = \sigma LA + b$$

↑

Observed

↑

$$N \pm \sqrt{N}$$

for statistical errors

Physics

parameter

↑

we need to know these,
probably from other
measurements (and/or theory)

Uncertainties → error in σ

Some are arguably statistical errors

$$LA = LA_0 \pm \sigma_{LA}$$

$$b = b_0 \pm \sigma_b$$

Shift Central Value

Bayesian

Frequentist

Mixed

Profile Likelihood

Bayesian

$$N_{\text{events}} = \sigma LA + b$$

↑
prior

Simplest Method

Evaluate σ_0 using LA_0 and b_0

Move nuisance parameters (one at a time) by their errors $\rightarrow \delta\sigma_L$ & $\delta\sigma_b$

If nuisance parameters are uncorrelated

Combine these contributions in quadrature

$\rightarrow$ total systematic

PROFILE $\mathcal{L}$

Rolke, Lopez, Conrad + James

"Limits & Confidence Intervals in the presence of Nuisance Parameters"

$$p\mathcal{L}(\mu | \text{data}) = \mathcal{L}(\mu, b_{\text{best}} | \text{data})$$

$$\Delta \ln p\mathcal{L} = 0.5$$

Coverage much smoother (as fn of μ)
than for standard Bayesian without
nuisance parameters

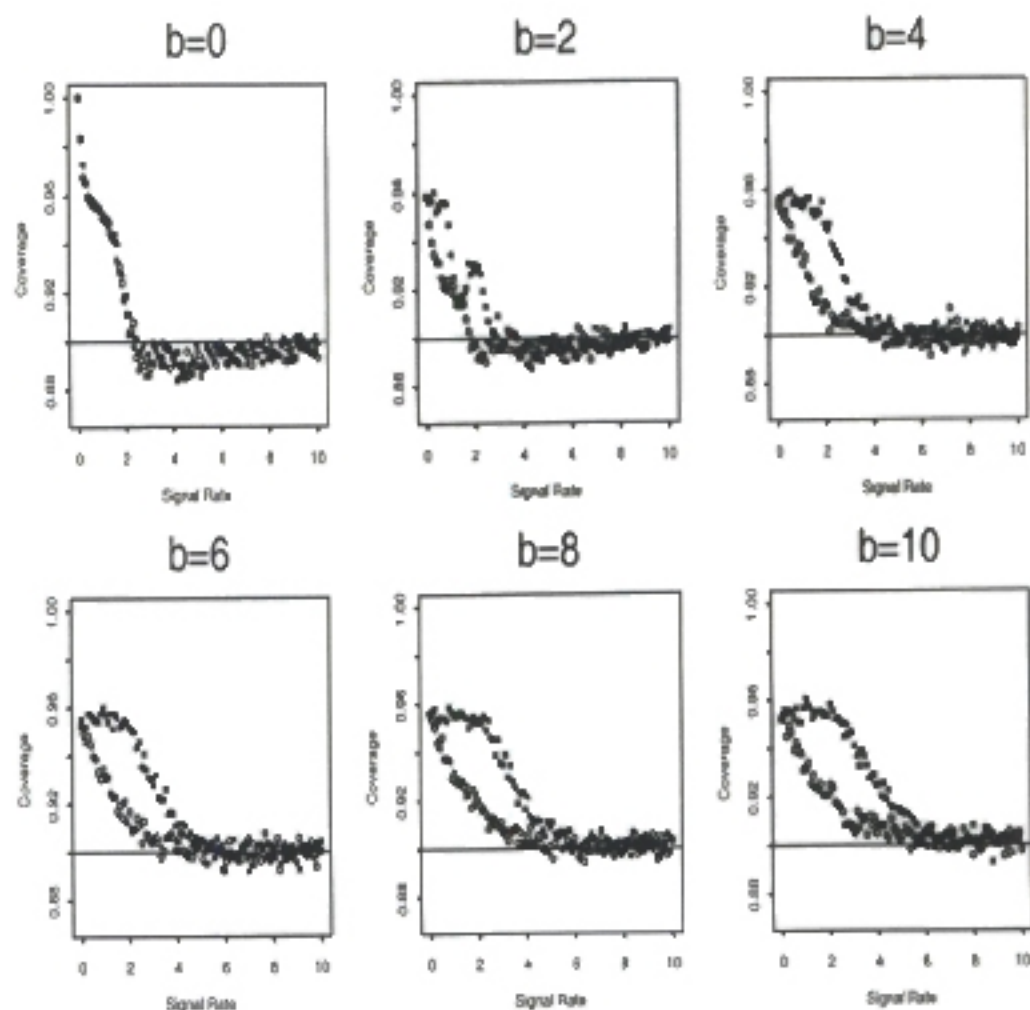


FIG. 3: 90% coverage graphs when the signal and the background are modeled as Poisson and the efficiency is modeled as a Binomial. We have $\tau = 3.5$, $\epsilon = 0.85$ and $m = 100$. The empty circles show the coverage using the unbounded likelihood method and the solid squares show the coverage using the bounded likelihood method.

Rolke et al

Profile χ^2

Bayesian

Without systematics

$$p(\sigma; N) \propto p(N; \sigma) \Pi(\sigma)$$



prior

With systematics

$$p(\sigma, LA, b; N) \propto p(N; \sigma, LA, b) \Pi(\sigma, LA, b)$$



$$\sim \Pi_1(\sigma) \Pi_2(LA) \Pi_3(b)$$

Then integrate over LA and b

$$p(\sigma; N) = \iint p(\sigma, LA, b; N) dLA db$$

$$p(\sigma; N) = \iint p(\sigma, LA, b; N) dLA db$$

If $\Pi_1(\sigma) = \text{constant}$ and $\Pi_2(LA) = \text{truncated Gaussian TROUBLE!}$

Upper limit on σ from $\int p(\sigma, N) d\sigma$

Significance from likelihood ratio for $\sigma=0$ and $\sigma_{\max}$

BAYES 90% UPPER LIMITS

$$\epsilon = 1.0 \pm 0.1$$

$$\epsilon = 1 \text{ exactly}$$

Bgd n_obs	0	3	0	3
0	2.35 indep of b		2.30 indep of b	
1	3.99	2.90	3.89	2.84
2	5.47	3.60	5.32	3.52
3	6.87	4.46	6.68	4.36
4	8.24	5.48	7.99	5.34
...	...	...	...	...
20	28.3	25.04	27.05	24.04

