

B-MODE FROM SPACE WORKSHOP
SECOND MEETING AT THE UNIVERSITY OF CALIFORNIA, BERKELEY

4 Dec 2017

Foregrounds cleaning for LiteBIRD with
xForecast-multipatch and *SMICA*

complementary slides from the San Diego workshop:

https://www.dropbox.com/s/2hpof74eje9dkjg/foregrounds_workshop.pdf?dl=0



**Josquin Errard
Maude Le Jeune
Radek Stompor**

Conclusions / to-do items after Montreal meeting (Jan 2017)

- we show **consistency** between xForecast and SMICA on constant spectral indices and PySM simulations
- **spatial variability of dust is important to characterize, and high frequency channels are crucial**

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- improve marginalization over residuals
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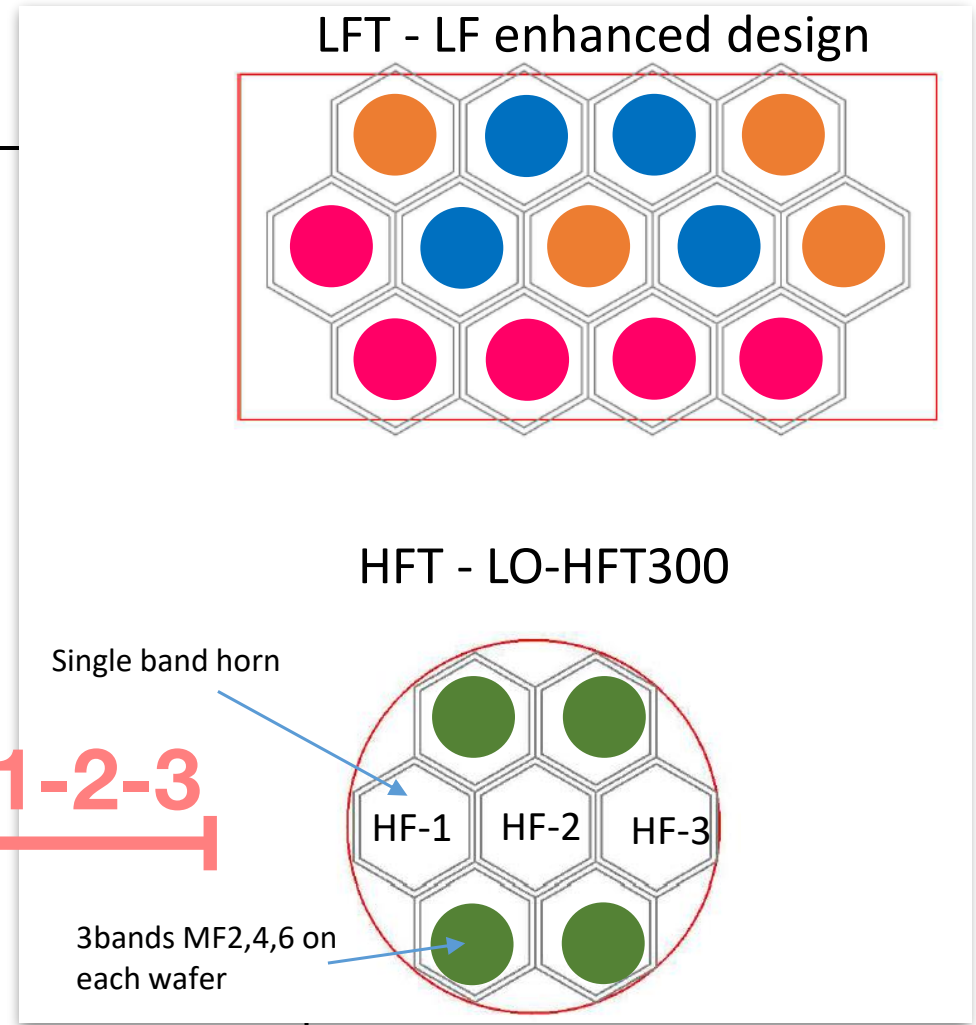
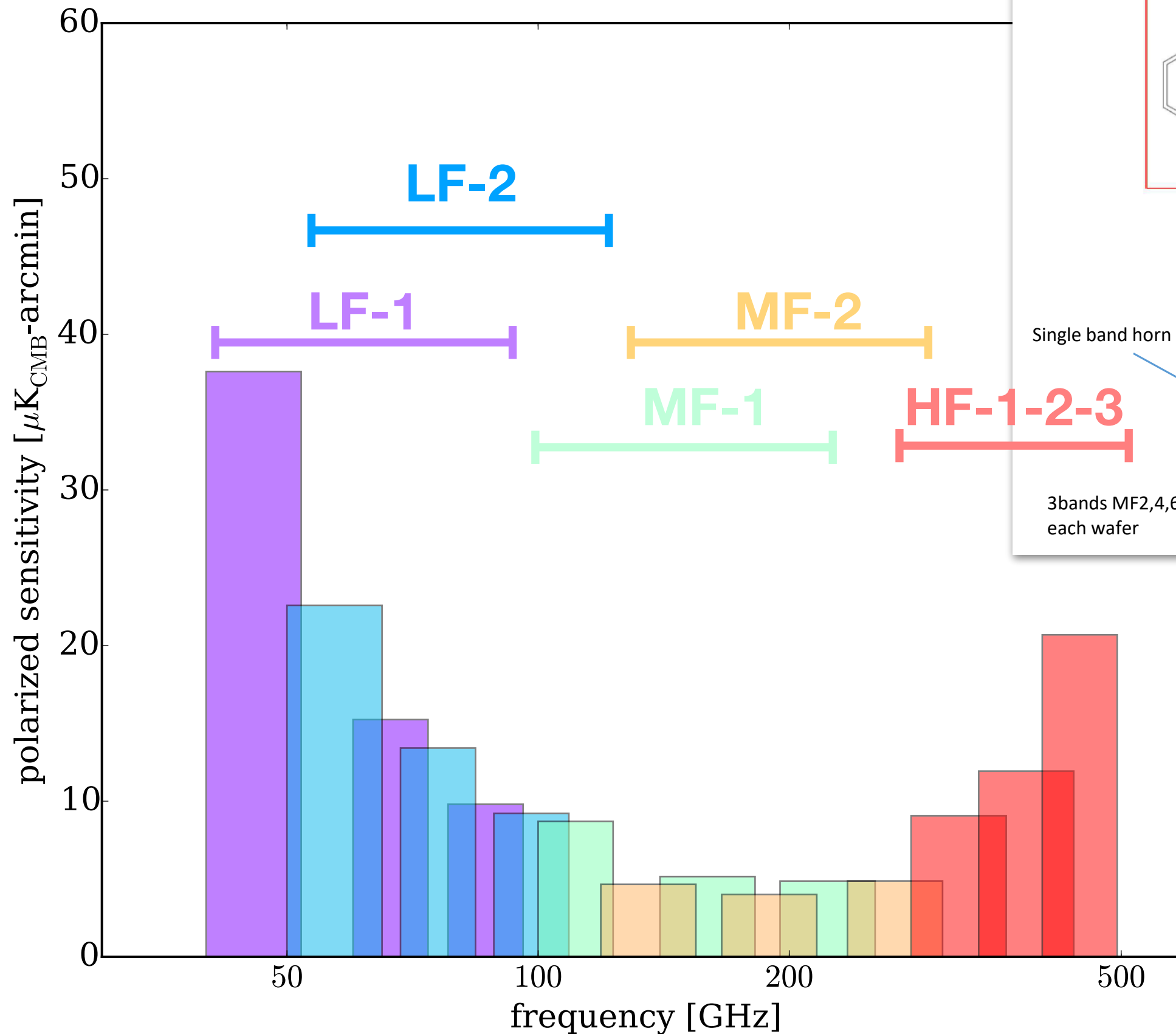
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TO DO:

- develop a multipatch approach for xForecast ✓
- explore the possibility of focal plane optimization ✓
- improve marginalization over residuals ✓
- continue comparison between the two approaches ✓

+ focal plane sensitivity has been updated

LiteBIRD assumed specifications



Method — xForecast

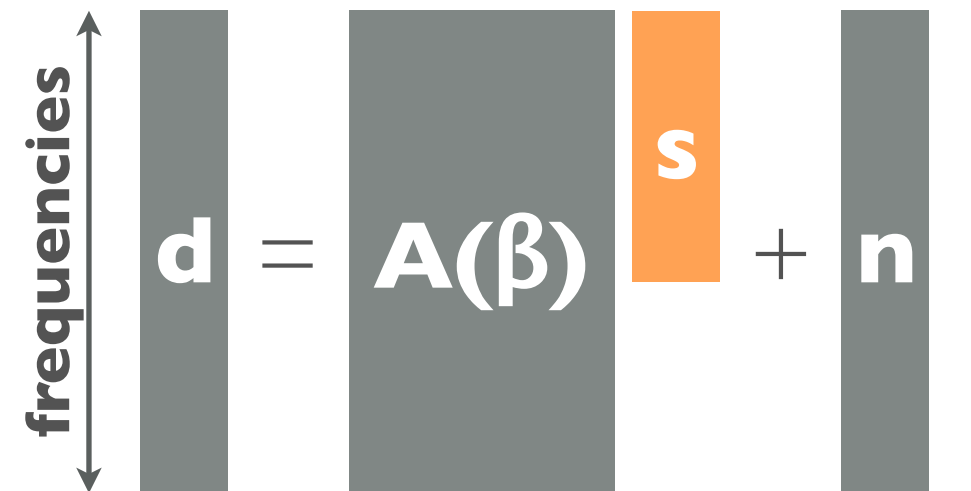
data modeling
for each sky pixel:

$$d_i(p) = A_{ij} s_j(p) + n_i(p)$$

The diagram illustrates the data modeling equation $d = A(\beta) \cdot s + n$. A vertical double-headed arrow on the left is labeled "frequencies". The equation is represented by vertical bars: a grey bar "d" equals a grey bar "A(β)" multiplied by an orange bar "s", plus a grey bar "n".

Method — xForecast

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for each sky pixel:

$$d_i(p) = A_{ij} s_j(p) + n_i(p)$$


I. estimation of the mixing matrix **A**

e.g. [Stompor et al. \(2009\)](#)

$$A_{\text{sync}}^{\text{raw}}(\nu, \nu_{\text{ref}}) \equiv \left(\frac{\nu}{\nu_{\text{ref}}} \right)^{\beta_s}$$

$$A_{\text{dust}}^{\text{raw}}(\nu, \nu_{\text{ref}}) \equiv \left(\frac{\nu}{\nu_{\text{ref}}} \right)^{\beta_d+1} \frac{e^{\frac{h\nu_{\text{ref}}}{kT_d}} - 1}{e^{\frac{h\nu}{kT_d}} - 1}$$

$$\mathbf{A} \equiv \mathbf{A}(\beta = \beta_d, \beta_s, \dots) \longrightarrow \max(\mathcal{L}(\beta))$$

**not perfect
recovery of input
spectral
parameters** ➤
**foregrounds
residuals**

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**not perfect
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2. solve for **s** [rather general to any comp sep method]

