

# SPIDER 2015 Flight Systematics

B-mode from space workshop | Berkeley | Dec. 5, 2017



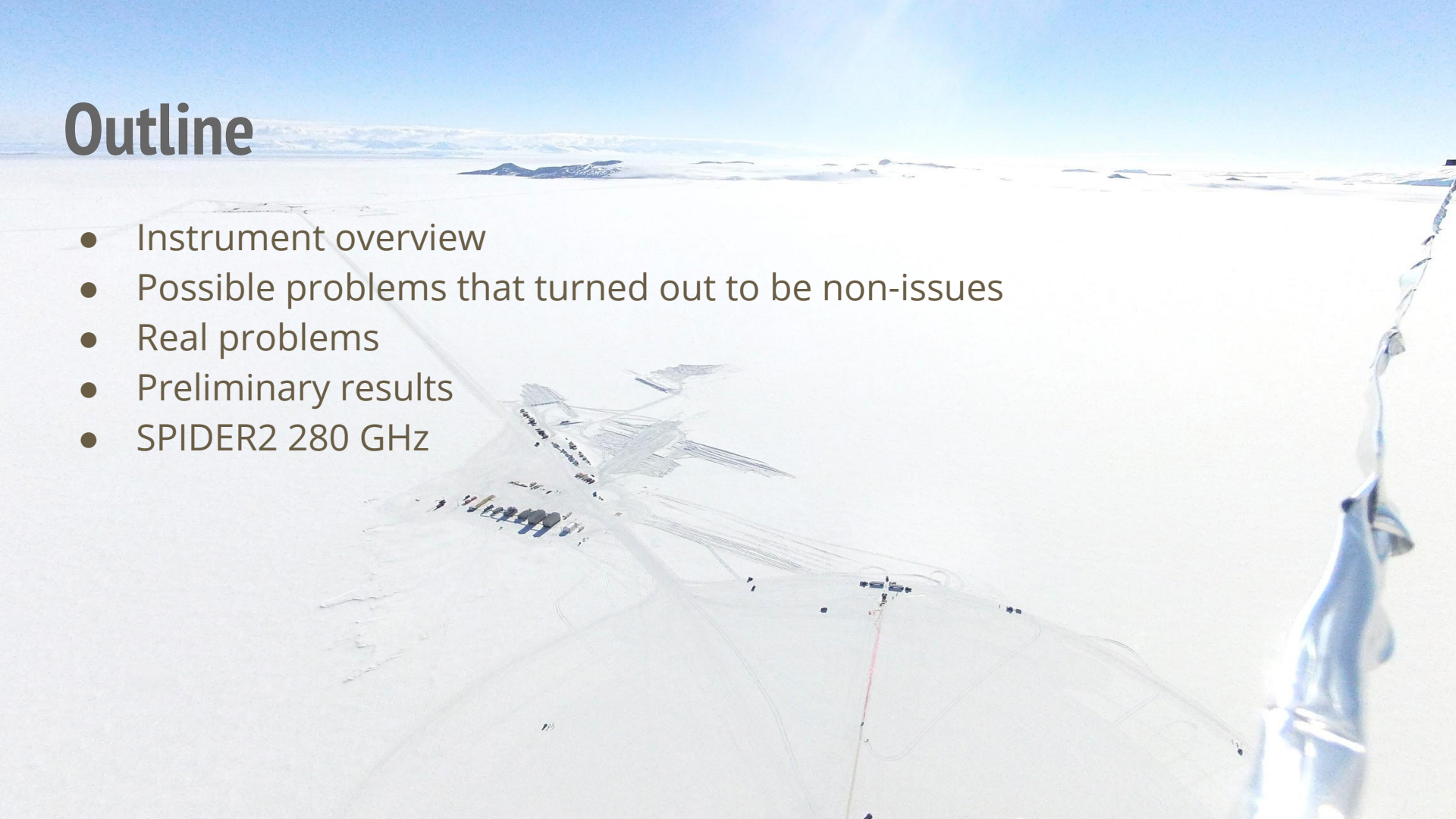
Edward Young  
Princeton University





# Outline

- Instrument overview
- Possible problems that turned out to be non-issues
- Real problems
- Preliminary results
- SPIDER2 280 GHz





# Instrument Overview

# Instrument overview

- Balloon-borne polarimeter
- Mapped approximately 10% of the sky in a 16.5 day flight
- Lightweight carbon fiber gondola
- 6 independent telescopes in a single cryogenic and vacuum system
  - 3 at 95 GHz, 3 at 150 GHz
- Custom control electronics



Photo from Steve Benton

# Cryogenic system

- 1300 Liter LHe4 cryostat
- Two vapor-cooled shields
- Capillary-fed 12 Liter superfluid tank
- Closed-cycle He3 adsorption fridge per telescope