$\uparrow$
 Less than
 10% bigger
 than for
 $\epsilon = 1 \text{ exactly}$

$\uparrow$ $\uparrow$
 $\Delta = 0$ for $b = 0$
 $\Delta = 3$ for large b

$$\sim n + \kappa \sqrt{n}$$

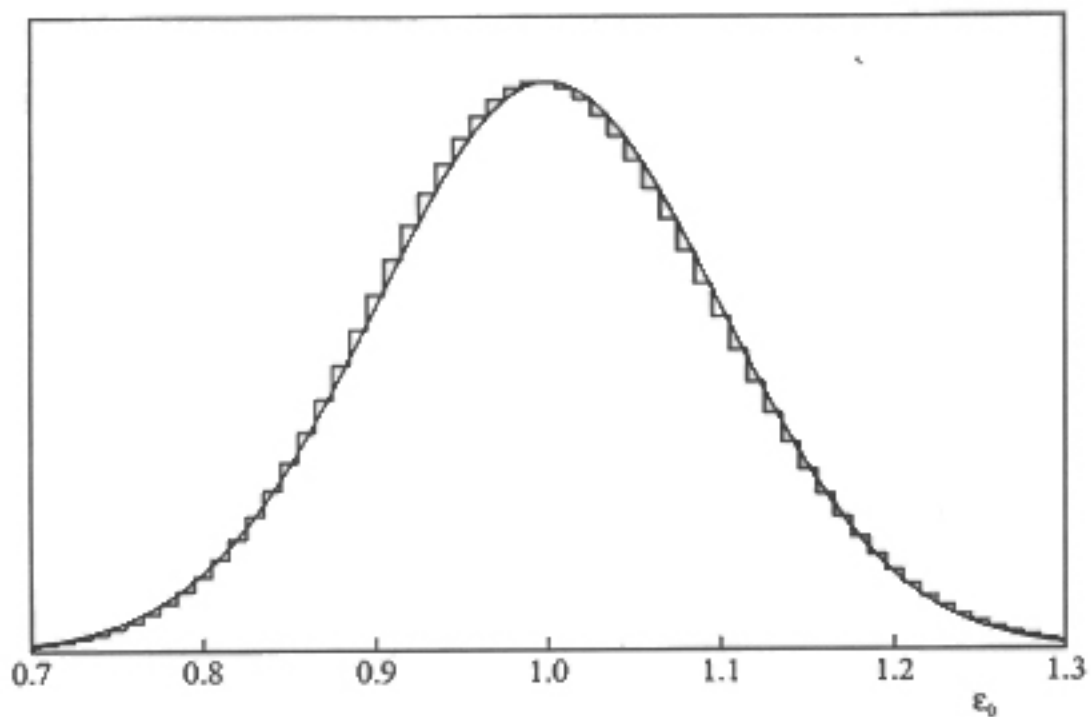


Figure 2: Comparison of our discrete probability for ϵ_0 (shown as a histogram, see eqn (11)) and Gaussian (continuous curve) for the case $\epsilon = 1 \pm 0.1$.

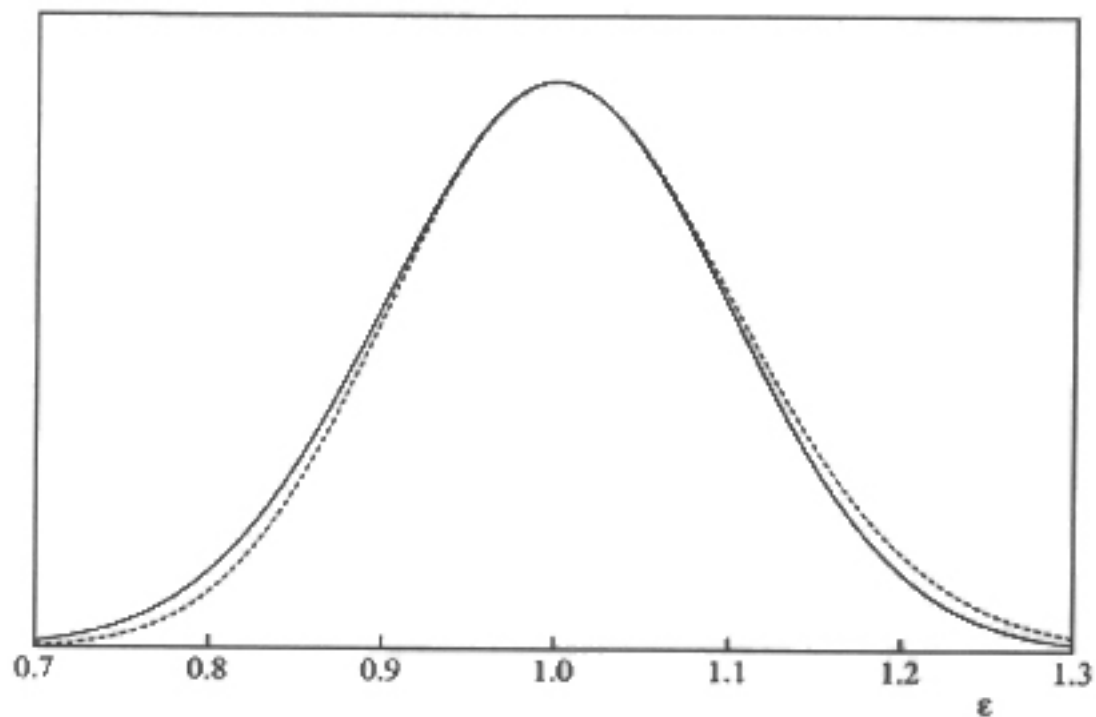


Figure 3: Comparison of our likelihood (dashed, see eqn (12)) and Gaussian (solid) for the case $\epsilon = 1 \pm 0.1$.

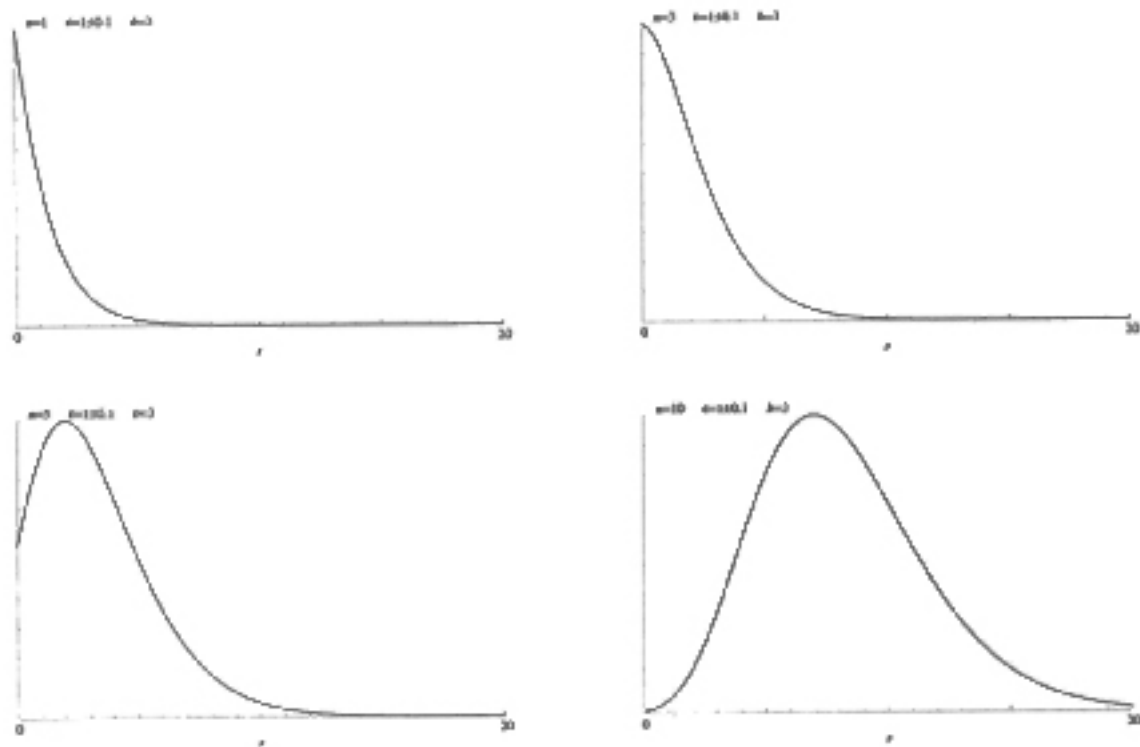


Figure 4: Posterior densities $p(s|n, b)$ vs s for $n = 1, 3, 5, 10$. In each case, $b = 3$ and $\epsilon = 1 \pm 0.1$ (i.e. $\kappa = 100$ and $m=99$).