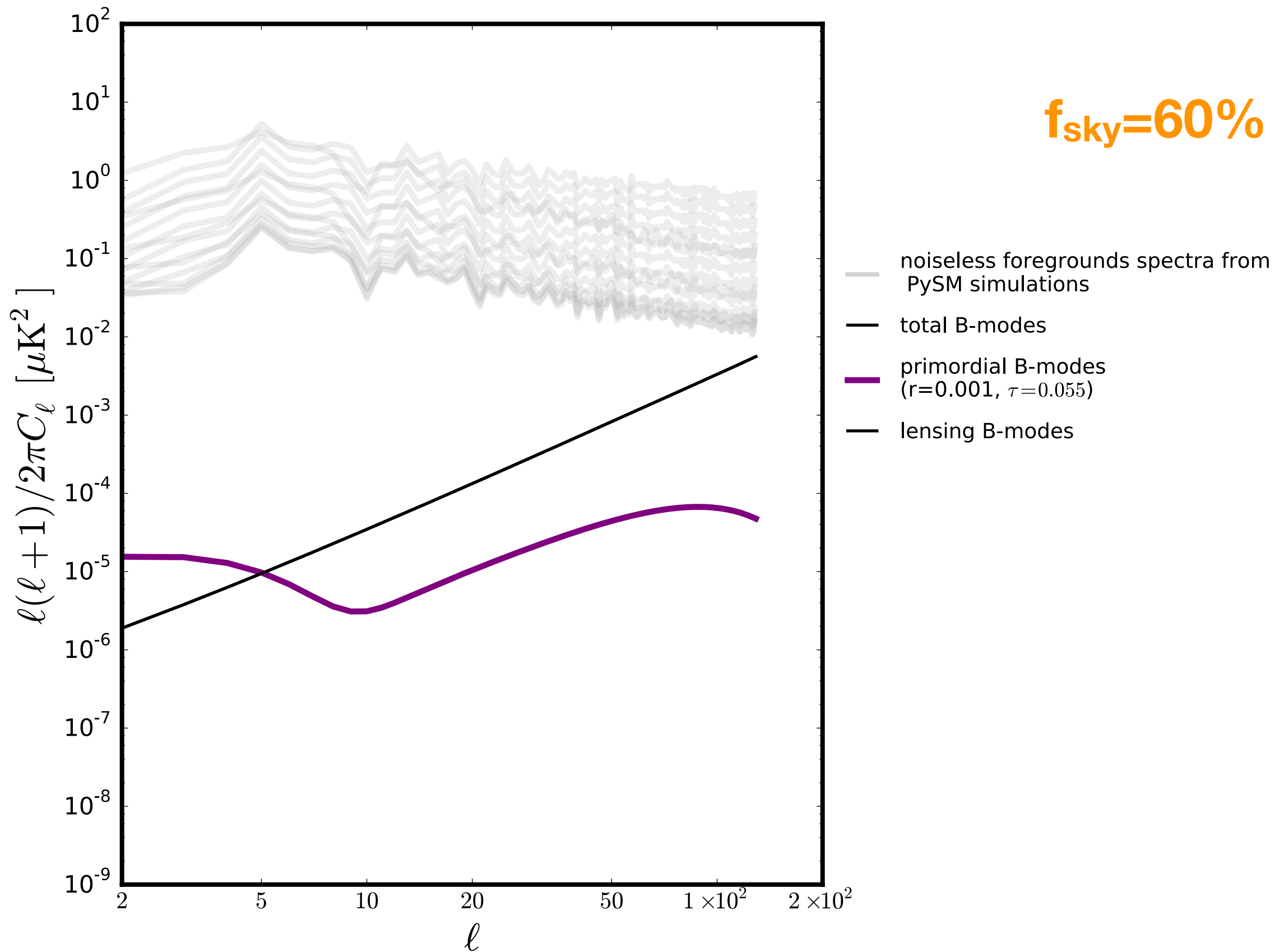
$$\mathbf{s} = (\mathbf{A}^T \mathbf{N}^{-1} \mathbf{A})^{-1} \mathbf{A}^T \mathbf{N}^{-1} \mathbf{d}$$

**linear combination
of various frequency
maps** ➤ **boosted
noise**

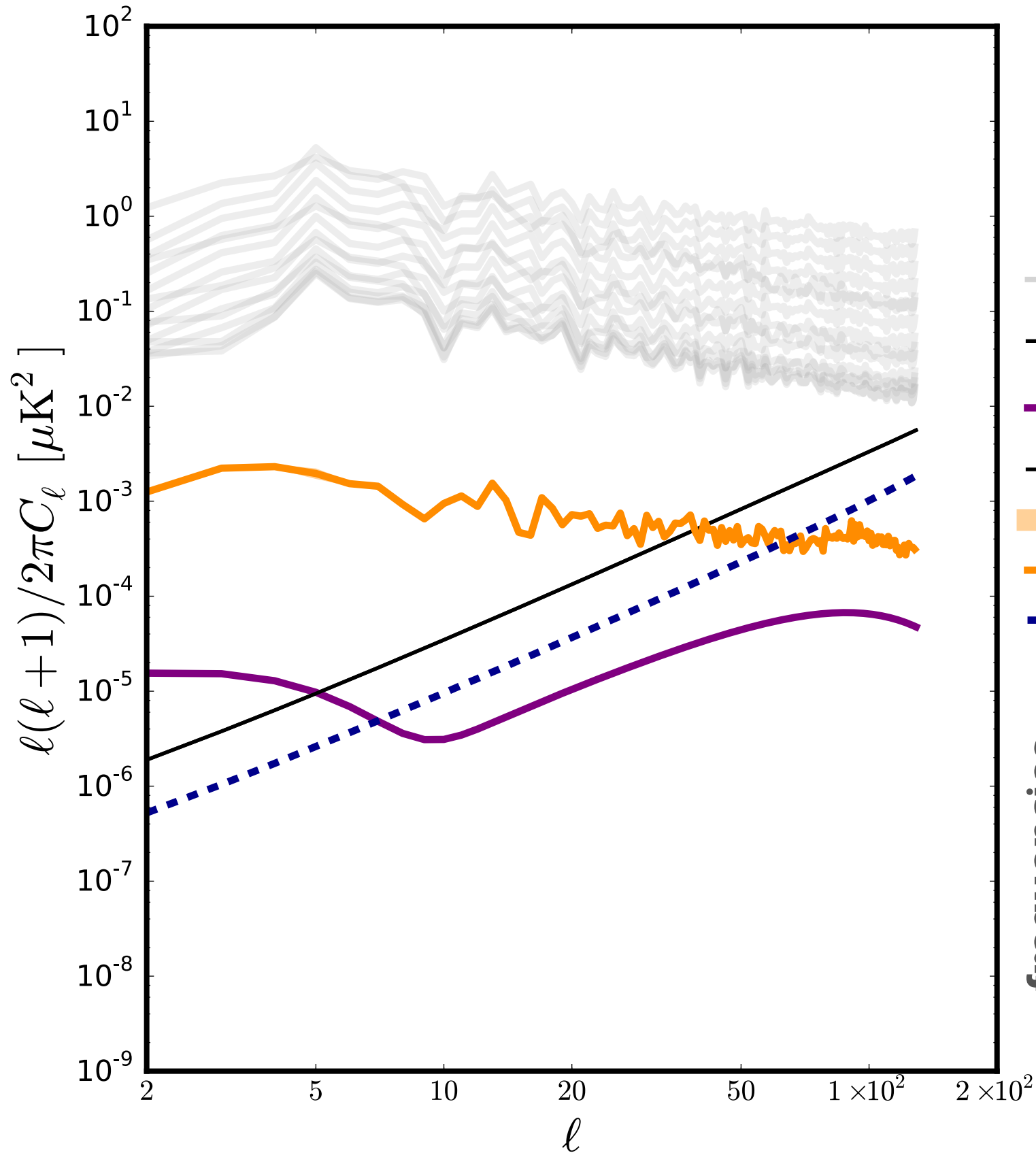
**xForecast results on PySM – a1d1f1s1 simulation
(nside=16 / 3.5deg spatial variations for spectral indices)**

[$r_{\text{sim}}=0$]

xForecast results on PySM – a1d1f1s1 simulation (nside=16 / 3.5deg spatial variations for spectral indices)



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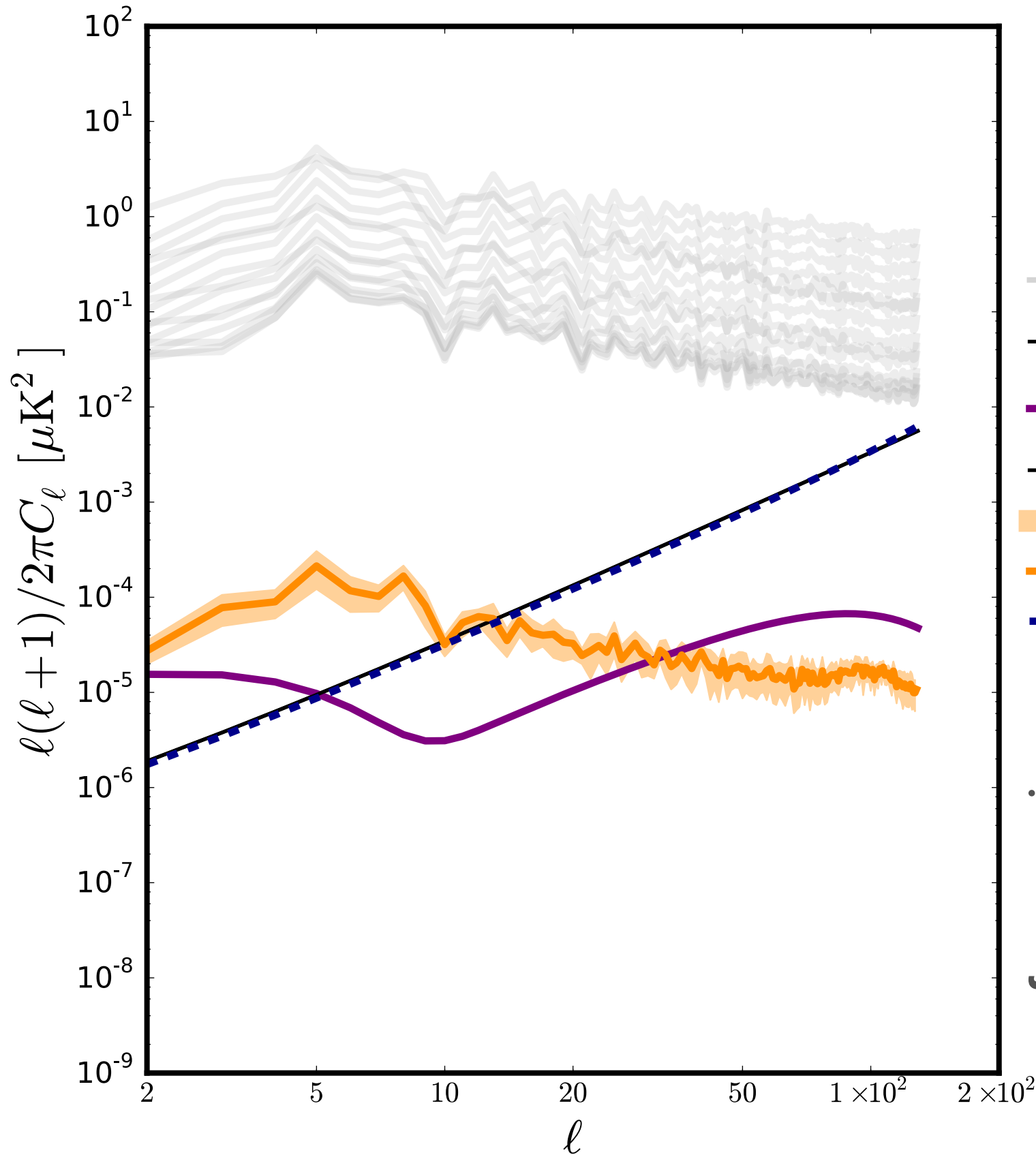


f_{sky}=60%

- noiseless foregrounds spectra from PySM simulations
- total B-modes
- primordial B-modes ($r=0.001, \tau=0.055$)
- lensing B-modes
- ▭ xF average residuals $\pm 2\sigma$
- xF sys+stat residuals
- - - N_ℓ

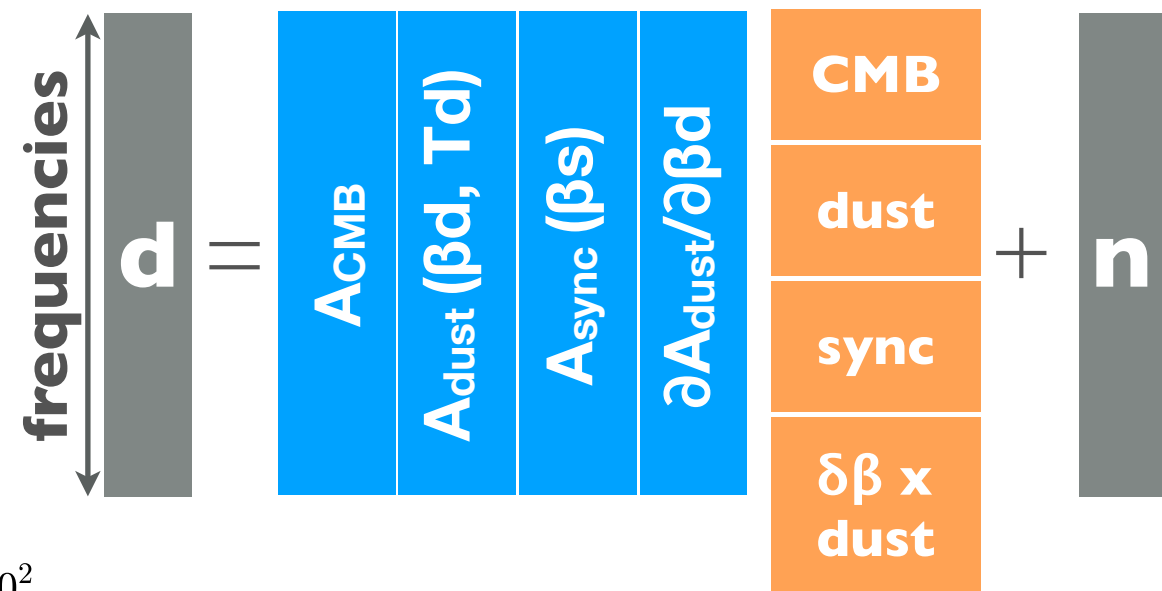


xForecast results on PySM – a1d1f1s1 simulation (nside=16 / 3.5deg spatial variations for spectral indices)