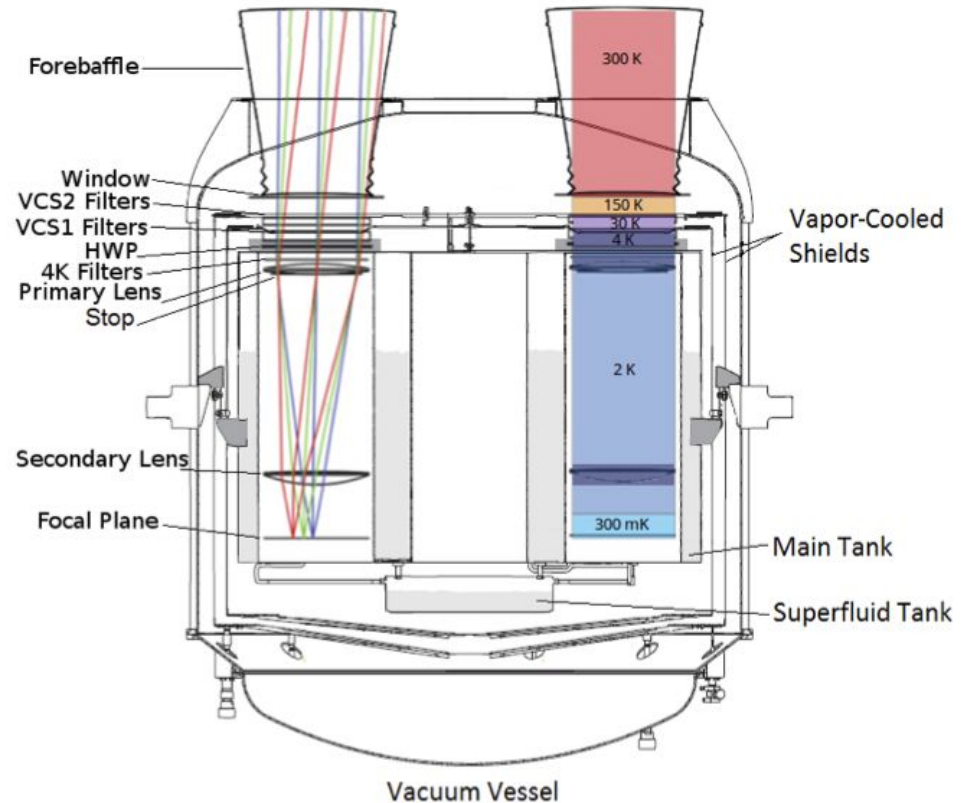


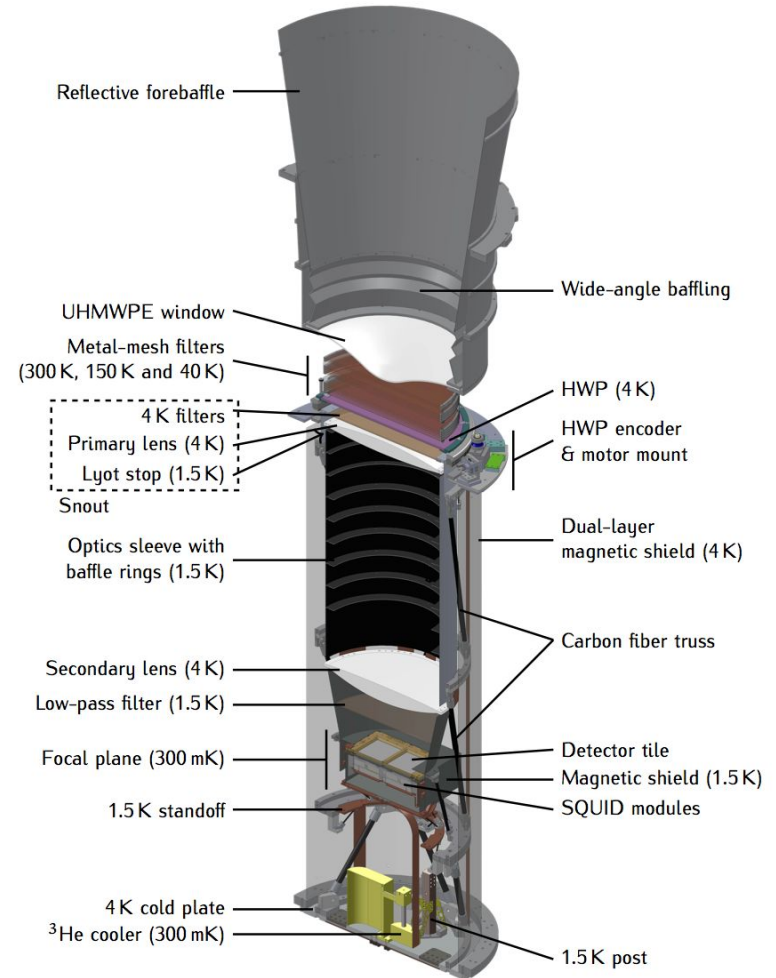
Figure from Johanna Nagy



# Telescope and detectors

- Part of the BICEP/Keck/SPIDER heritage
- Almost all optical filtering using reflective filters (one Nylon filter at 4 K)
- Internal baffles at 1.5 K

	95 GHz	150 GHz
FPU's	3	3
Detectors	697 (816)	1256 (1488)
FWHM (arcmin)	42	30
Observed loading (pW)	< .25	< .35
NET ( $\mu K \sqrt{s}$ )	7.1	5.3



# Half-wave plate

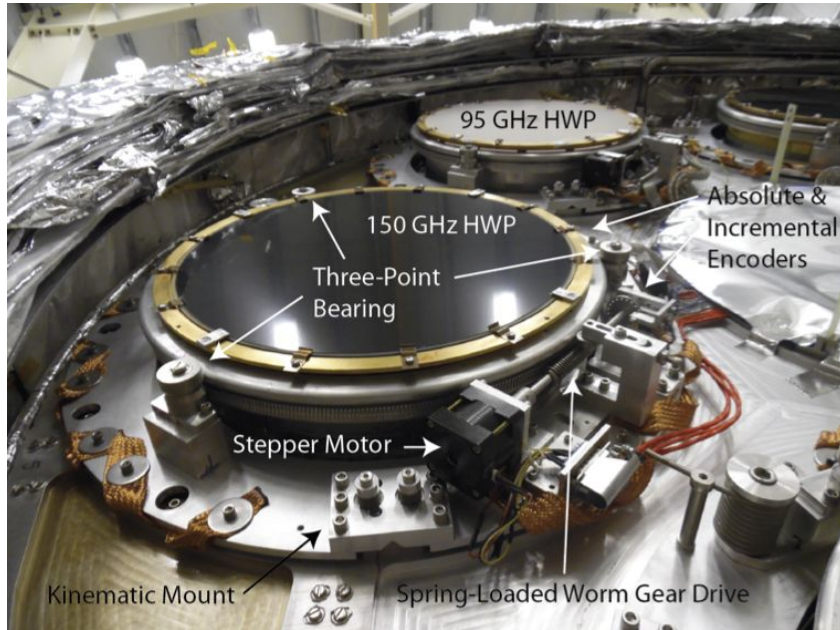


Photo from Johanna Nagy

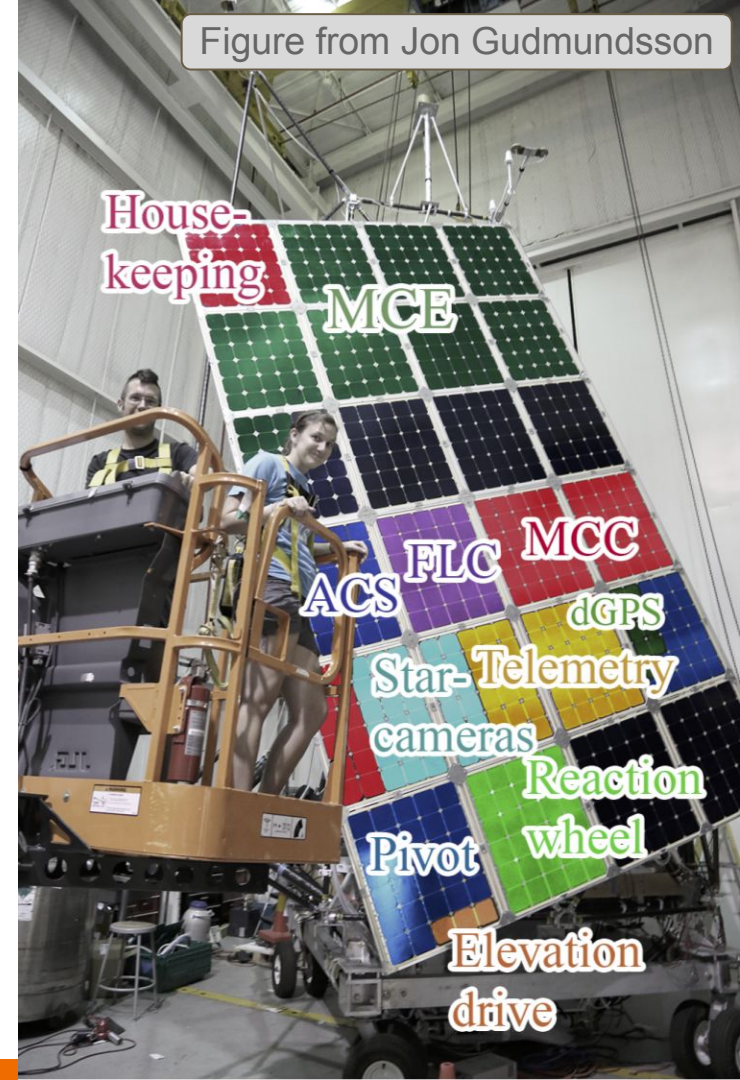
- Birefringent single-crystal sapphire with anti-reflection coating
- Mounted at 4 K
- Rotated twice a day - full Q/U coverage per pixel every 2 days



# Power

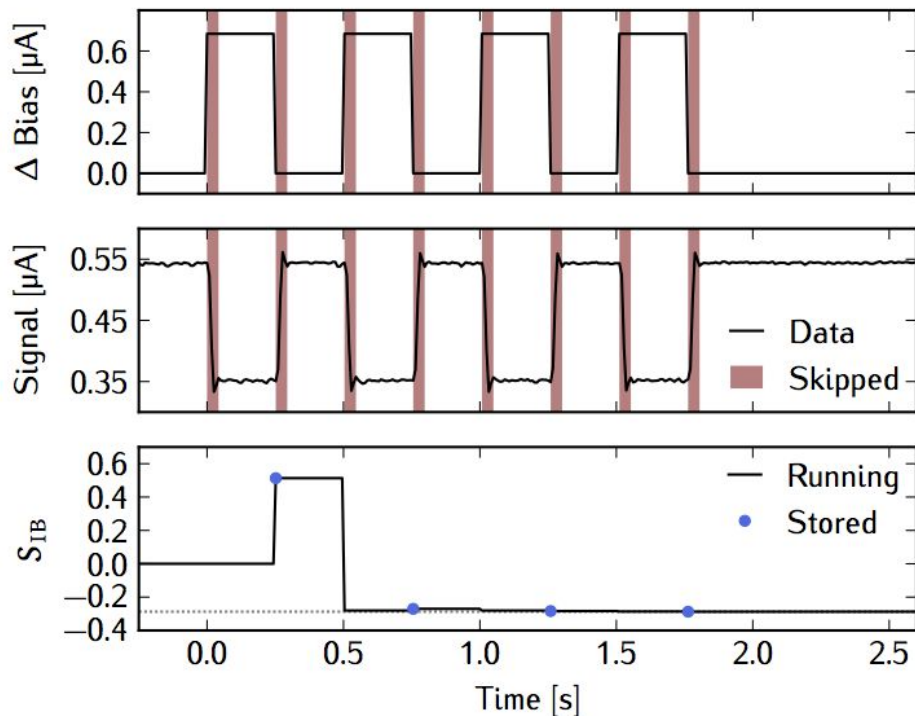
- Array 2200 W (peak), 1440 W (average)
- Two independent systems
- 35 V for switched mode DC power supply
- Charges 2 40 Ah/12 V lead acid battery