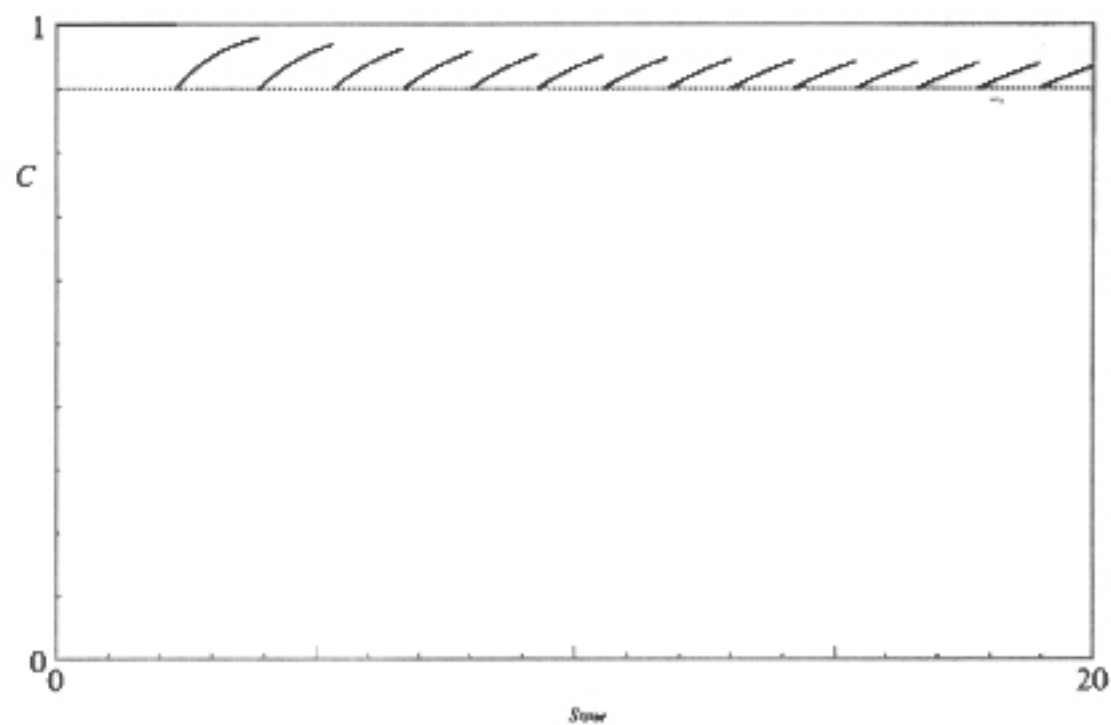


Figure 1: Coverage as a function of the true signal rate s for Bayes 90% limits, for the simple case of no background and no uncertainty on $\epsilon = 1$.

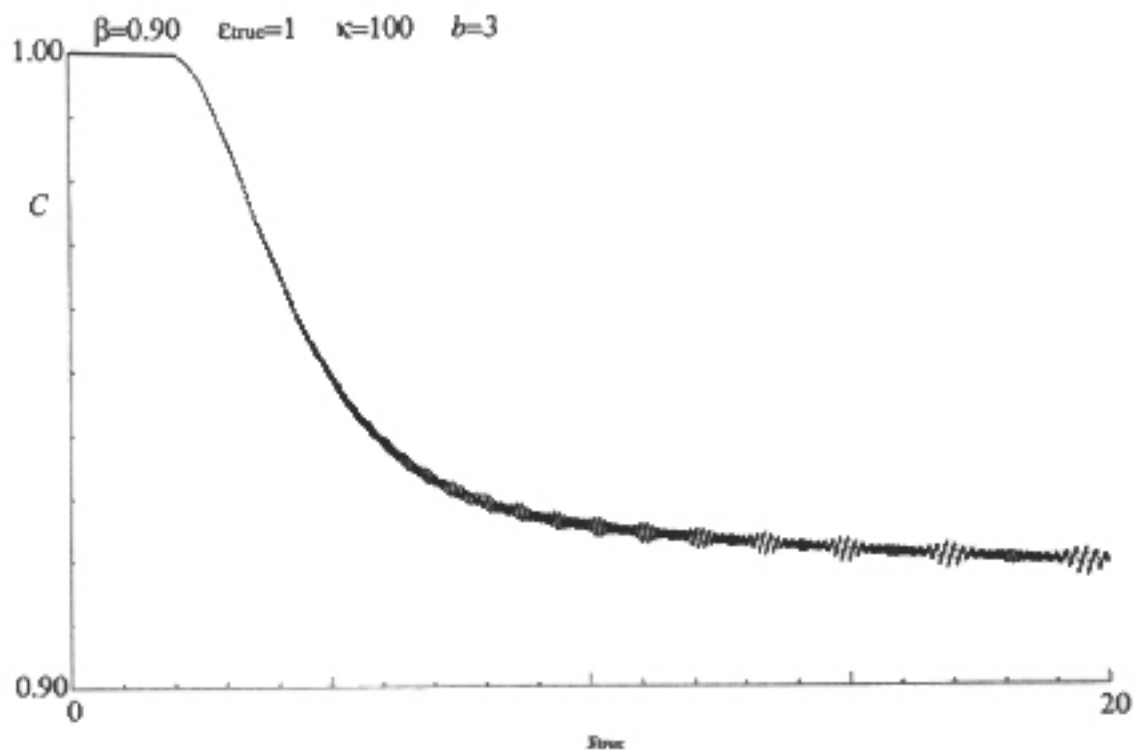


Figure 5: Coverage of 90% upper limits as a function of s_{true} for $\epsilon_{\text{true}} = 1$, nominal 10% uncertainty of the subsidiary measurement of ϵ , and $b = 3$ background expected.

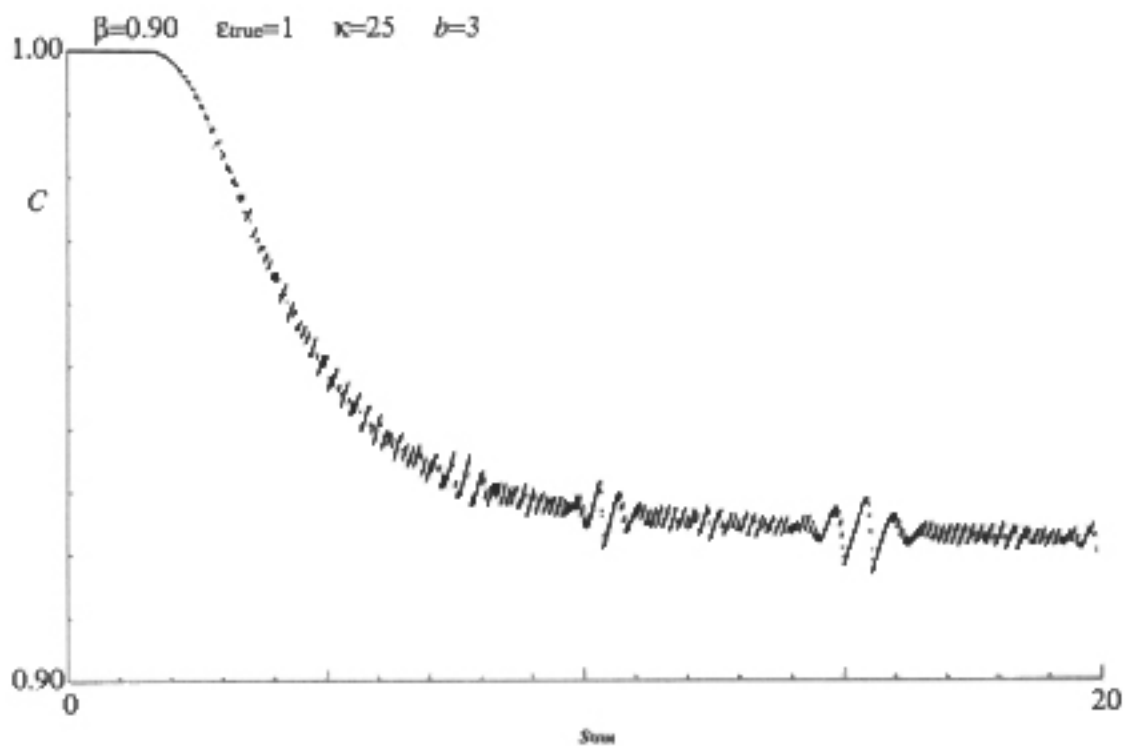


Figure 6: Coverage of 90% upper limits as a function of s_{true} for $\epsilon_{\text{true}} = 1$, nominal 20% uncertainty of the subsidiary measurement of ϵ , and $b = 3$ background expected.