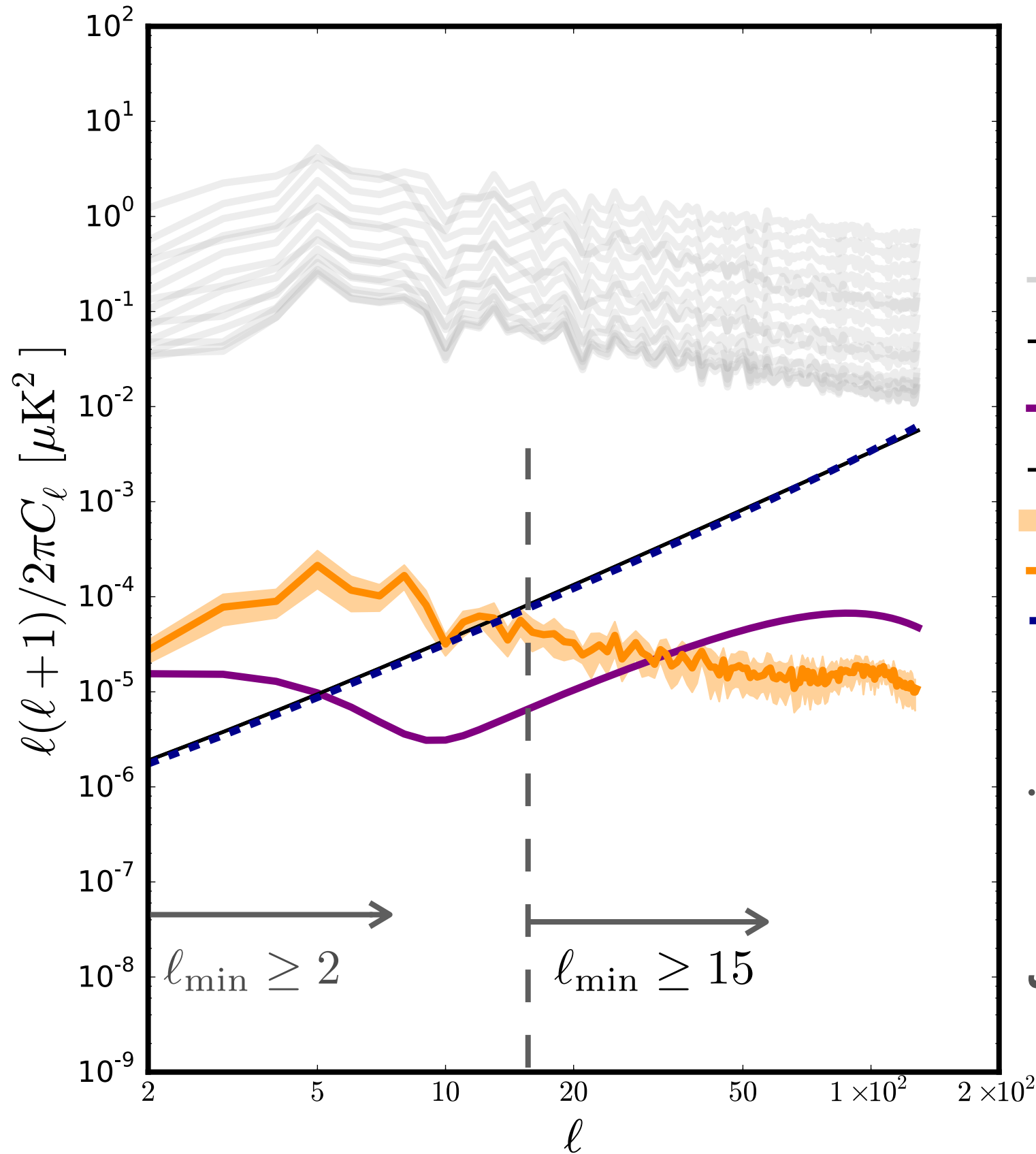


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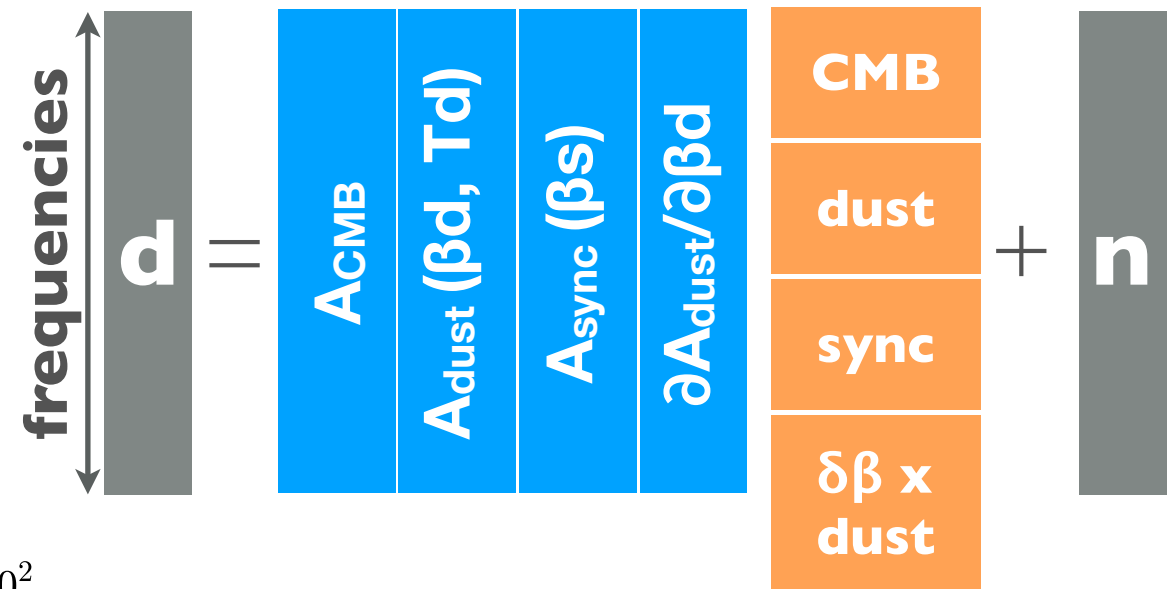


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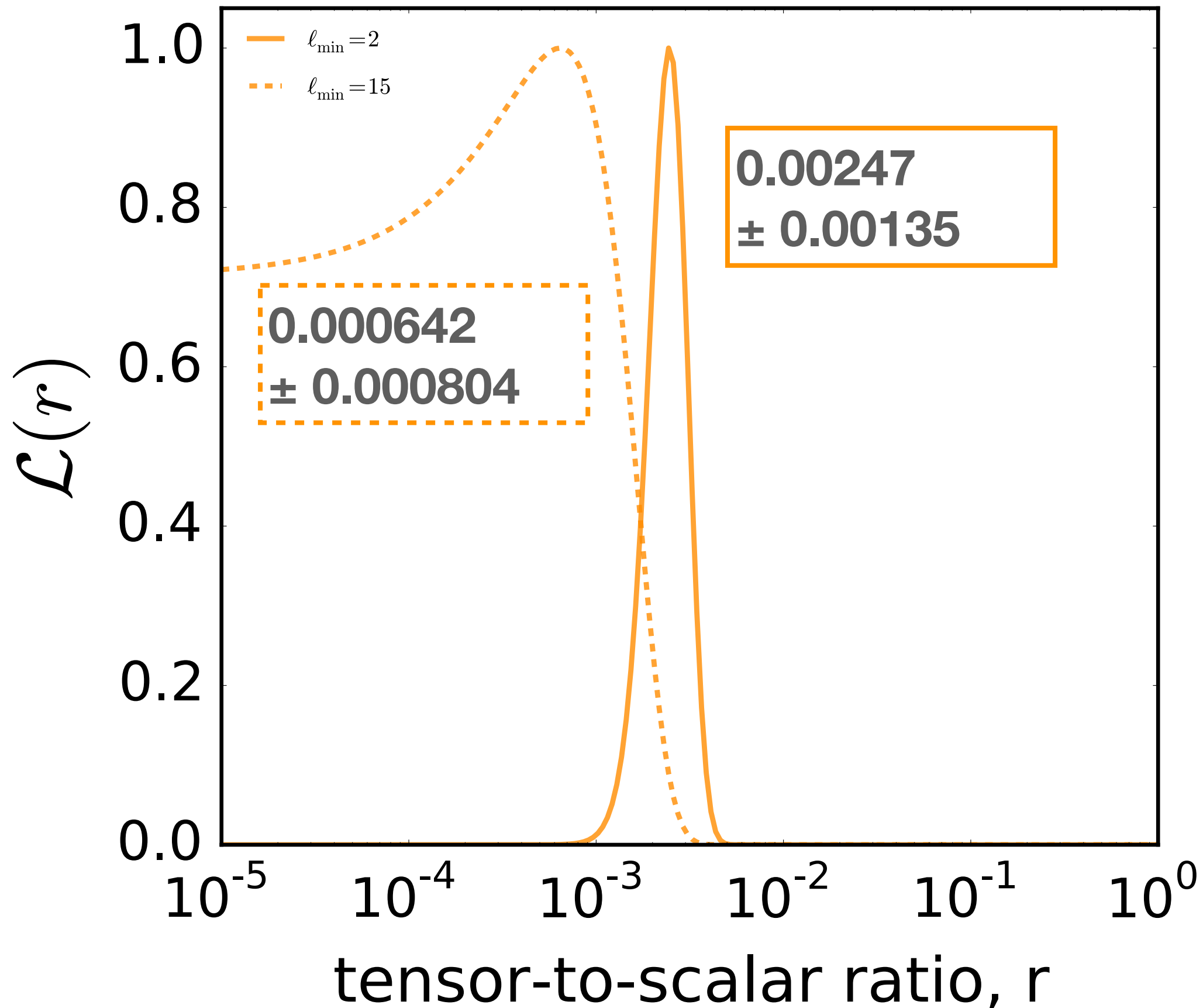


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xForecast results on PySM — a1d1f1s1 simulation (nside=16 / 3.5deg spatial variations for spectral indices)