Figure from Jon Gudmundsson



# Autonomous detector operations

- SQUID tuning
  - Retuned after every fridge cycle
  - Compares to preflight templates and adjusts parameters as needed
  - ~5 minutes
- Detector responsivity
  - Electrical bias step as a proxy for gain
  - 2 seconds to run for .1% uncertainty on gain
  - Monitors and readjusts bias automatically during flight
- Fully automated
  - Downlinks minimal set of statistics to verify functionality



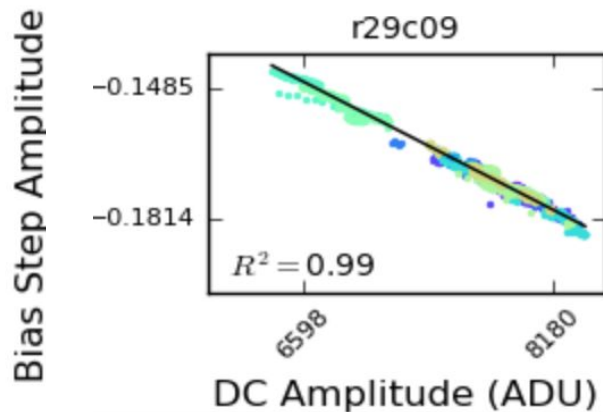


**Possible problems that weren't**



# Possible problems that weren't: Gain drift

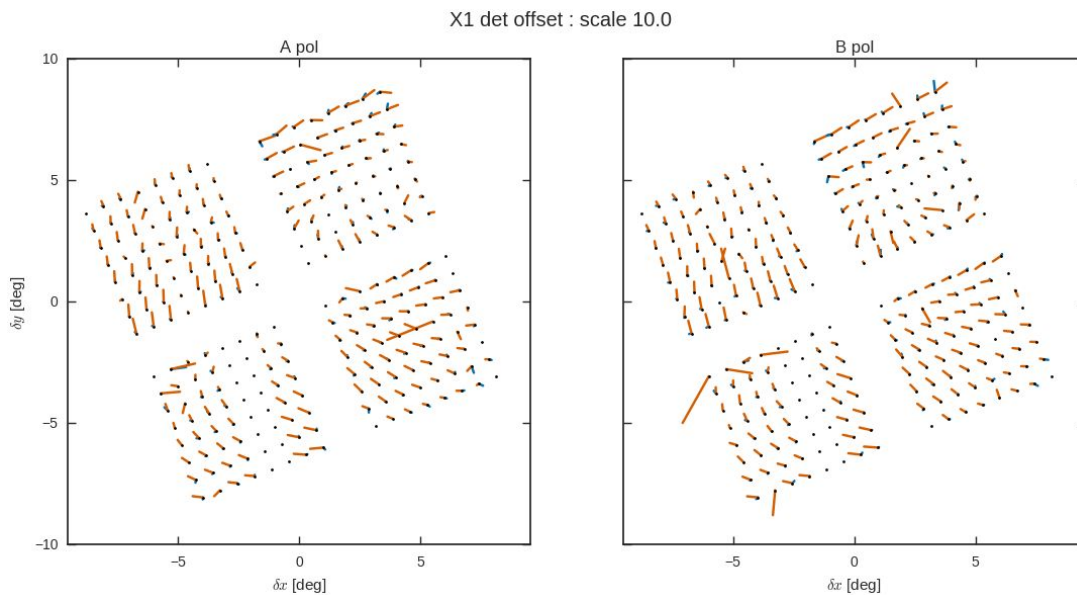
- Bias steps stopped halfway through flight on several FPUs
  - Bias step results were not downlinked during flight
- No rebiasing during this time
- Used detector DC level as a proxy for gain
- Turns out we were rebiasing too often



Plot from Anne Gambrel

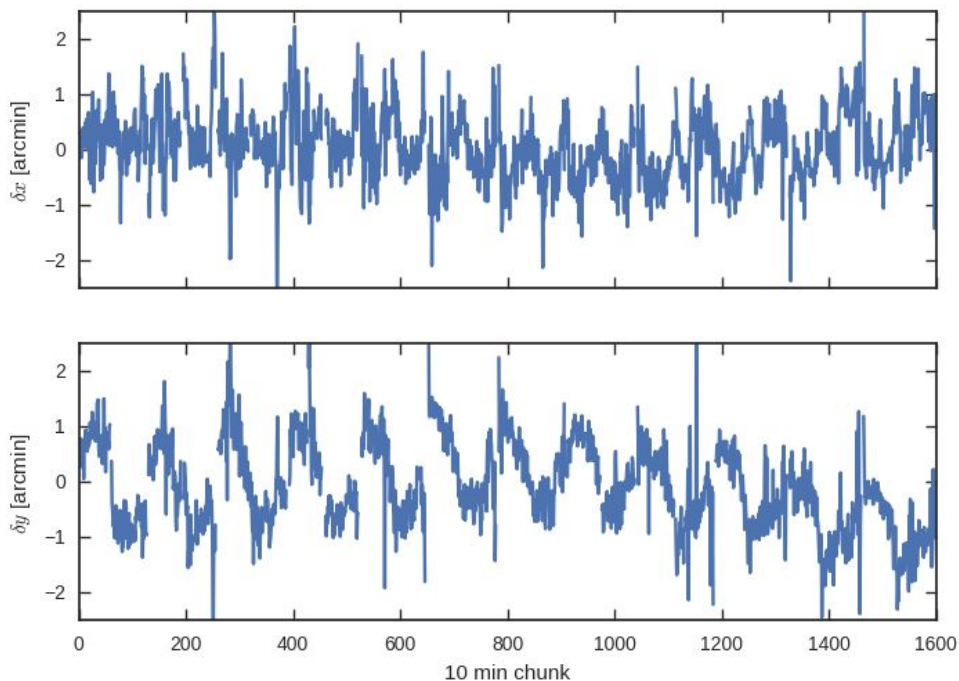
# Possible problems that weren't: Detector pointing

- Used a deprojection analysis with Planck
- Corrections to the plate-scale pointing of each detector



# Possible problems that weren't: Boresite pointing

SPIDER averaged offset

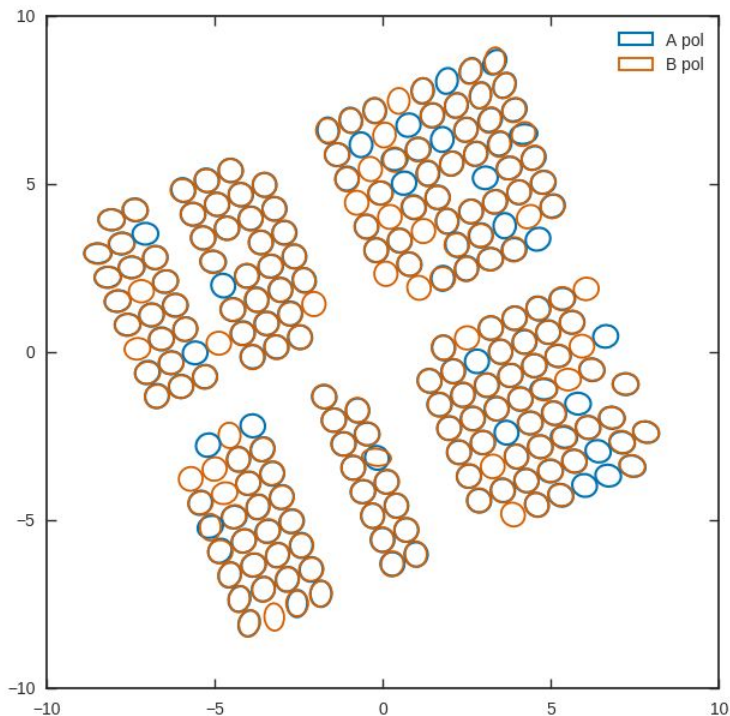


- Corrections relative to dedicated pointing system
- Uses the same sensors to get pointing so don't need to worry about referencing two instruments