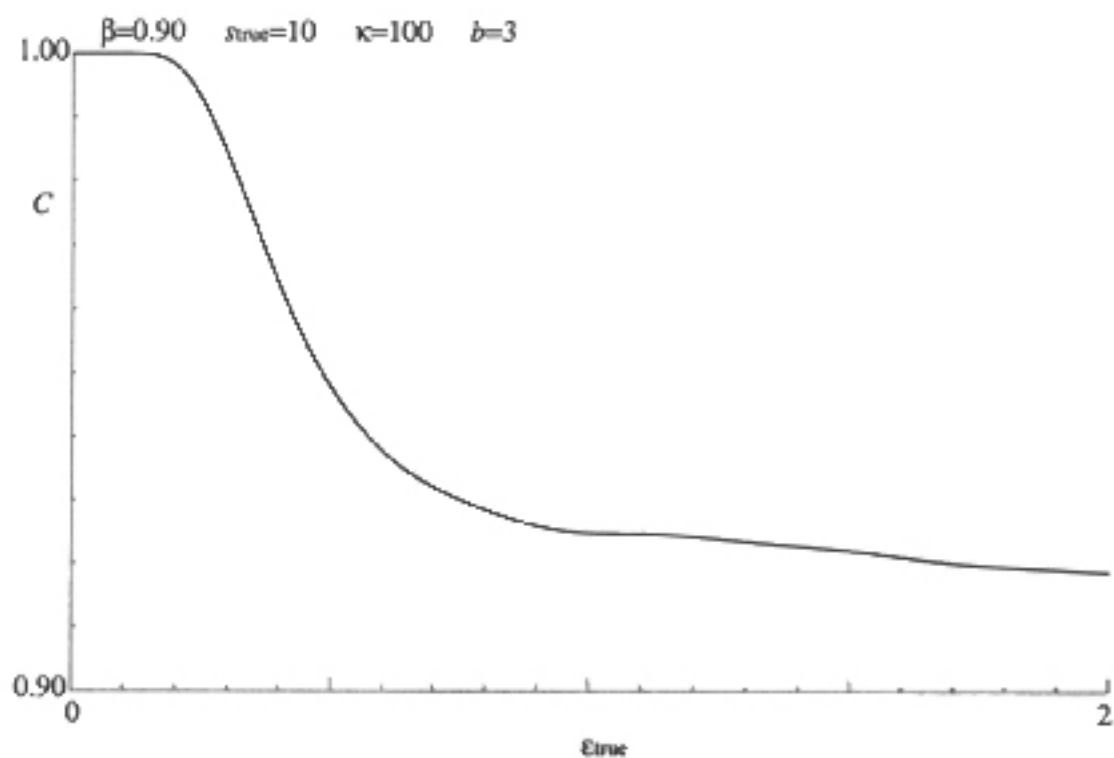


Figure 7: Coverage of 90% upper limits as a function of ϵ_{true} for $s_{\text{true}} = 10$, nominal 10% uncertainty of the subsidiary measurement of ϵ , and $b = 3$ background expected.

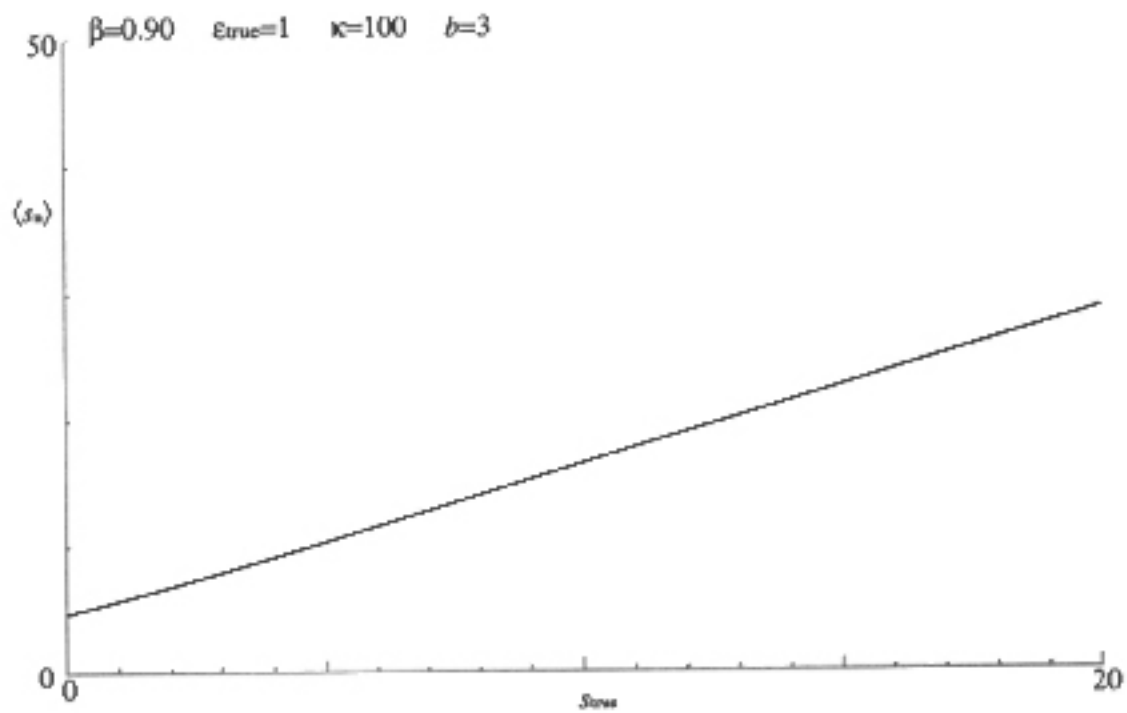


Figure 8: Sensitivity of 90% upper limits as a function of s_{true} for $\epsilon_{\text{true}} = 1$, nominal 10% uncertainty of the subsidiary measurement of ϵ , and $b = 3$ background expected.

Frequentist

Full Method

Imagine just 2 parameters

σ and LA

and 2 measurements

N and M



Physics

Nuisance

Do Neyman construction in 4-D

Use observed N and M, to give

Confidence Region



Then project onto σ axis

This results in OVERCOVERAGE

Aim to get better shaped region, by suitable choice of ordering rule

Example: Profile likelihood ordering

$$\frac{L(N_0 M_0; \sigma, LA_{best}(\sigma))}{L(N_0 M_0; \sigma_{best}, LA_{best}(\sigma))}$$

Full frequentist method hard to apply in several dimensions

Used in ≤ 3 parameters

For example: Neutrino oscillations (CHOOZ)

$$\sin^2 2\theta, \Delta m^2$$

Normalisation of data

Use approximate frequentist methods that reduce dimensions to just physics parameters

e.g. Profile pdf

$$\text{i.e. } pdf_{\text{profile}}(N; \sigma) = pdf(N, M_0; \sigma, LA_{\text{best}})$$

Contrast Bayes marginalisation

Distinguish “profile ordering”

Method: Mixed Frequentist - Bayesian

Bayesian for nuisance parameters and

Frequentist to extract range

Philosophical/aesthetic problems?

Highland and Cousins



(Motivation was paradoxical behavior of Poisson limit when LA not known exactly)