Method – SMICA

Cardoso et al, A&A, 2007

sky simulations + noise

second order statistics

$$\hat{R}_q^{BB} = \sum_m [a_{lm}^B] [a_{lm}^B]^T$$

minimization of

$$\|\hat{\mathbf{R}} - \mathbf{R}\|$$

modeling of the data covariance:

$$R_q = AP_qA^T + N_q$$

e.g. $R_q^{BB} = aa^{cmb^T} (r \cdot c_q^{prim} + c_q^{lensed}) + A^{FG^T} P_q^{FG} A^{FG^T} + diag(\sigma_n^2)$

fit for r , and $\sigma(r)$
estimated with
Fisher

weights

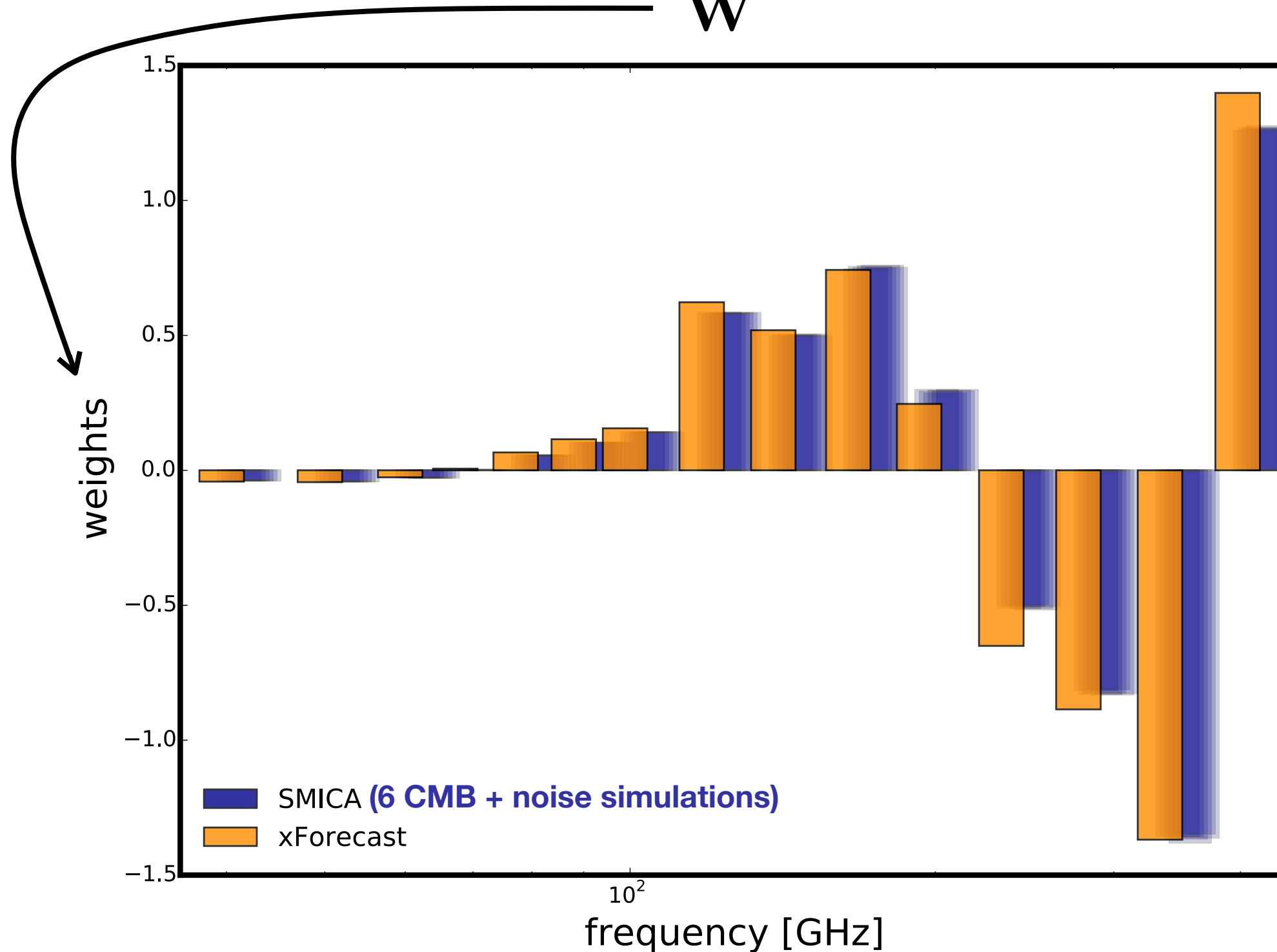
$$W = A^T N^{-1} [A^T N^{-1} A]^{-1}$$

SMICA results on PySM – a1d1f1s1 simulation (nside=16 / 3.5deg spatial variations for spectral indices)

$$\mathbf{s} = \underbrace{(\mathbf{A}^T \mathbf{N}^{-1} \mathbf{A})^{-1} \mathbf{A}^T \mathbf{N}^{-1}}_{\mathbf{W}} \mathbf{d}$$

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SMICA results on PySM – a1d1f1s1 simulation (nside=16 / 3.5deg spatial variations for spectral indices)

xForecast

$$l_{\min} \geq 2$$

0.00247
± 0.00135
(Hessian: ± 0.000507)

$$l_{\min} \geq 15$$

0.000642
± 0.000804
(Hessian: ± 0.000792)

SMICA
(Hessian error bars)

0.00222
± 0.000673

0.000565
± 0.000728

since Montreal:

- simplification of the foregrounds (spatial variation on nside=16): $\sigma(r)=0.001 \rightarrow \sigma(r)=0.0009$
- new instrumental configuration: $\sigma(r)=0.0009 \rightarrow \sigma(r)=0.0007$



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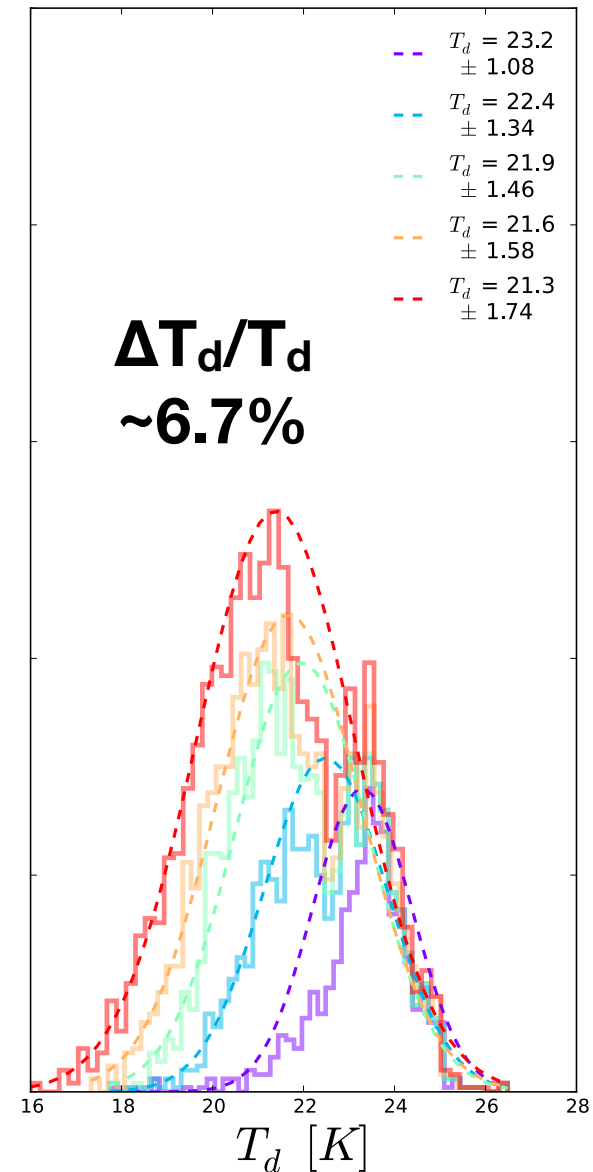
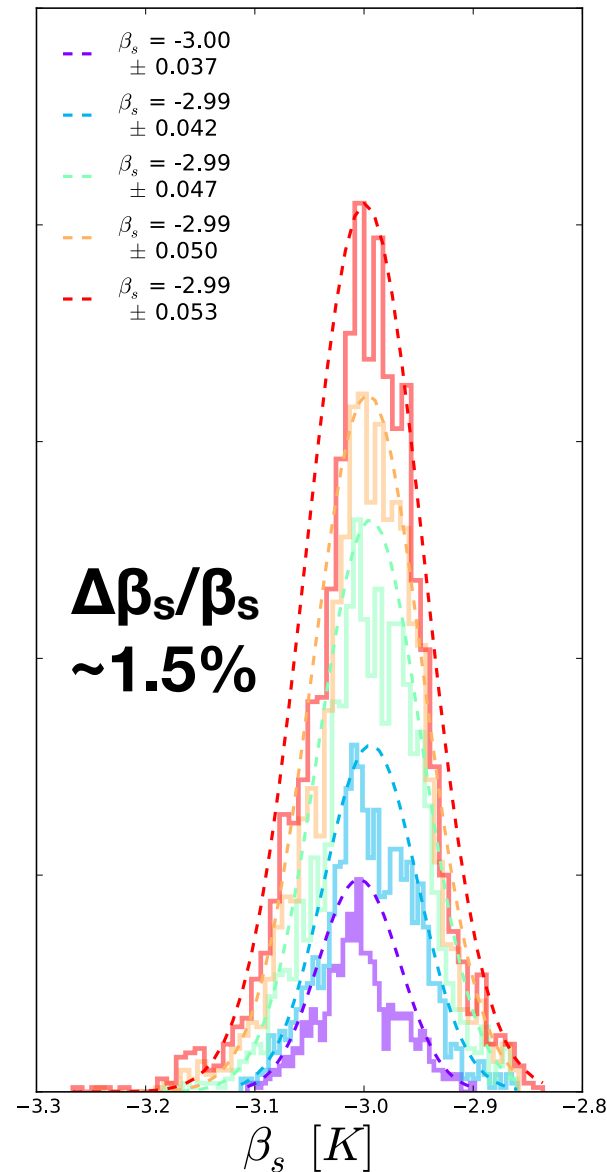
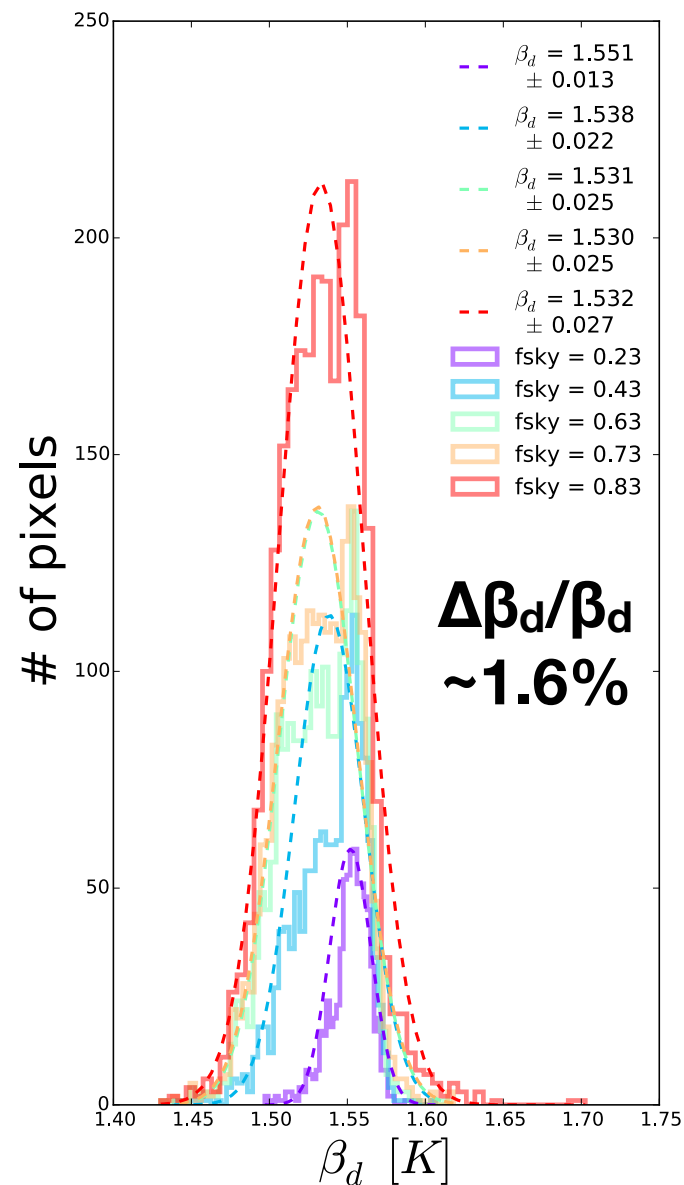
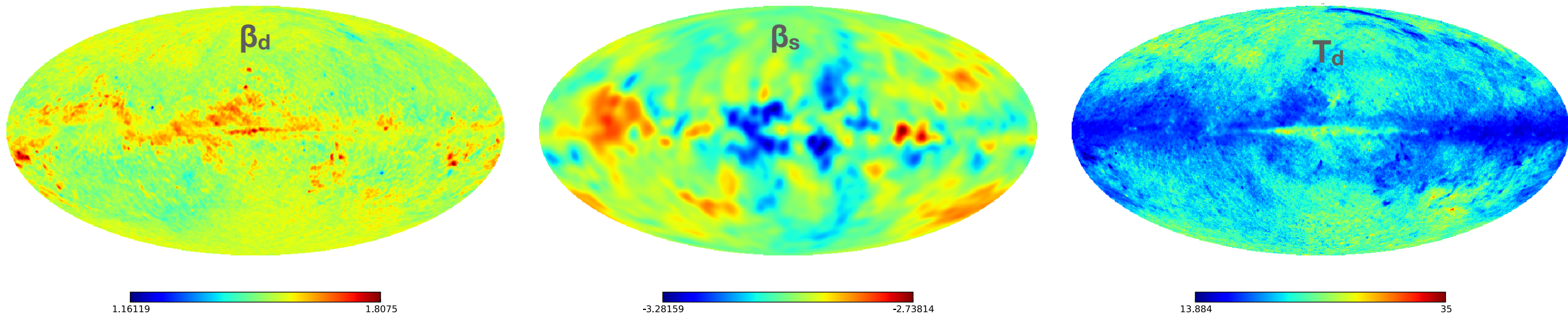
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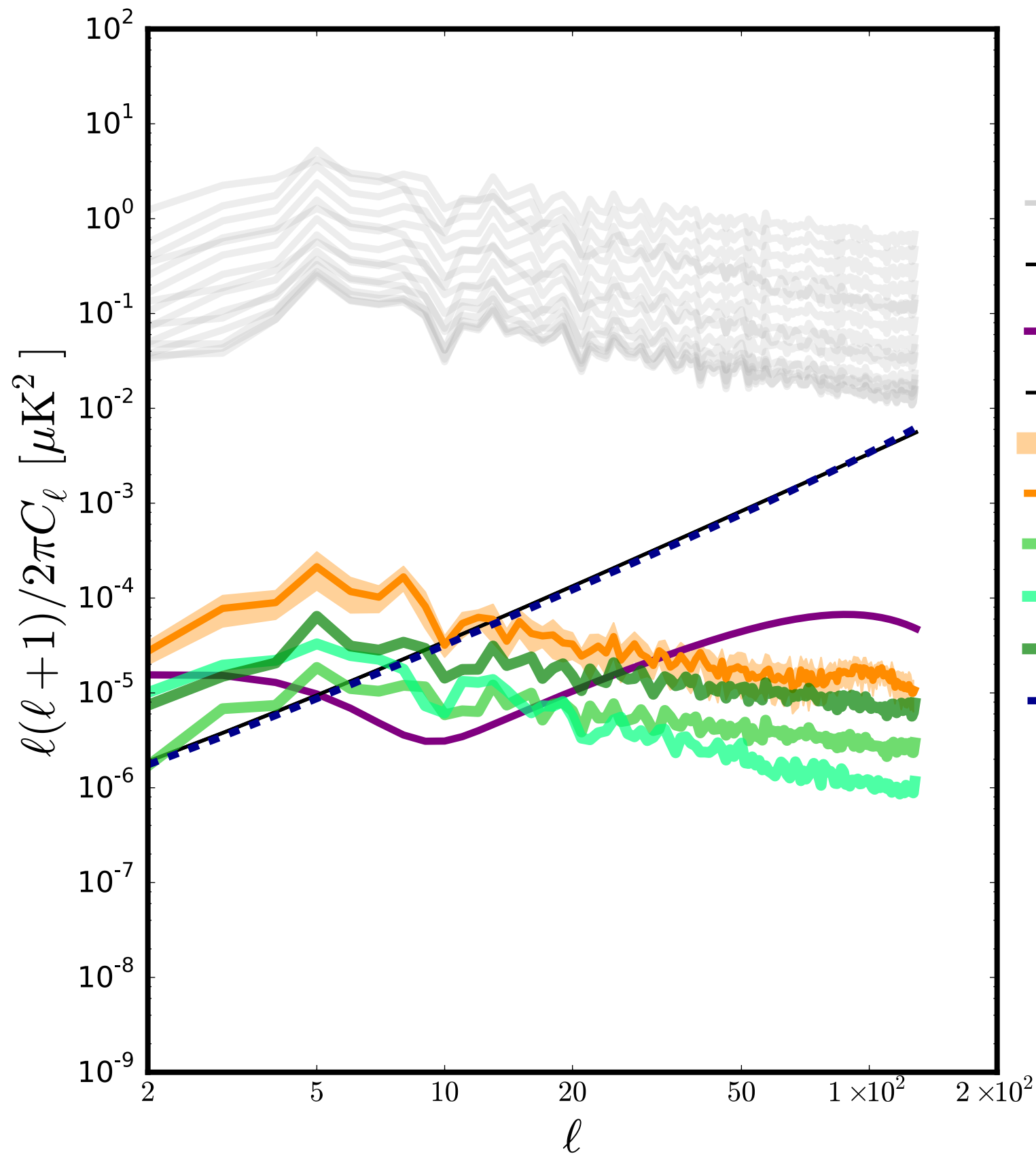
bias $\sim O(0.002)$ on r on the
largest angular scales:

it is crucial to take into
account the **spatial variations**
of spectral indices in the
analysis

spatial variations of the spectral indices in the PySM templates



spatial variations of the spectral indices in the PySM templates



$f_{\text{sky}}=60\%$

- noiseless foregrounds spectra from PySM simulations
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- lensing B-modes
- xF average residuals $\pm 2-\sigma$
- xF sys+stat residuals
- sys. res. from β_d spat. var.
- sys. res. from β_s spat. var.
- sys. res. from T_d spat. var.
- N_ℓ

$$s^{\text{est.}} \equiv \mathbf{W} d^{\text{in}}$$

$$\Rightarrow \text{residuals} \equiv s^{\text{est.}} - s^{\text{in}}$$

$$\simeq \delta\beta \left. \frac{\partial \mathbf{W}}{\partial \beta} \right|_{\beta^{\text{true}}} d^{\text{in}}$$

we should look for a balance between statistical and systematic errors

STATISTICAL error
bars on spectral
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SYSTEMATIC error
bars on spectral
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$$\Sigma \equiv \begin{bmatrix} \sigma(\beta_d)^2 & \sigma(\beta_d)\sigma(\beta_s) & \sigma(\beta_d)\sigma(T_d) \\ \star & \sigma(\beta_s)^2 & \sigma(\beta_s)\sigma(T_d) \\ \star & \star & \sigma(T_d)^2 \end{bmatrix}$$

STATISTICAL error bars on spectral parameters

- better signal-to-noise (instrumental sensitivity, etc.)
- few degrees of freedom
- broad frequency range
- large sky area (more pixels!)

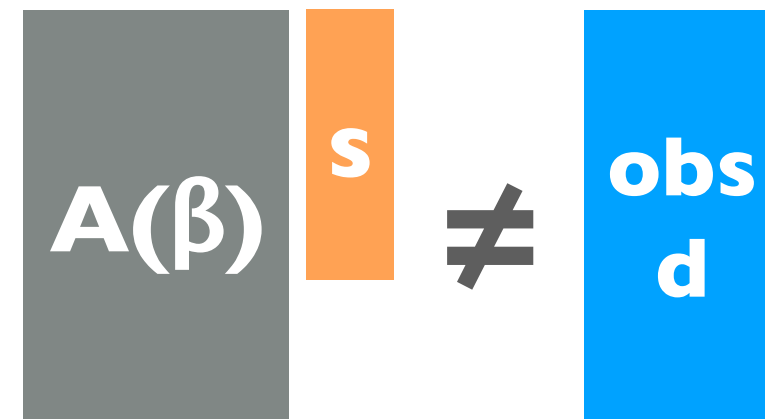
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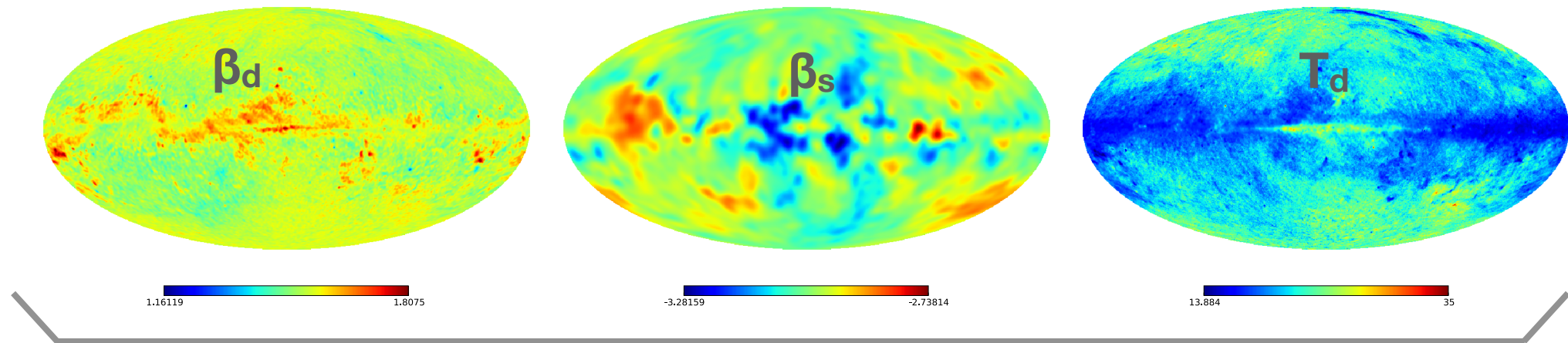


SYSTEMATIC error bars on spectral parameters

- more internal degrees of freedom (free spectral parameters, sky templates, etc.)
- reduced frequency range
- small sky area (less complexity!)

Method – multipatch

simulation



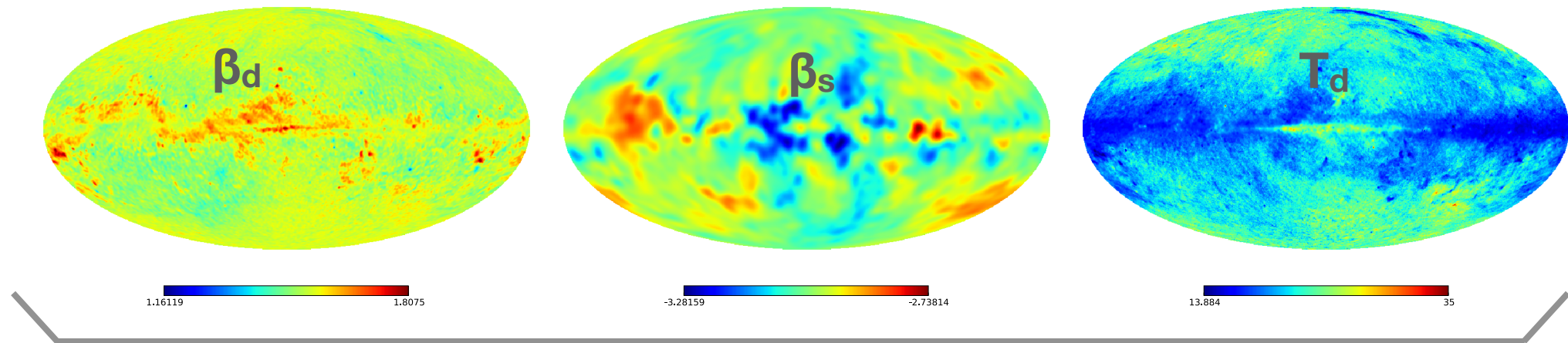
degrading/smoothing β maps down to $n_{\text{side}}=2 / 4 / 8 / 16$

upgrading β maps to $n_{\text{side}}=32$

simulate frequency maps + **CMB** + noise

Method – multipatch

simulation



degrading/smoothing β maps down to $n_{\text{side}} = 2 / 4 / 8 / 16$

upgrading β maps to $n_{\text{side}} = 32$

simulate frequency maps + **CMB + noise**

cleaning

fit for $\{\beta\}$ in each $n_{\text{side}} = 2 / 4 / 8 / 16$ pixels, matching the input simulation

estimate foregrounds residuals and noise by combining contribution from each pixels