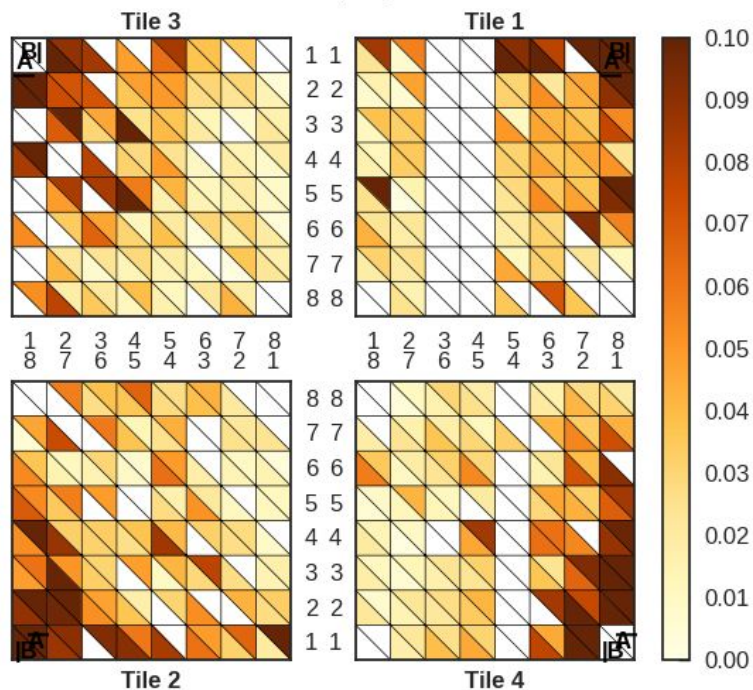


# Possible problems that weren't: Beam ellipticity

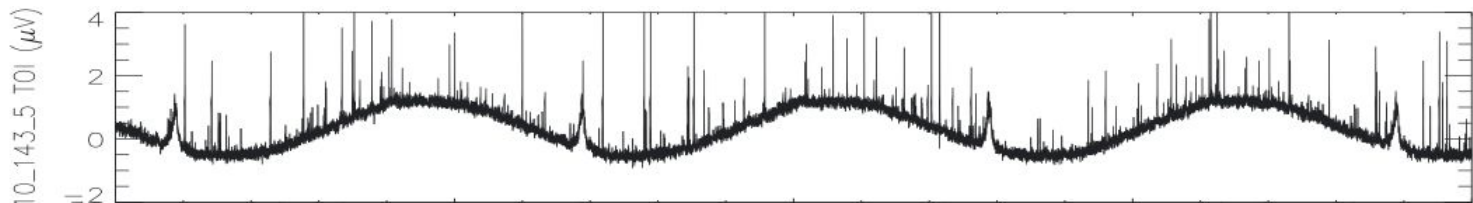
X1 Beam Ellipticity



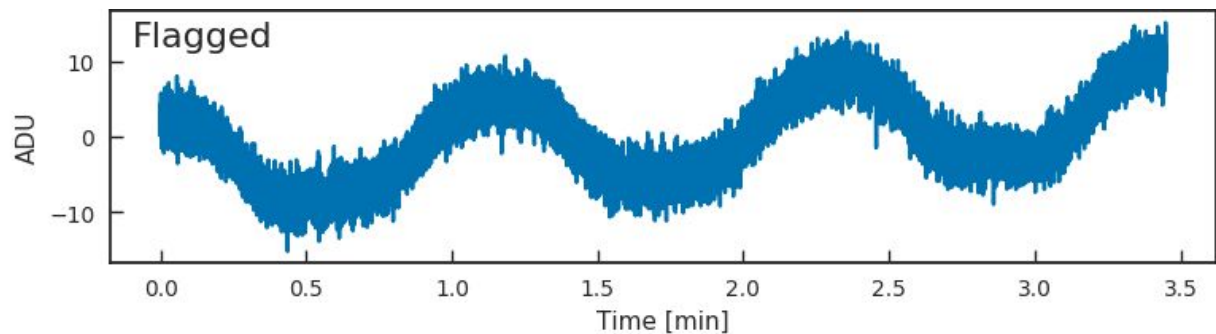
X1 ellipticity



# Possible problems that weren't: Cosmic rays



Planck  
143 GHz



SPIDER  
150 GHz

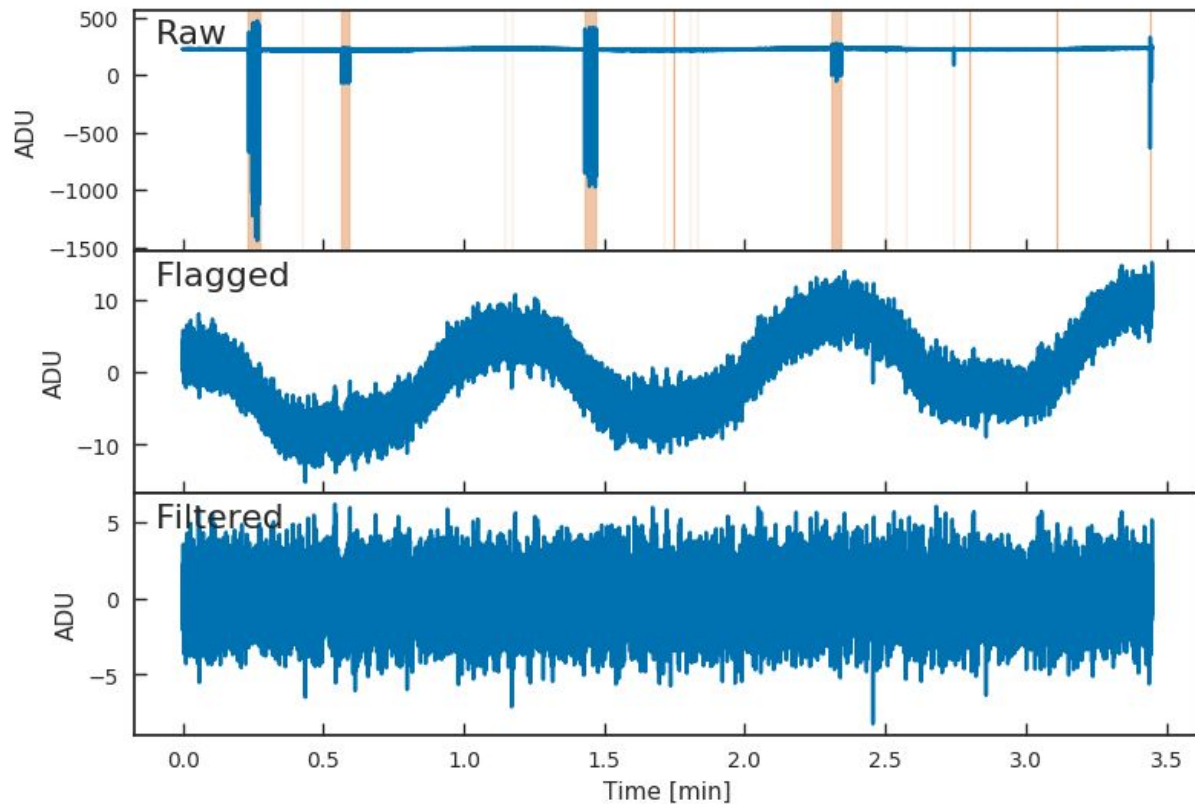
See Jeff Filippini's talk for more details!

A globe with a heatmap overlay. The central region is colored in bright red and orange, indicating high intensity or a significant feature. This central region is surrounded by yellow and light orange areas, which then transition into blue and purple areas towards the edges of the globe. The overall pattern suggests a concentration of activity or data in the center, with varying levels of intensity across the surface.