Coverage studied by Tegenfeldt + Conrad

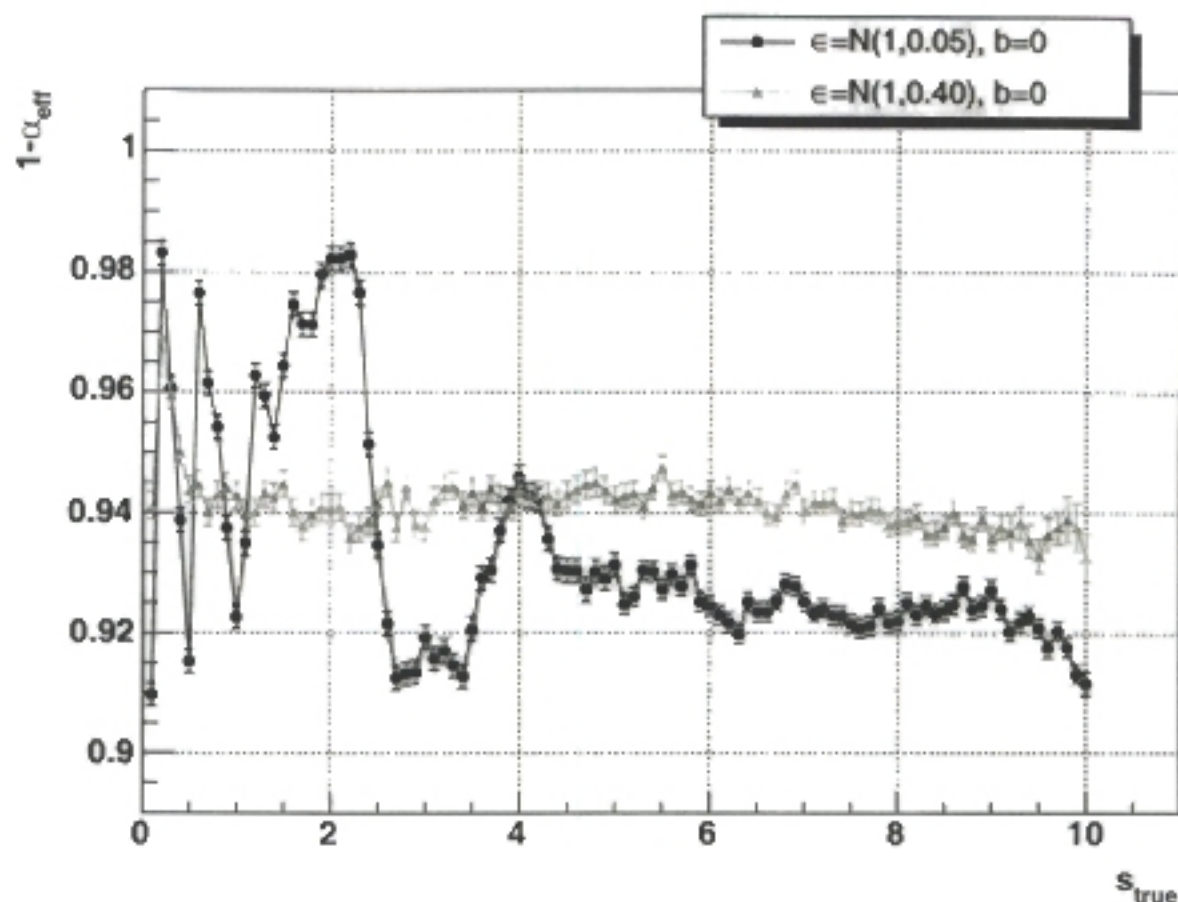


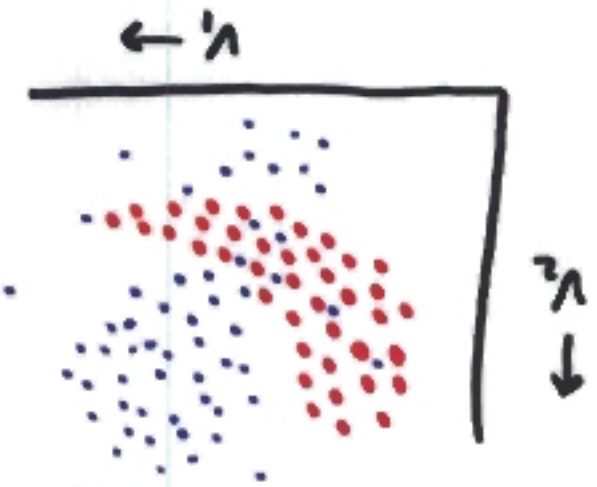
Fig. 1. Calculated coverage as function of signal hypothesis. Two case are shown: 5 % and 40 % Gaussian uncertainties in the signal efficiency. The nominal coverage was 90%.

Tegenfeldt + Conrad

Feldman - Cousins + Bayes

MULTIVARIATE ANALYSIS

Aim to separate **SIGNAL** FROM BACKGROUND



NEYMAN-PEARSON THEOREM

1) MINIMIZE ALL POSSIBLE CONTOURS THAT
SELECT SIGNAL WITH $\alpha\%$ EFFICIENCY

(LOSS = ERROR OF 1% KIND)

2) BEST IS ONE CONTAINING MINIMAL

AMOUNT OF BGD (CONSTANT = ERROR OF 2%)

EQUIVALENT TO ORDERING DATA BY

$$\alpha\text{-RATIO} = \frac{\alpha_S(v_1, v_2, \dots)}{\alpha_B(v_1, v_2, \dots)}$$

IF VARIABLES INDEPENDENT,

$$\rightarrow \frac{\alpha_S(v_1)}{\alpha_S(v_2)} \times \frac{\alpha_B(v_2)}{\alpha_B(v_1)} \times \dots$$

PROBLEM: DON'T KNOW χ^2 -RATIO
EXACTLY BECAUSE:-

- 1) GENERATED BY M.C. WITH FINITE STATISTICS
- 2) UNCERTAIN PARAMETERS
(NUISANCE PARAMS, SYSTEMATICS)
- 3) NEGLECTED SOURCES OF BGD
- 4) HARD TO IMPLEMENT N-P IN MANY DIMENSIONS

METHODS: CUTS

FISHER DISCRIMINANT

PRINCIPAL COMPONENT ANALYSIS

INDEPENDENT COMP. ANALYSIS

BOOSTED TREE METHODS

KERNEL DENSITY ESTIMATION

NEURAL NETS * *

SUPPORT VECTOR MACHINES

⋮

USEFUL REFERENCES

H. PROSPER: 'MULTIVARIATE ANALYSIS'
(DURHAM)

J. FRIEDMAN: 'PREDICTIVE MACHINE
LEARNING' (PHYSTAT 2003)

R. BOCK: 'MULTIM. EVENT CLASSIFICATION
FOR γ RAY SHOWERS (DURHAM)

FNAL AAG [http://projects.fnal.gov/
tun2aag/](http://projects.fnal.gov/tun2aag/)

S. TOWERS: i) PROB DENSITY ESTIMATION.

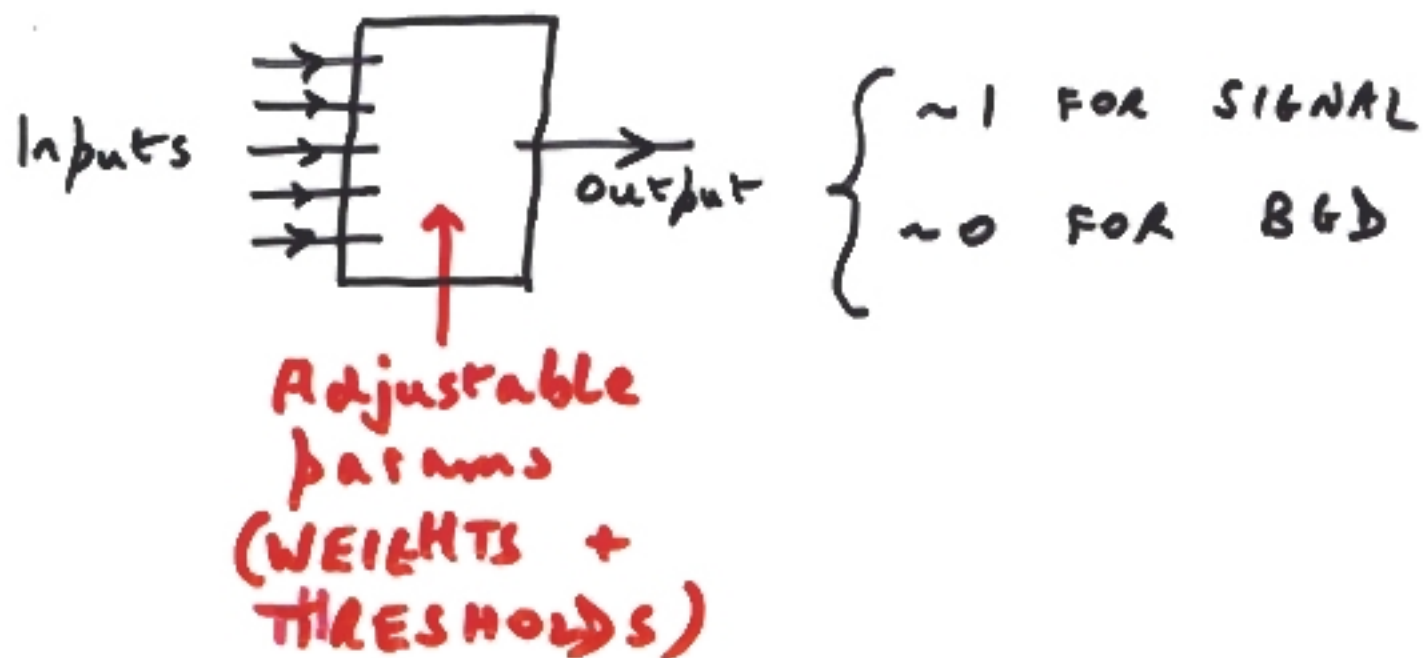
ii) REDUCE NUMBER OF VARIABLES
(BOTH AT DURHAM)