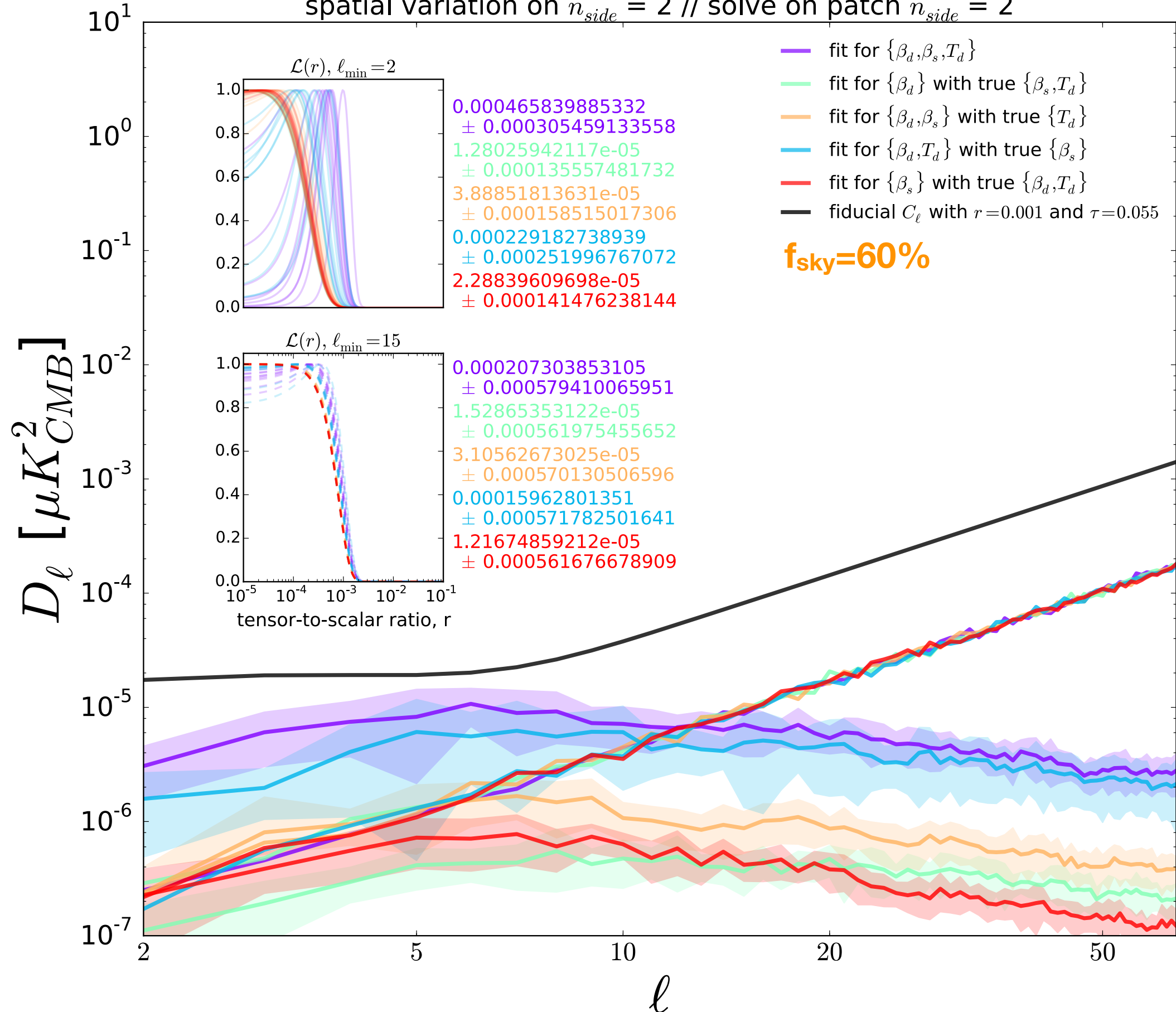
power spectrum estimation and likelihood on r

10 sims

variations of $\{\beta_d, \beta_s, T_d\}$ on this healpix resolution

we perform component separation independently on this healpix resolution

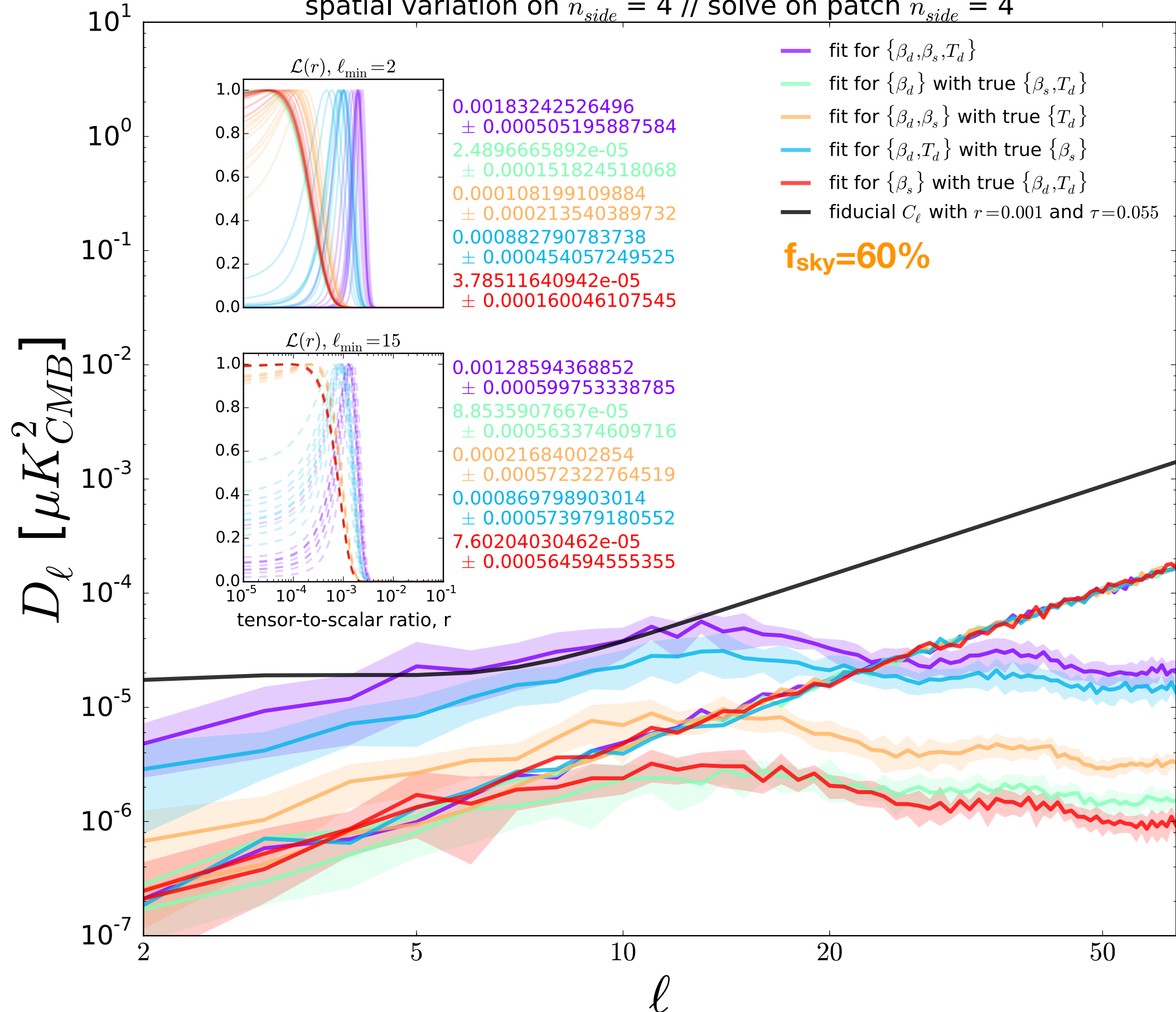
spatial variation on $n_{side} = 2$ // solve on patch $n_{side} = 2$



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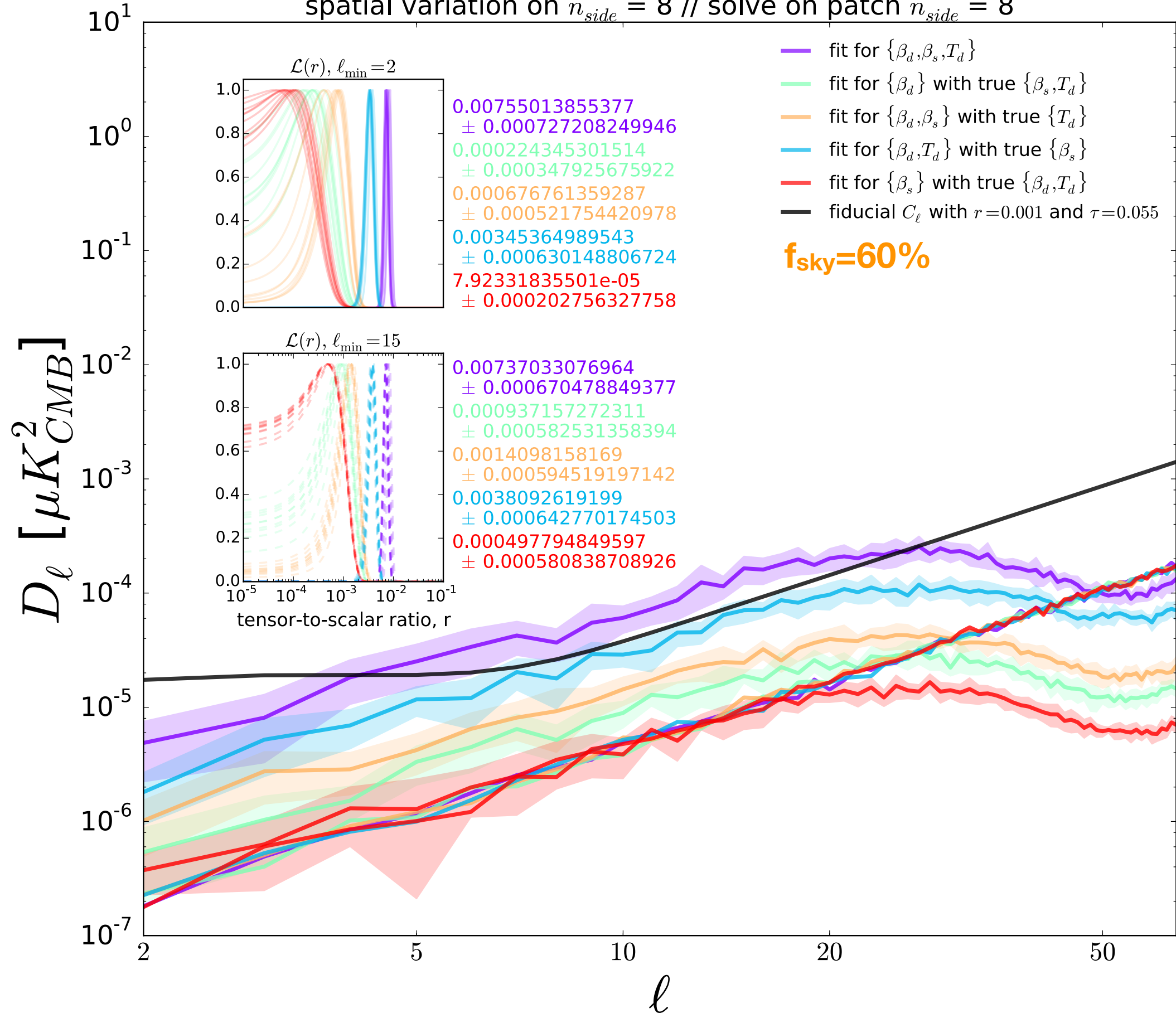
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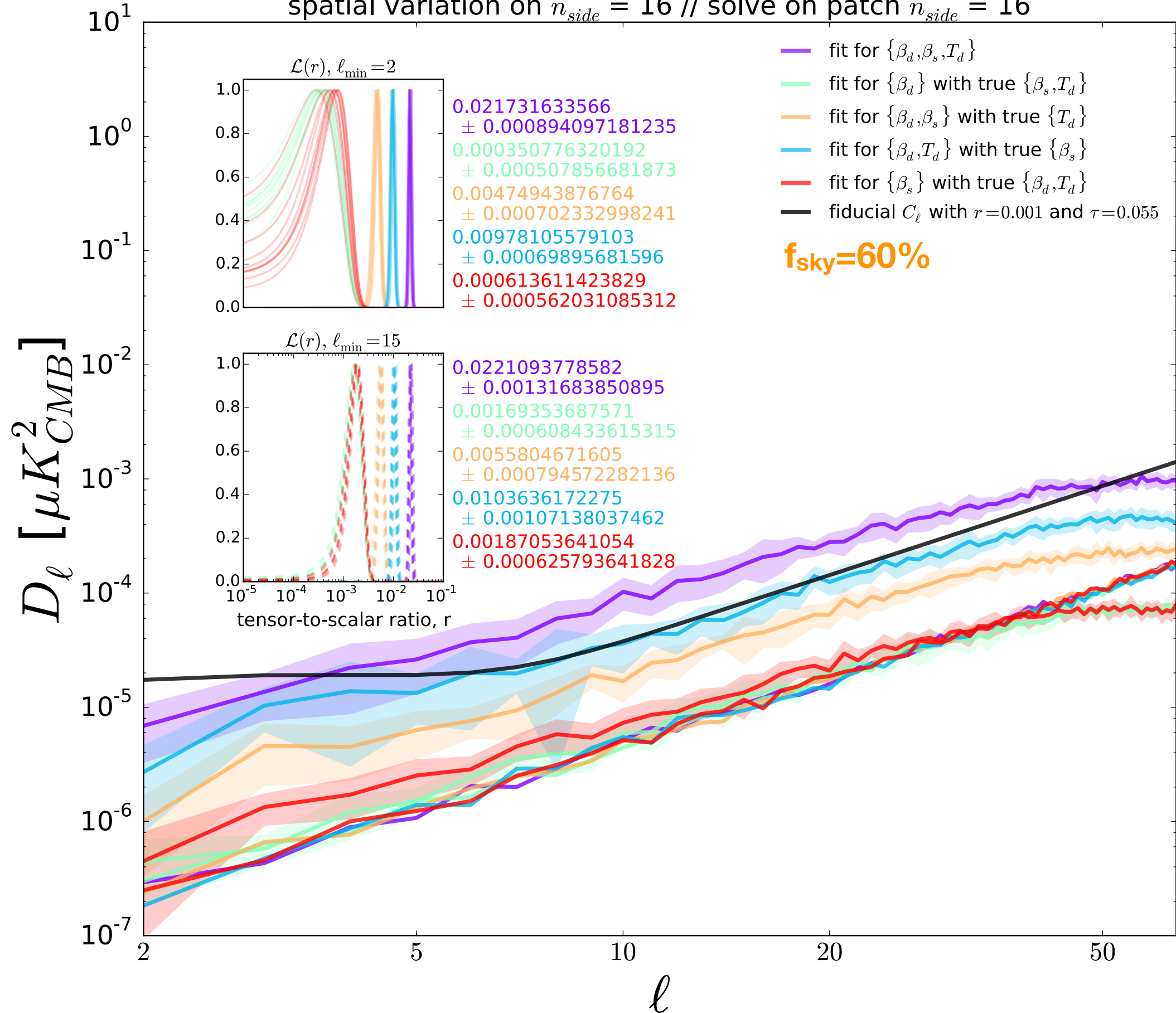
spatial variation on $n_{side} = 8$ // solve on patch $n_{side} = 8$