# Real Problems

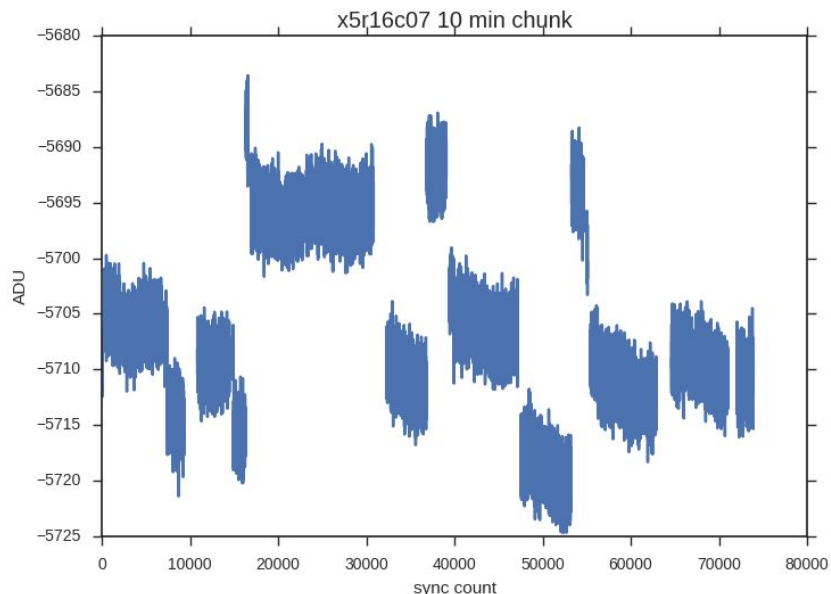


# Real problems: RF pickup



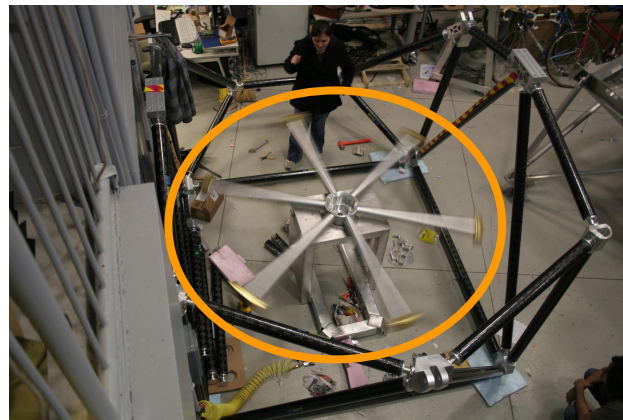
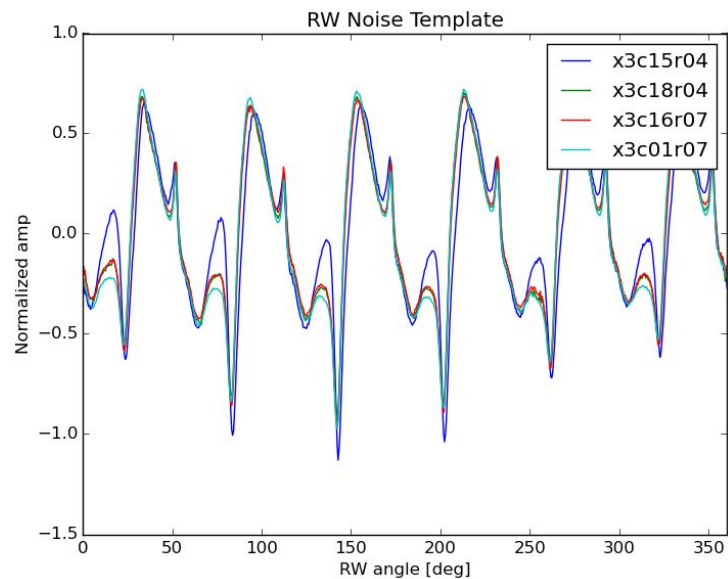
- Loss of ~10% of data on good channels
- Transmitters handshake every ~minute

# Real problems: RF pickup

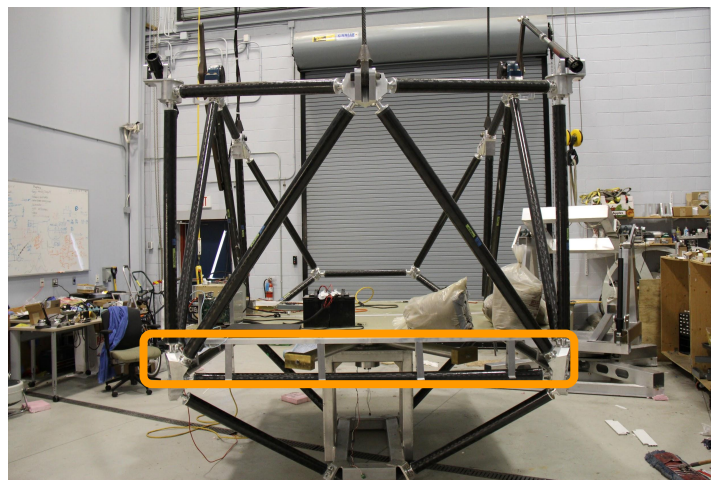


- Loss of DC level
- Difficult to reestablish DC level because it is caused by transmitter pulses, which simultaneously cause a loss of data
- Often flux jumps in one detector will cause a small DC level step in another detector in column