A. VAICHELIS: SUPPORT VECTOR MACHINES
(DURHAM)

NEURAL NETWORKS

TYPICAL APPLICATION:

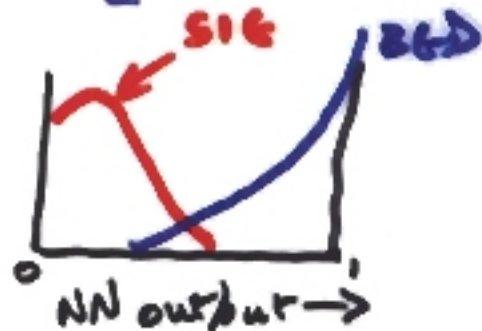
CLASSIFY EVENTS AS $\begin{cases} \text{SIGNAL} \\ \text{BACKGROUND} \end{cases}$



1) LEARNING PROCESS:

INPUT = $\begin{cases} \text{KNOWN SIGNAL} \\ \text{KNOWN BGD} \end{cases}$ $\leftarrow$ M.C.?

ADJUST PARAMS $\Rightarrow$
'BEST' OUTPUT

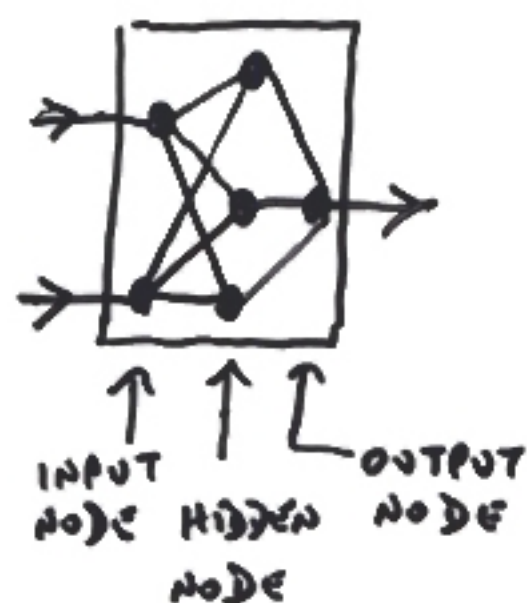


2) TESTING PROCESS

MAKE SURE NO 'OVERTRAINING'

3) USE TRAINED NET ON ACTUAL DATA,
CLASSIFY AS SIGNAL IF NN OUTPUT $\geq C.C.$

How DOES IT WORK?

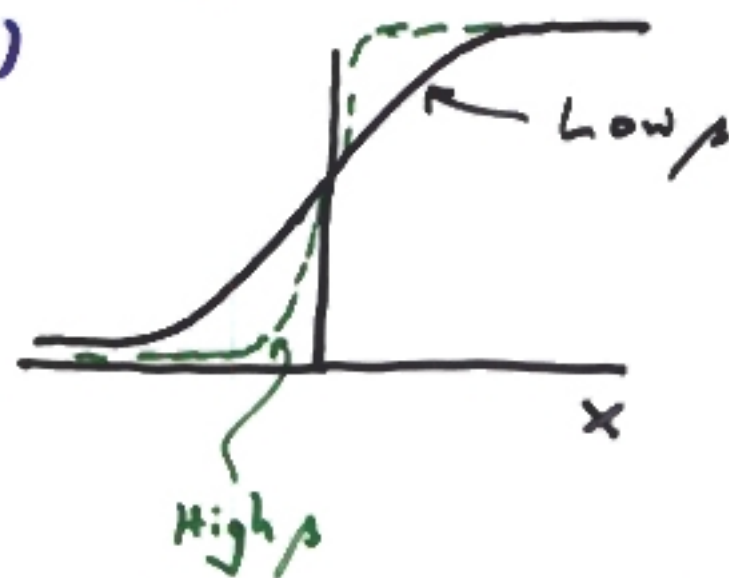


FOR EACH NODE

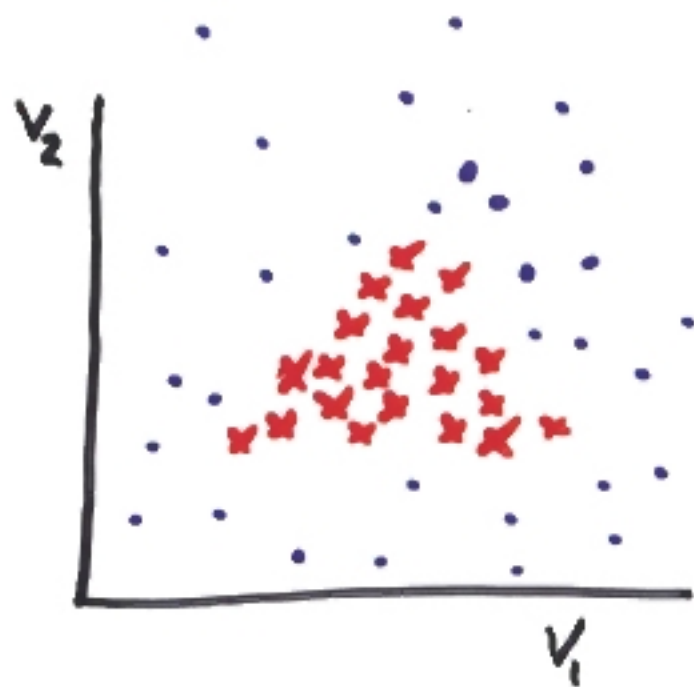
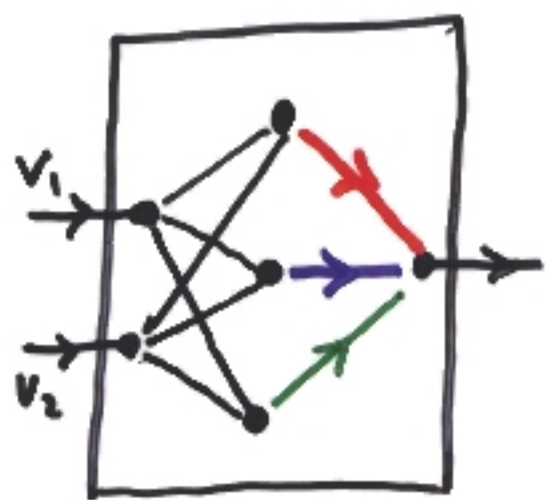
$$\text{Output} = F\left[\sum \text{Input}_i \times \underset{\substack{\uparrow \\ \text{PARAMS}}}{W_i} + \underset{\substack{\uparrow \\ \text{PARAMS}}}{T}\right]$$