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spatial variation on $n_{side} = 16$ // solve on patch $n_{side} = 16$



Results — multipatch on nside 2 → 16

 = $r_{\text{bias}} < \sigma(r) < 0.001$

$l_{\text{min}} \geq 2$

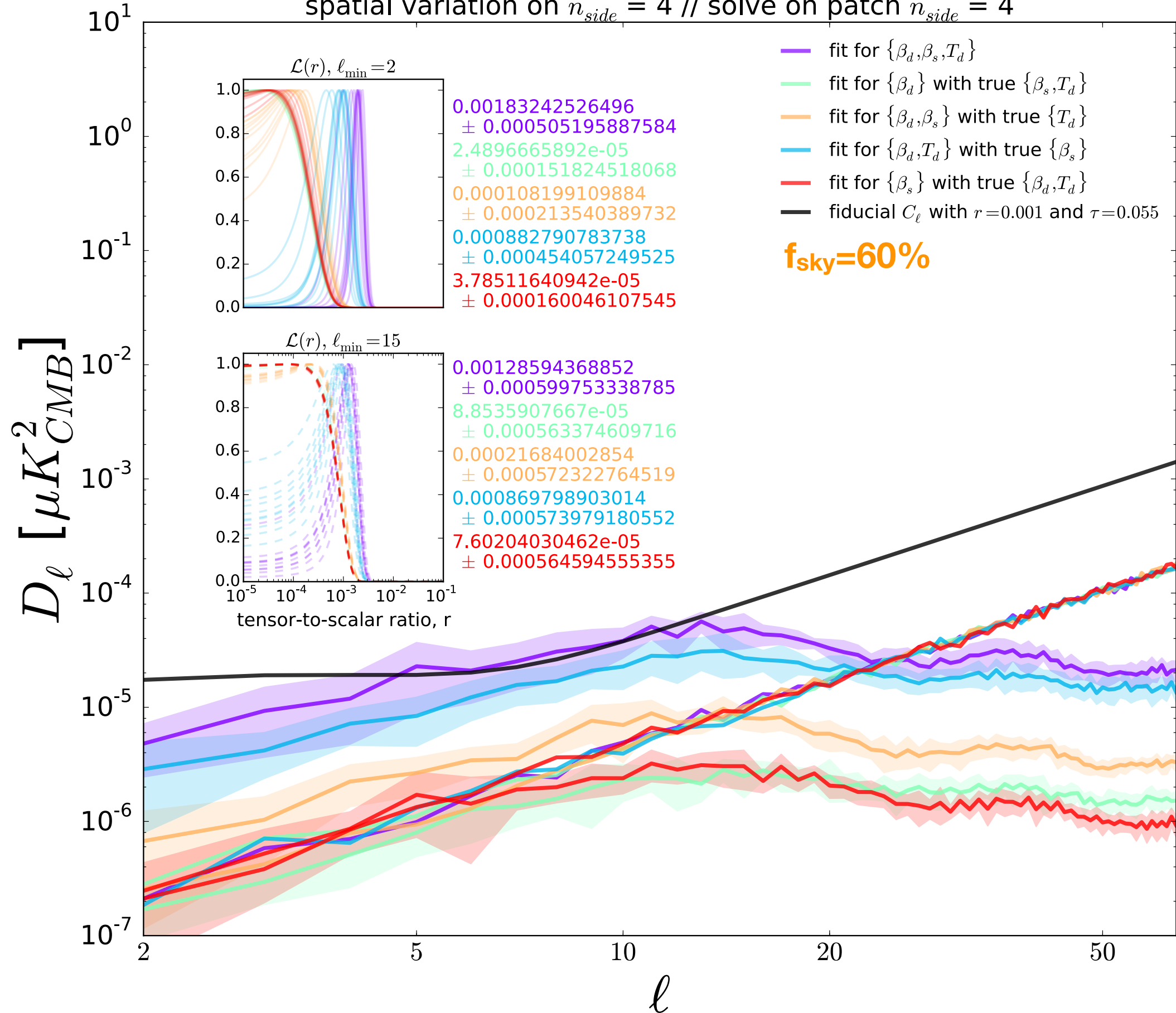
	fit for {Bd} true {Bs,Td}	fit for {Bd,Bs} true {Td}	fit for {Bd,Bs,Td}	fit for {Bd,Td} true {Bs}	fit for {Bs} true {Bd,Td}
nside = 2 (sim and cleaning)	1.28e-05 ± 0.000136	3.89e-05 ± 0.000159	0.000466 ± 0.000305	0.000229 ± 0.000252	2.29e-05 ± 0.000141
nside = 4 (sim and cleaning)	2.49e-05 ± 0.000152	0.000108 ± 0.000214	0.00183 ± 0.000505	0.000883 ± 0.000454	3.79e-05 ± 0.000160
nside = 8 (sim and cleaning)	0.000224 ± 0.000348	0.000677 ± 0.000522	0.00755 ± 0.000727	0.00345 ± 0.000630	7.92e-05 ± 0.000203
nside = 16 (sim and cleaning)	0.000351 ± 0.000508	0.00475 ± 0.000702	0.0217 ± 0.000894	0.00978 ± 0.000699	0.000614 ± 0.000562

is it possible to **reduce**
the bias on r by **modeling**
the foregrounds residuals
and marginalizing over
them?

variations of $\{\beta_d, \beta_s, T_d\}$ on this healpix resolution

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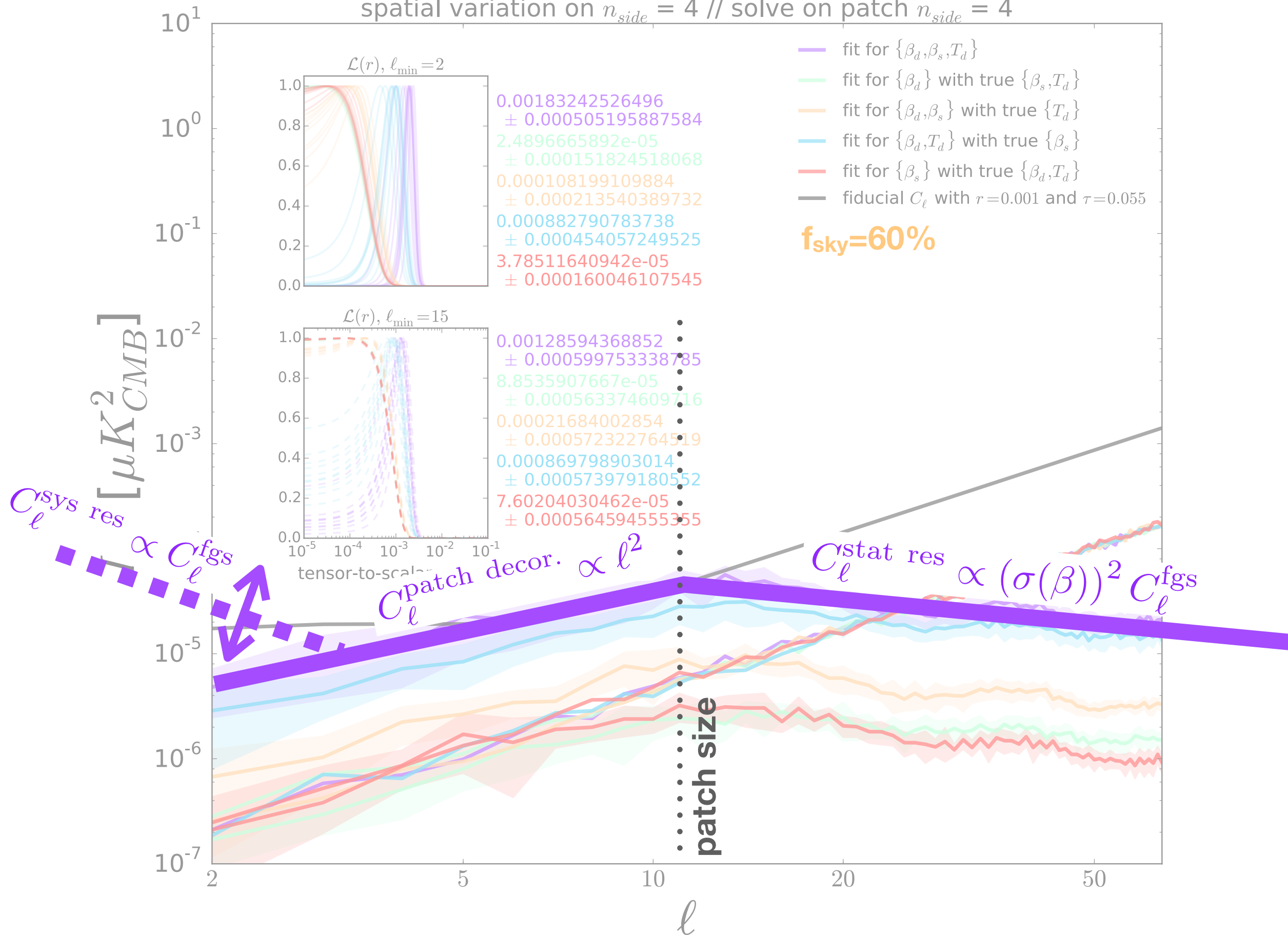
spatial variation on $n_{side} = 4$ // solve on patch $n_{side} = 4$