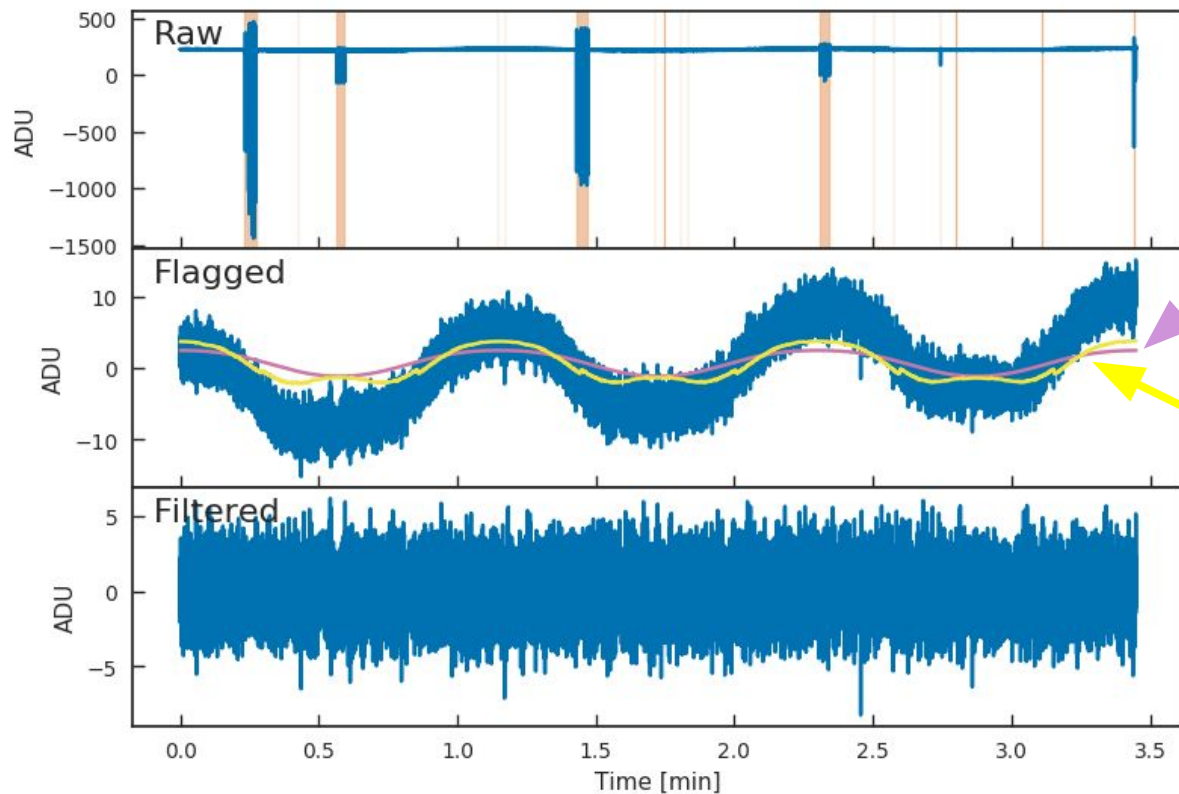
# Real problems: RF pickup



Reaction Wheel



# Real problems: Scan-synchronous noise



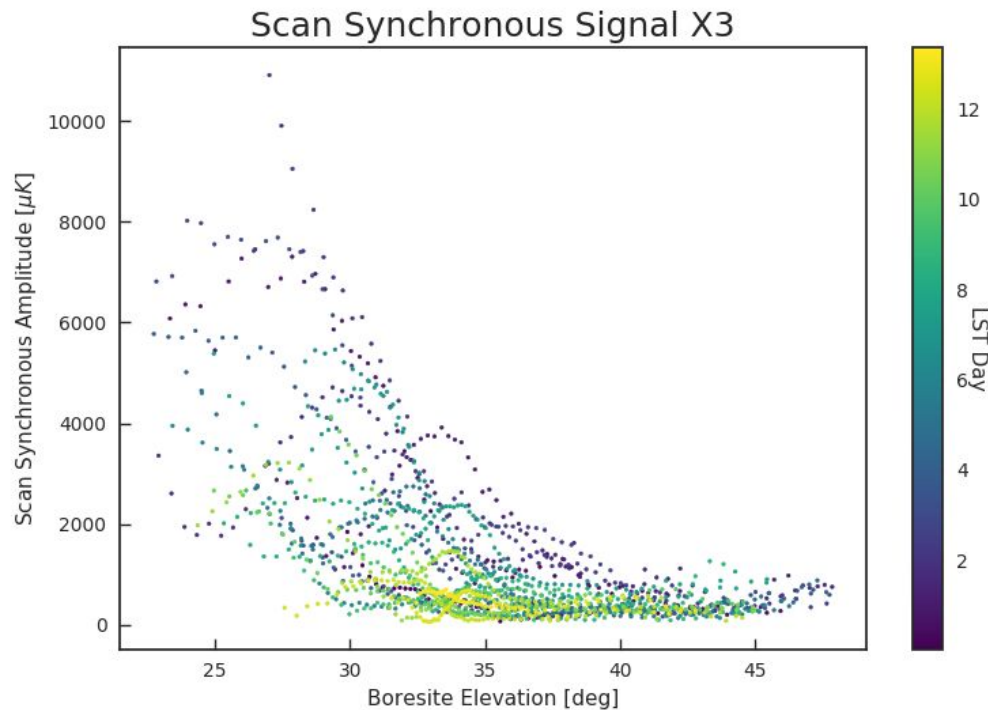
Dipole

Scan-synchronous noise



# Real problems: Scan-synchronous noise

- Boresite elevation dependent
- Requires heavy filtering to remove
  - Poly-5 removed per detector per half-scan
  - Terrible for filter function
  - Working on alternatives to poly-5 removal (SVD, template fitting, etc.)

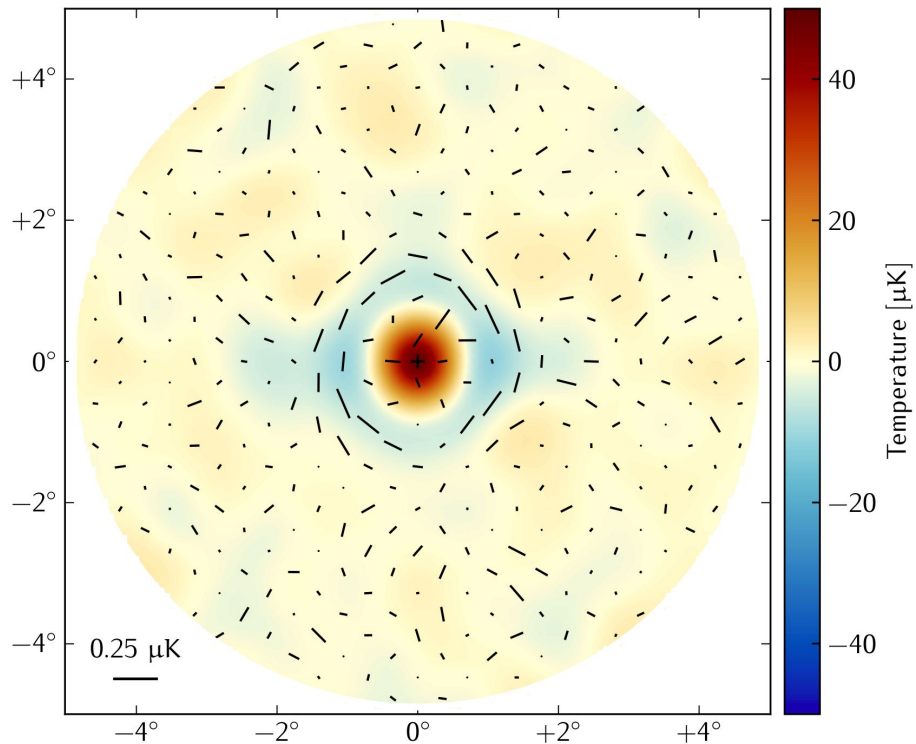




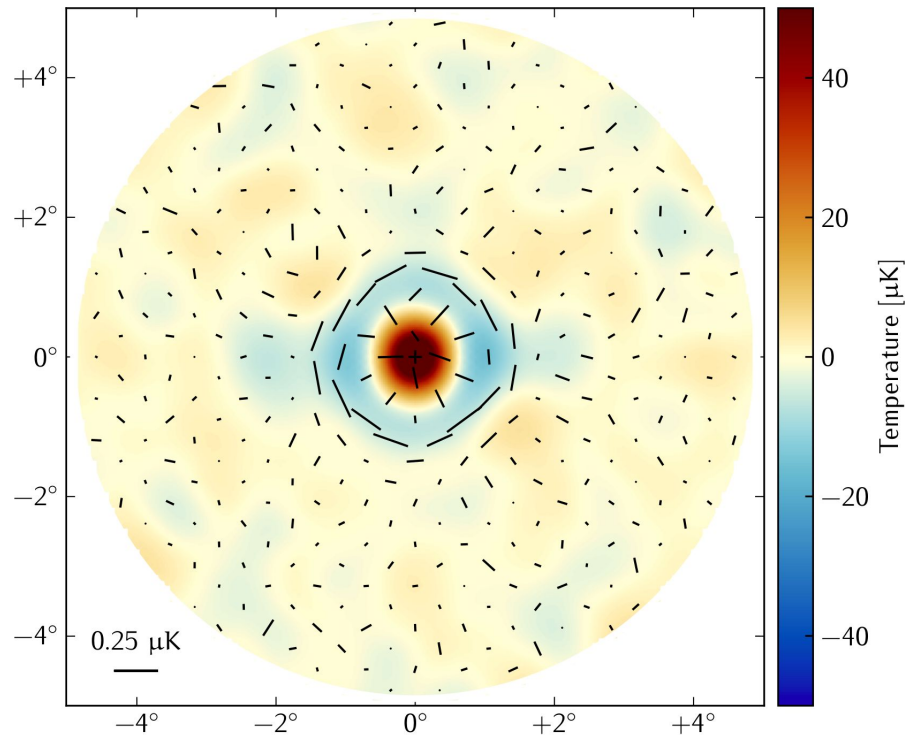
# Preliminary Science Results

# Beam stacks

95 GHz All Stack

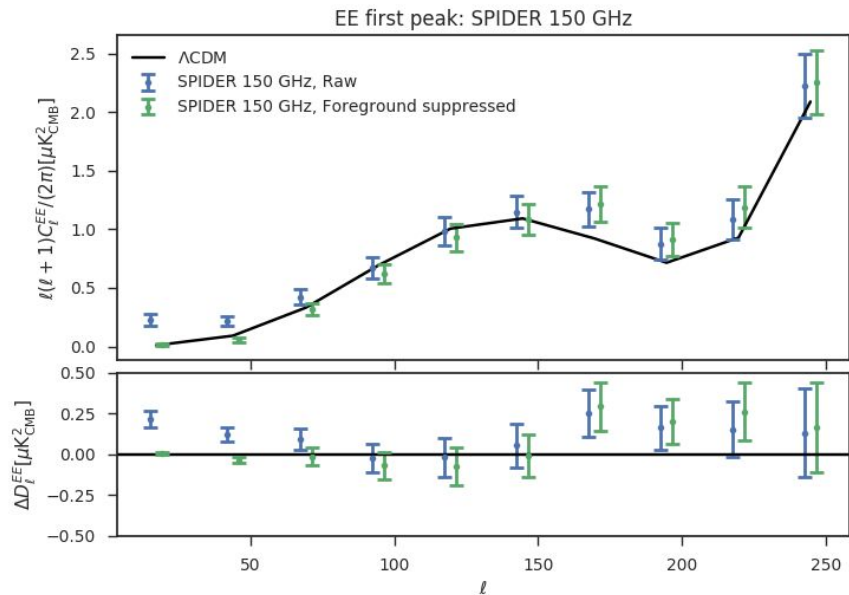
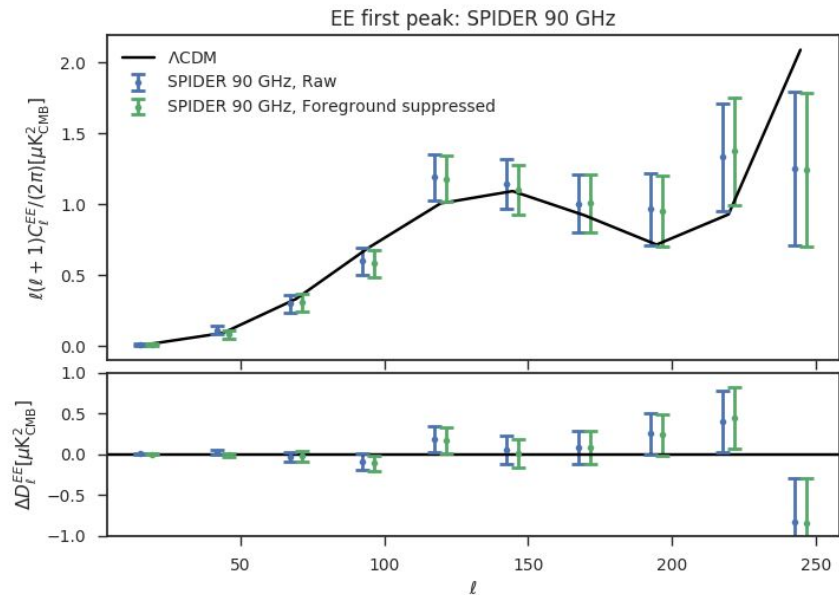