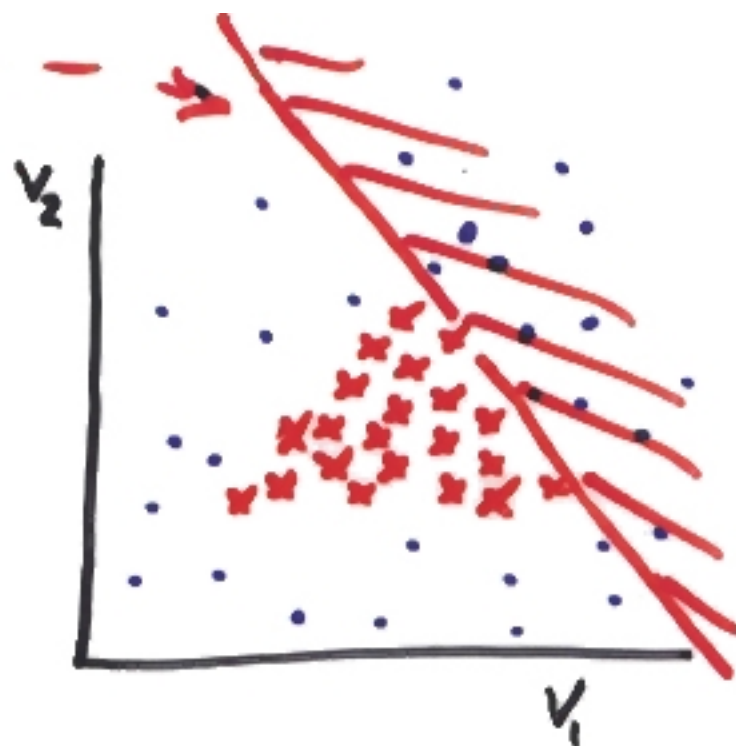
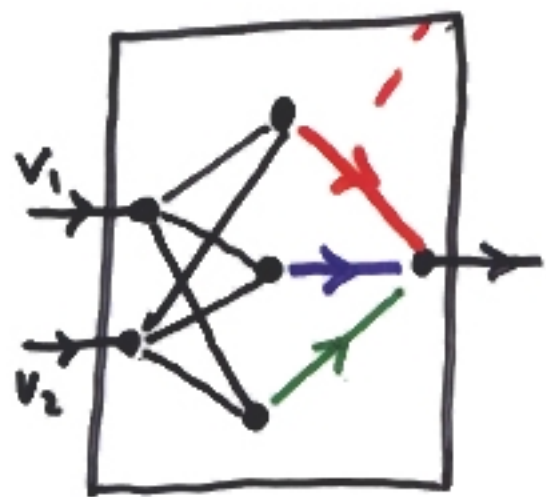
Typical $F(x)$

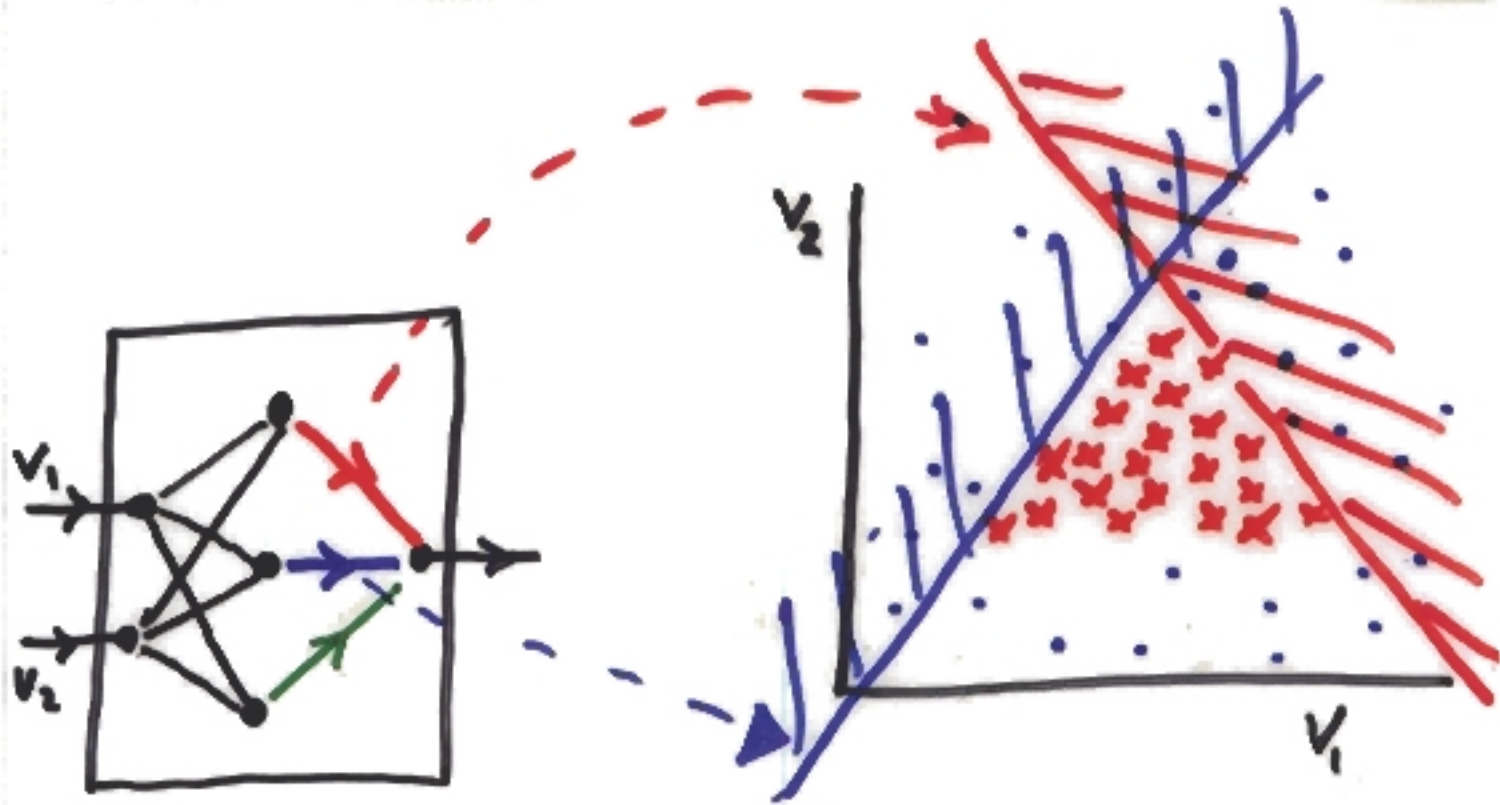
$$\frac{1}{1 + e^{-\beta x}}$$

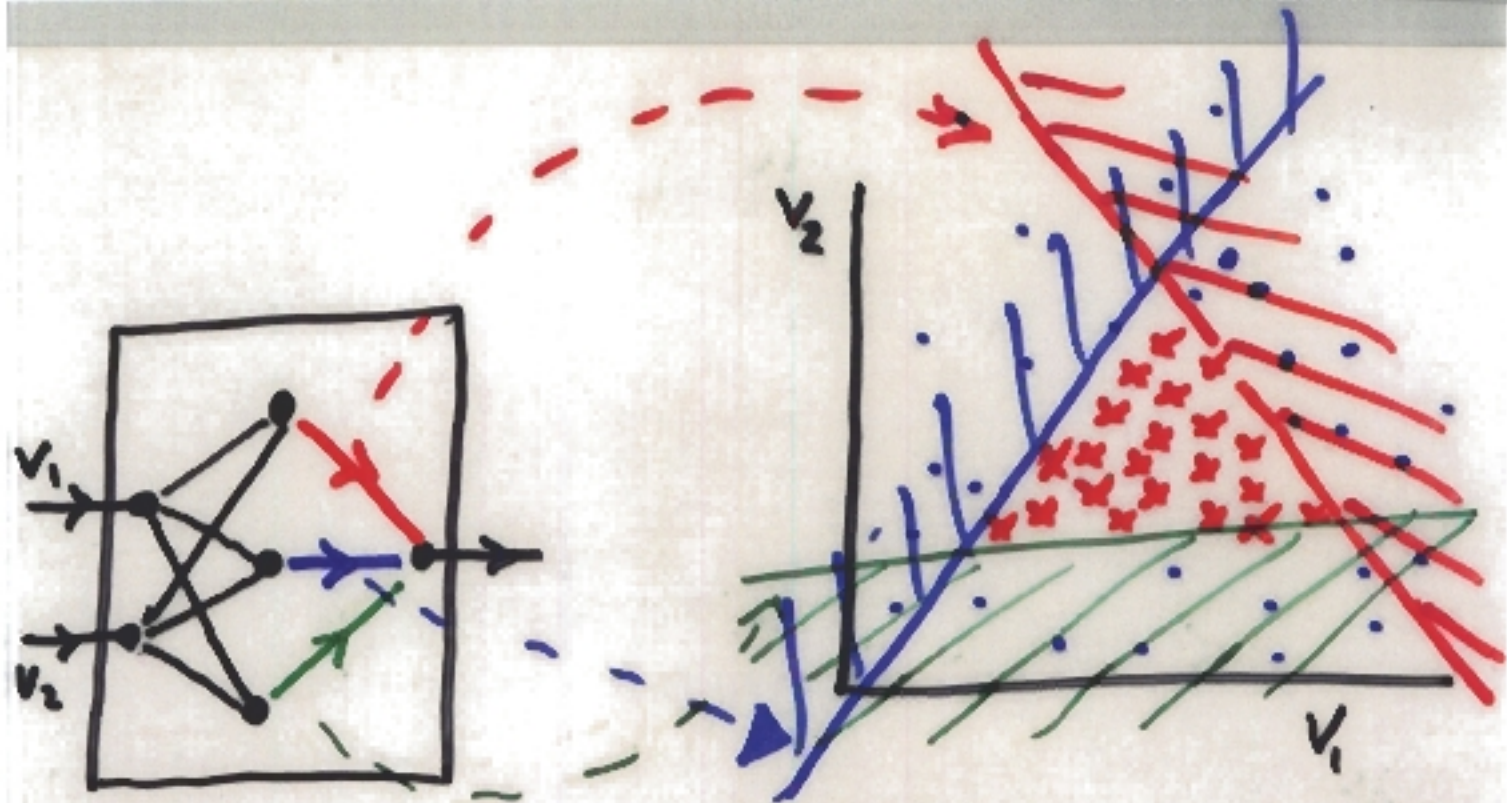


$\Rightarrow$ Output of node in "ON"
if $\sum I_i w_i + T > 0$
This is "hyper-plane" in I . space









$$\text{Output} = F[0.4 H_1 + 0.4 H_2 + 0.4 H_3 - 1.0]$$

Output = "ON" only if H_1, H_2, H_3
all are "ON"

N.B.

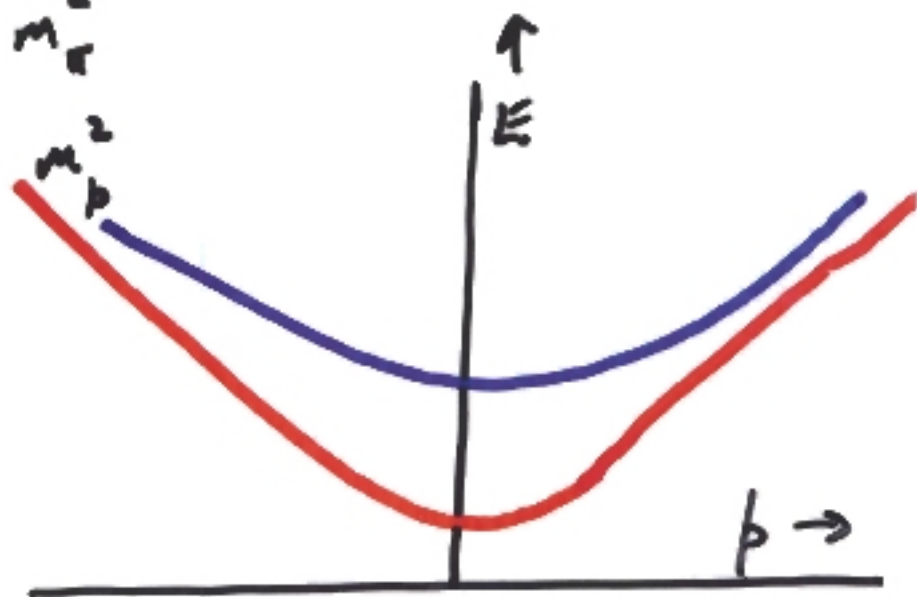
- 1) Complexity of final region depends on number of hidden nodes
 - 2) Finite $\beta \Rightarrow$ rounded edges for selected region.
- [Output contour lines in v_1 - v_2 plane]

TOY EXAMPLE

Try to separate $\left\{ \begin{matrix} \pi \\ p \end{matrix} \right\}$ using p or E

π : $E^2 = p^2 + m_\pi^2$

p : $E^2 = p^2 + m_p^2$



Easy: $p = 0 \rightarrow 2 \text{ GeV}/c$

Harder: $p = -4 \rightarrow +4 \text{ GeV}/c$

Hardest $\left. \begin{matrix} p_x \\ p_y \\ p_z \end{matrix} \right\} = -4 \rightarrow +4 \text{ GeV}/c$

More realistic: Add scatter of data
about curves

Is NN better than simple cuts?

In principle, NO

[Can cut on complicated variable
e.g. NN output]

In practice, YES (usually)

But better NN performance

⇒ motivation to improve cuts.

PHYSICS EXAMPLE

Separate $e^+e^- \rightarrow c\bar{c}$
from: $b\bar{b}$, $q\bar{q}$, W^+W^- , ZZ
at LEP

Input variables: "lifetime"
Track rapidities
Secondary vertex mass
quality
etc.

ISSUES: PRE N-N. CUTS
MISSING VARIABLES
WHERE TO GET TRAINING/TESTING EVENTS
HOW MANY NN'S.
HOW MANY INPUT VARIABLES
HOW MANY HIDDEN NODES/LAYERS
SINGLE OUTPUT OR SEVERAL
RATIO OF $c\bar{c}$, $b\bar{b}$, $q\bar{q}$, ... TRAINING
EVENTS
SYSTEMATICS [USE DIFFERENT SETS OF
TESTING EVENTS]
STABILITY W.R.T. NN CUT

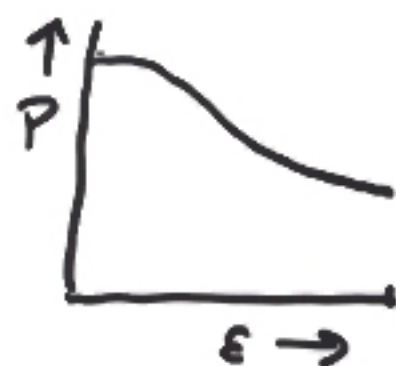
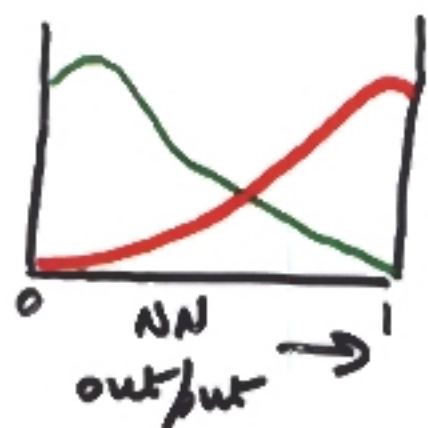
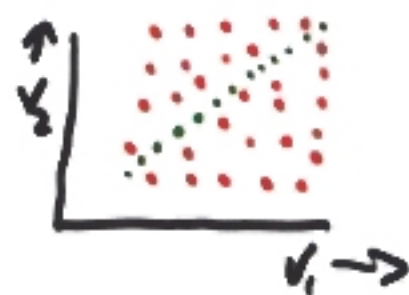
NN SUMMARY

ADVANTAGES:

VERY FLEXIBLE
CORRELATIONS O.K.

TUNABLE CUT

e.g. minimum σ



DISADVANTAGES

TRAINING TAKES TIME

TENDENCY TO INCLUDE TOO MANY VARIABLES

TREAT AS BLACK BOX

OVER LAST FEW YEARS, CHANGE IN
ATTITUDE FROM:

CONVINCE COLLEAGUES NN IS SENSIBLE
TO

"WHY DON'T YOU USE NN?"

BLUE

Best Linear Unbiased Estimate

$x_i \pm \sigma_i$, possibly correlated

$$\hat{x} = \sum \alpha_i x_i$$

$$\sum \alpha_i = 1$$

$$\sigma_{\hat{x}}^2 = \text{minimum}$$

LL, Duncan Gibault & Peter Clifford
NIM A270(1988) 110

For contemplation:

Given x_1 and x_2 (& error matrix),

Can $\hat{x}$ lie outside range $x_1 \rightarrow x_2$?