150 GHz All Stack



# Spectra

PRELIMINARY!





# SPIDER 2

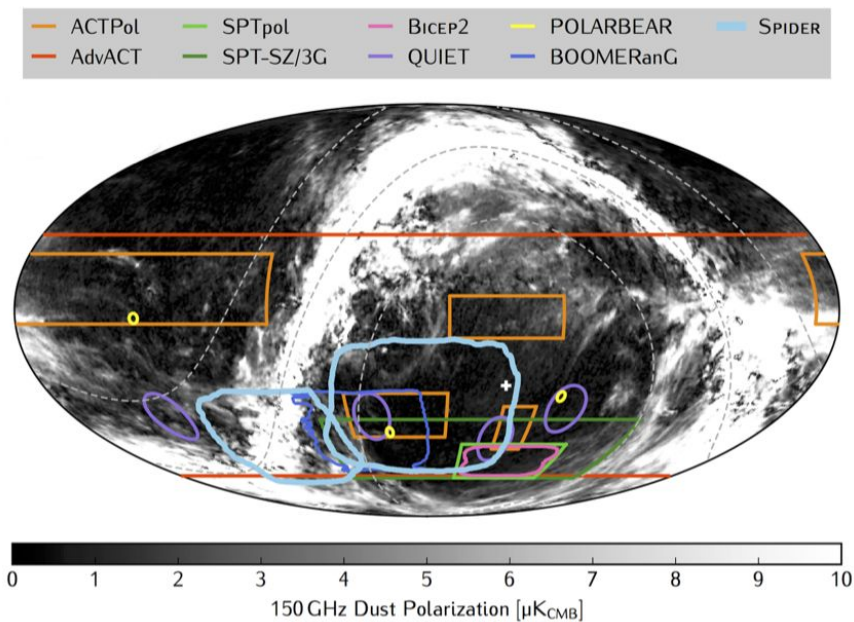


Figure from Sasha Rahlin

- 280 GHz FPUs (3)
- Launch December 2018
- Overlap with ground experiments for foreground rejection

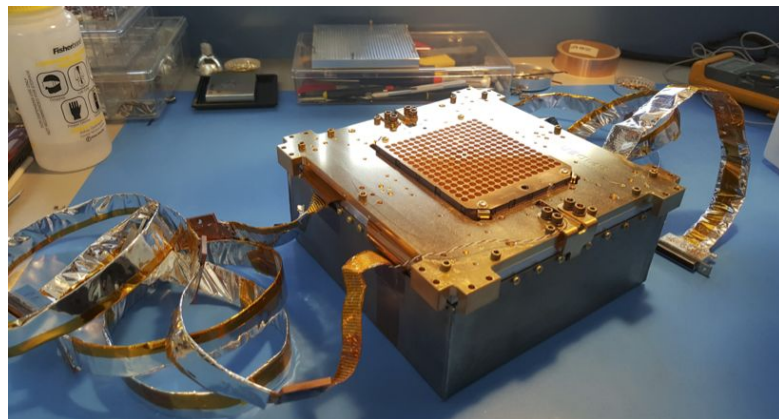


Photo from Stevie Bergman

# Takeaways

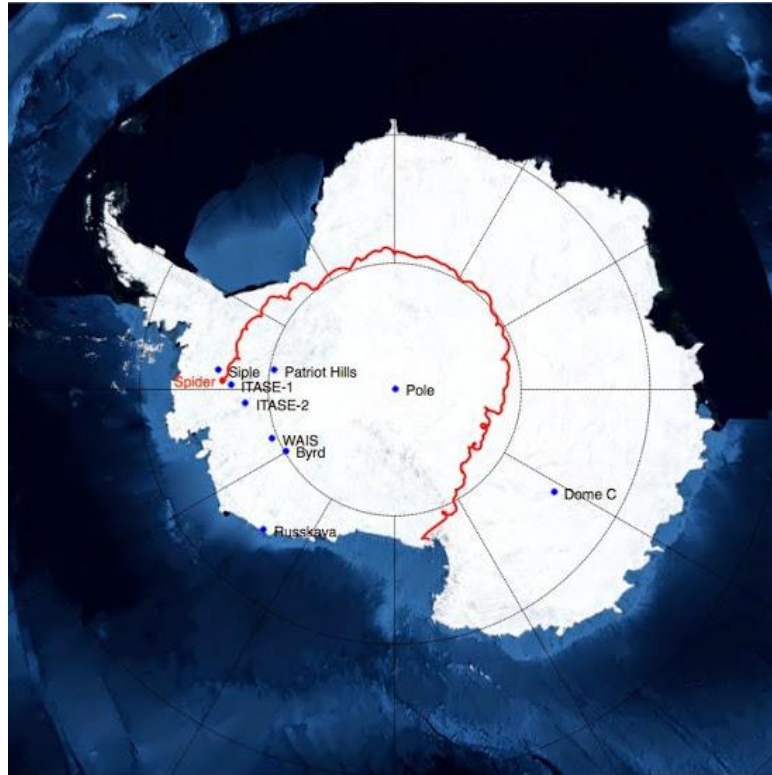
- Low detector loading, much lower than designed saturation power
- Successful autonomous operations
- No beam or pointing systematics
- Cosmic rays not a problem - see Jeff's poster
- Real problems are RF pickup and scan synchronous noise
  - Loss of data due to flagging
  - Aggressive poly filtering
- Competitive polarization maps at 95 and 150 GHz
- SPIDER2 will launch Dec. 2018 with 280 GHz detectors





# Bonus Slides

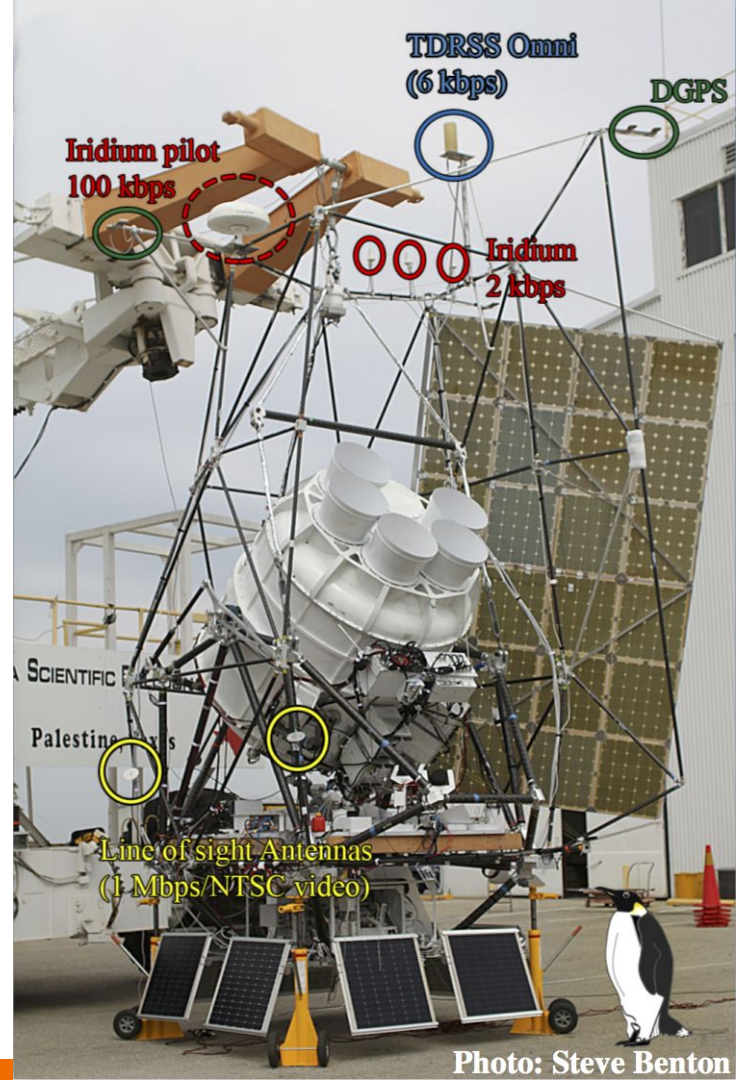
# Flight



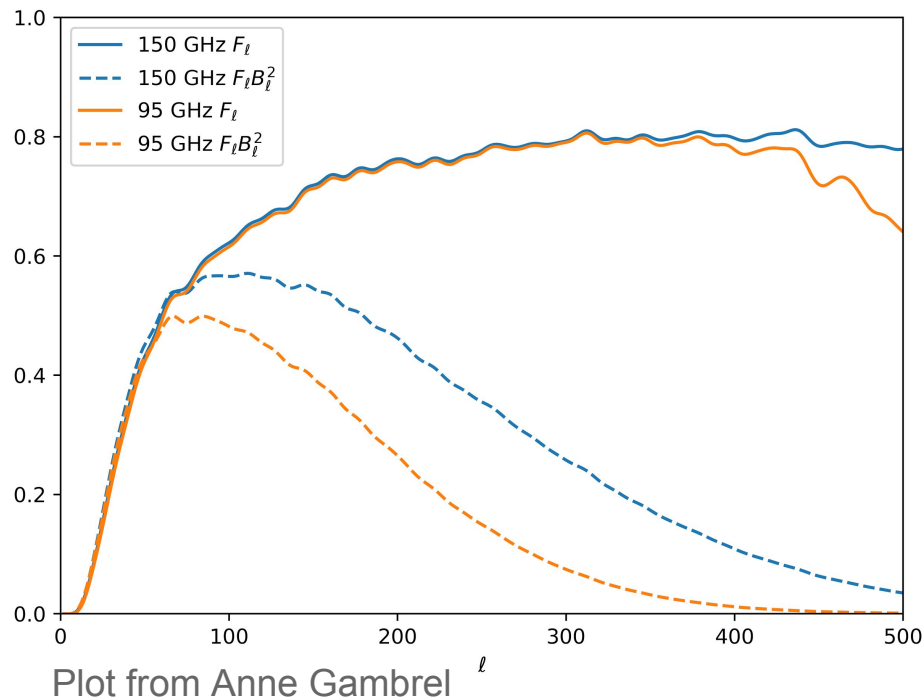


# Telemetry

- TDRSS
- LOS
- DGPS
- Iridium

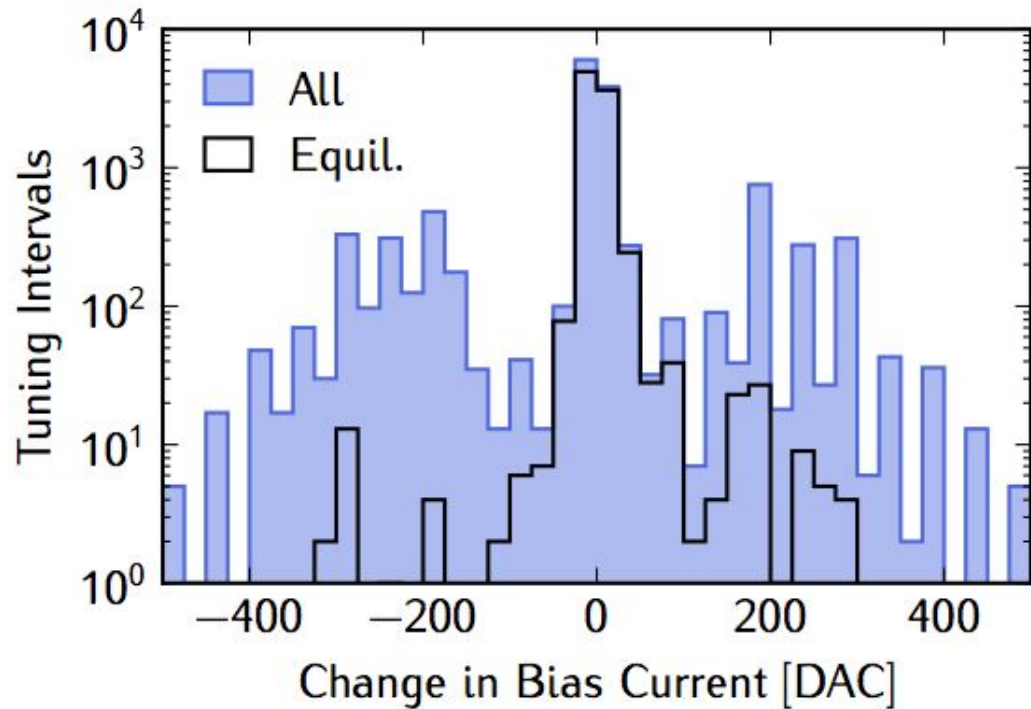


# Filter function



- Poly 5 per half scan

# Rebias amplitudes



# Filter stack

STAGE	TEMPERATURE	ELEMENT	CUTOFF [GHz]
Window	250 K	1/8" UHMWPE + AR	1500
		C15 shader	5200
		C30 shader	2300
VCS2	130 K	C15 shader ( $\times 2$ )	5200
		C30 shader ( $\times 2$ )	2300
VCS1	35 K	C15 shader	5200
		C30 shader ( $\times 2$ )	2300
		$12 \text{ cm}^{-1}$	360
Receiver	4 K	$10 \text{ cm}^{-1}$	290
		Nylon + AR	540
Receiver	2 K	$6 \text{ cm}^{-1}$ (150 GHz)	180
		$4 \text{ cm}^{-1}$ (94 GHz)	115



# Deprojection Equations

Param	Template
$\delta g$	$T_g(t) = g (\mathcal{B} \cdot \Theta) (\vec{p}(t))$
$\delta x$	$T_x(t) = g\sigma \left( -\frac{\cos \gamma}{\sin \theta} \frac{\partial}{\partial \phi} + \sin \gamma \frac{\partial}{\partial \theta} \right) \cdot (\mathcal{B} \cdot \Theta) (\vec{p}(t))$
$\delta y$	$T_y(t) = g\sigma \left( -\frac{\sin \gamma}{\sin \theta} \frac{\partial}{\partial \phi} - \cos \gamma \frac{\partial}{\partial \theta} \right) (\mathcal{B} \cdot \Theta) (\vec{p}(t))$
$\delta \sigma$	$T_\sigma(t) = g \left( \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial \theta^2} \right) (\mathcal{B} \cdot \Theta) (\vec{p}(t))$
$\delta p$	$T_p(t) = g \left[ \cos 2\gamma \left( \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial \theta^2} \right) + \sin 2\gamma \left( \frac{\cos \theta}{\sin^2 \theta} \frac{\partial}{\partial \phi} - \frac{2}{\sin \theta} \frac{\partial^2}{\partial \phi \partial \theta} \right) \right] (\mathcal{B} \cdot \Theta)$
$\delta c$	$T_c(t) = g \left[ \sin 2\gamma \left( \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} - \frac{\partial^2}{\partial \theta^2} \right) + \cos 2\gamma \left( -\frac{\cos \theta}{\sin^2 \theta} \frac{\partial}{\partial \phi} + \frac{2}{\sin \theta} \frac{\partial^2}{\partial \phi \partial \theta} \right) \right] (\mathcal{B} \cdot \Theta)$

# Recovery

- Preliminary recovery  
February 2015
- Full recovery  
November 2015
- Lead by BAS



# Atmosphere