variations of $\{\beta_d, \beta_s, T_d\}$ on this healpix resolution

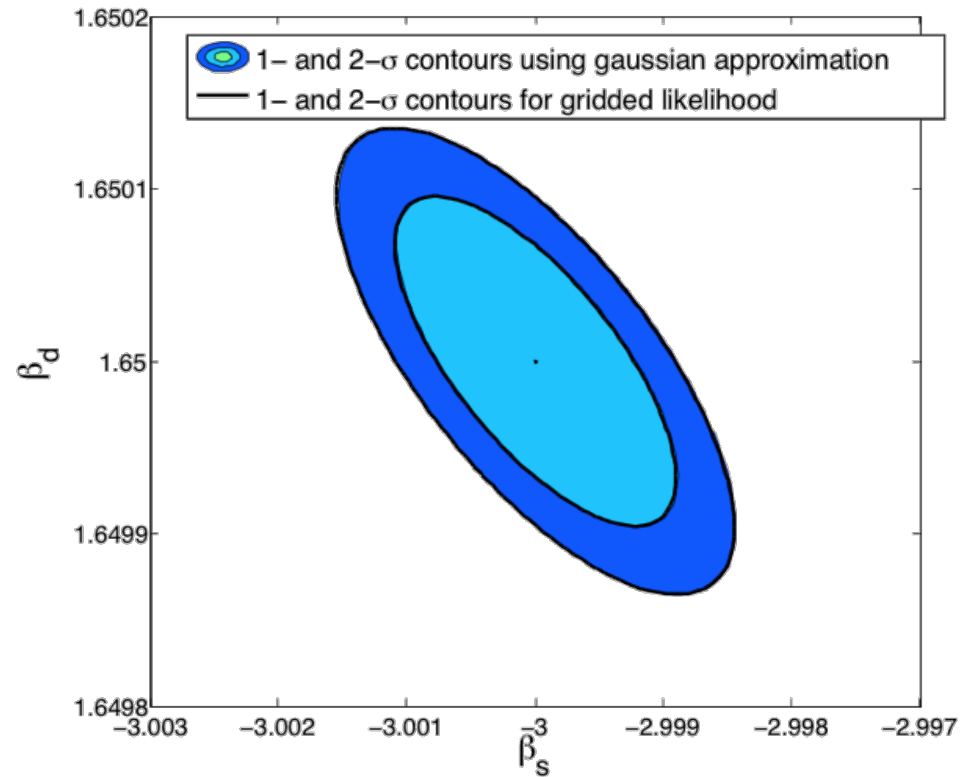
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Yet, we can semi-analytically estimate what are the statistical foreground residuals

Statistical error bars on spectral parameters:



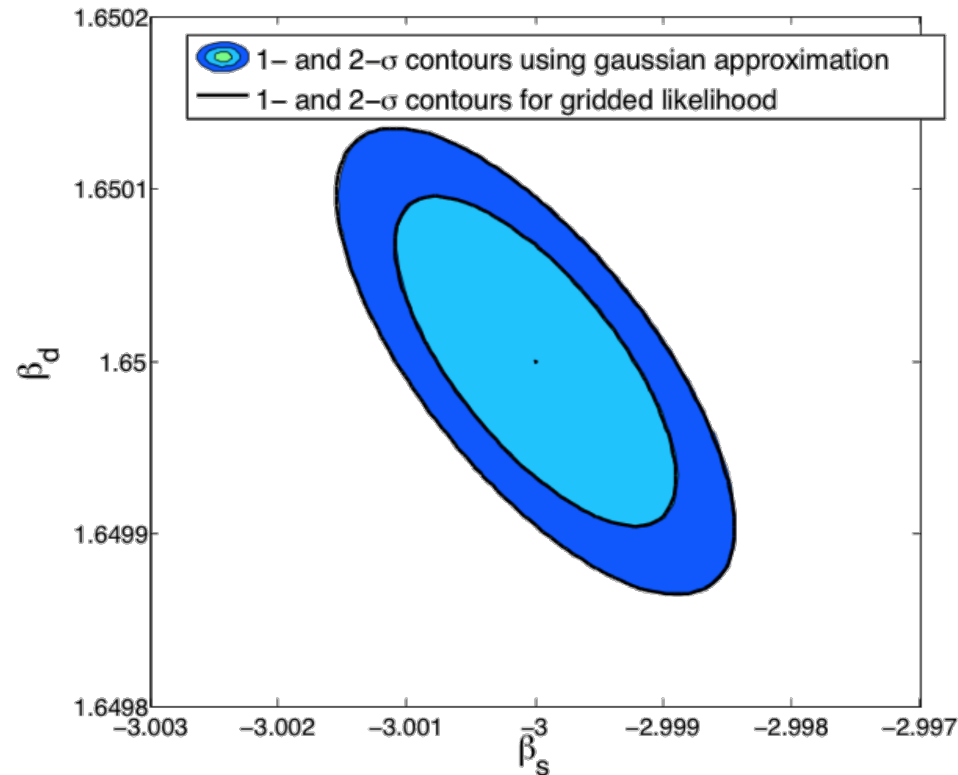
$$-2 \ln \mathcal{L}_{spec}(\boldsymbol{\beta}) = \text{CONST} - (\mathbf{A}^t \mathbf{N}^{-1} \mathbf{d})^t (\mathbf{A}^t \mathbf{N}^{-1} \mathbf{A})^{-1} (\mathbf{A}^t \mathbf{N}^{-1} \mathbf{d})$$

Errard, Stivoli and Stompor (PRD, 2011)

$$\boldsymbol{\Sigma}^{-1} \approx - \left\langle \frac{\partial^2 \mathcal{L}}{\partial \beta \partial \beta'} \right\rangle_{\text{noise} \mid \text{true } \beta}$$

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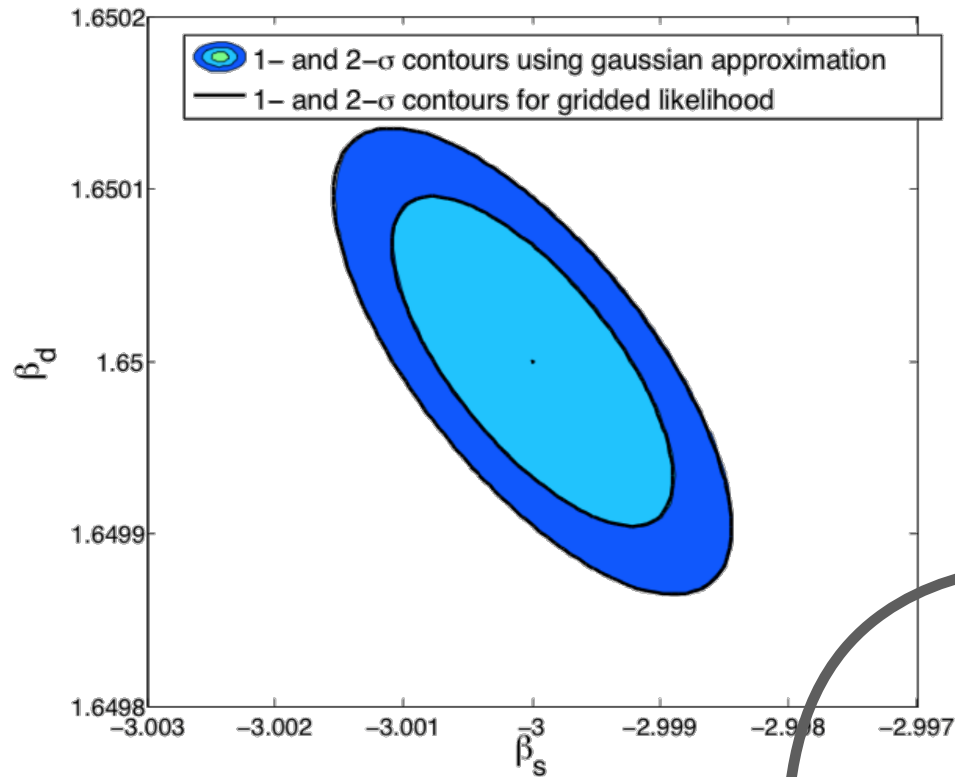
$$\boldsymbol{\Sigma}^{-1} \simeq - \left\langle \frac{\partial^2 \mathcal{L}}{\partial \beta \partial \beta'} \right\rangle_{\text{noise} \mid \text{true } \beta}$$

Synchrotron and dust templates

→ estimated using the **most extreme frequency channels** of LiteBIRD (scaling them to 150GHz using the estimated spectral indices in each pixels)

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Amplitude of statistical foreground residuals:

$$C_{\ell}^{\text{fg res}} \equiv \sum_{k, k'} \sum_{j, j'} \Sigma_{kk'} \kappa_{kk'}^{jj'} C_{\ell}^{jj'}$$

Stivoli, Grain, Leach, Tristram, Baccigalupi, Stompor (MNRAS, 2010)

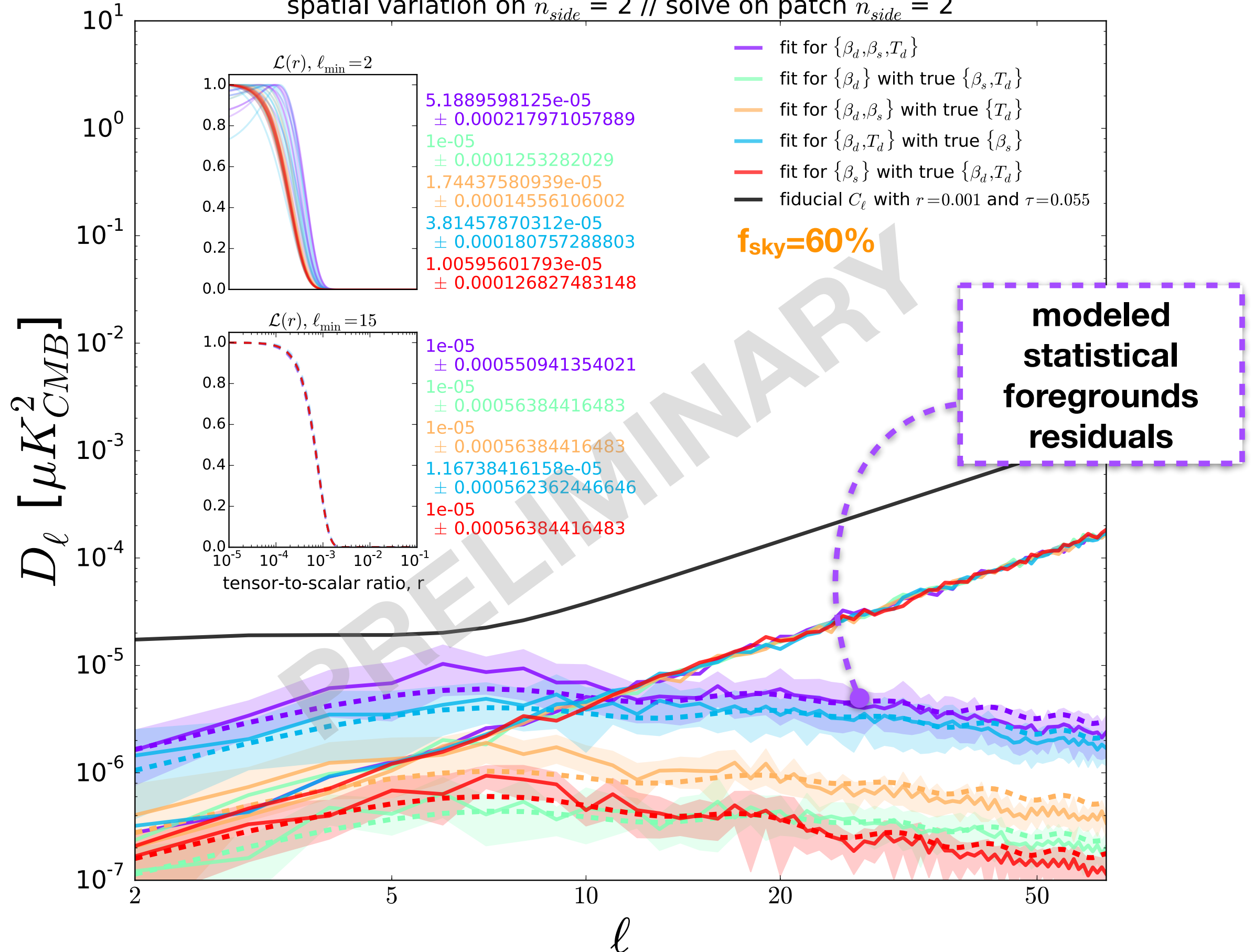
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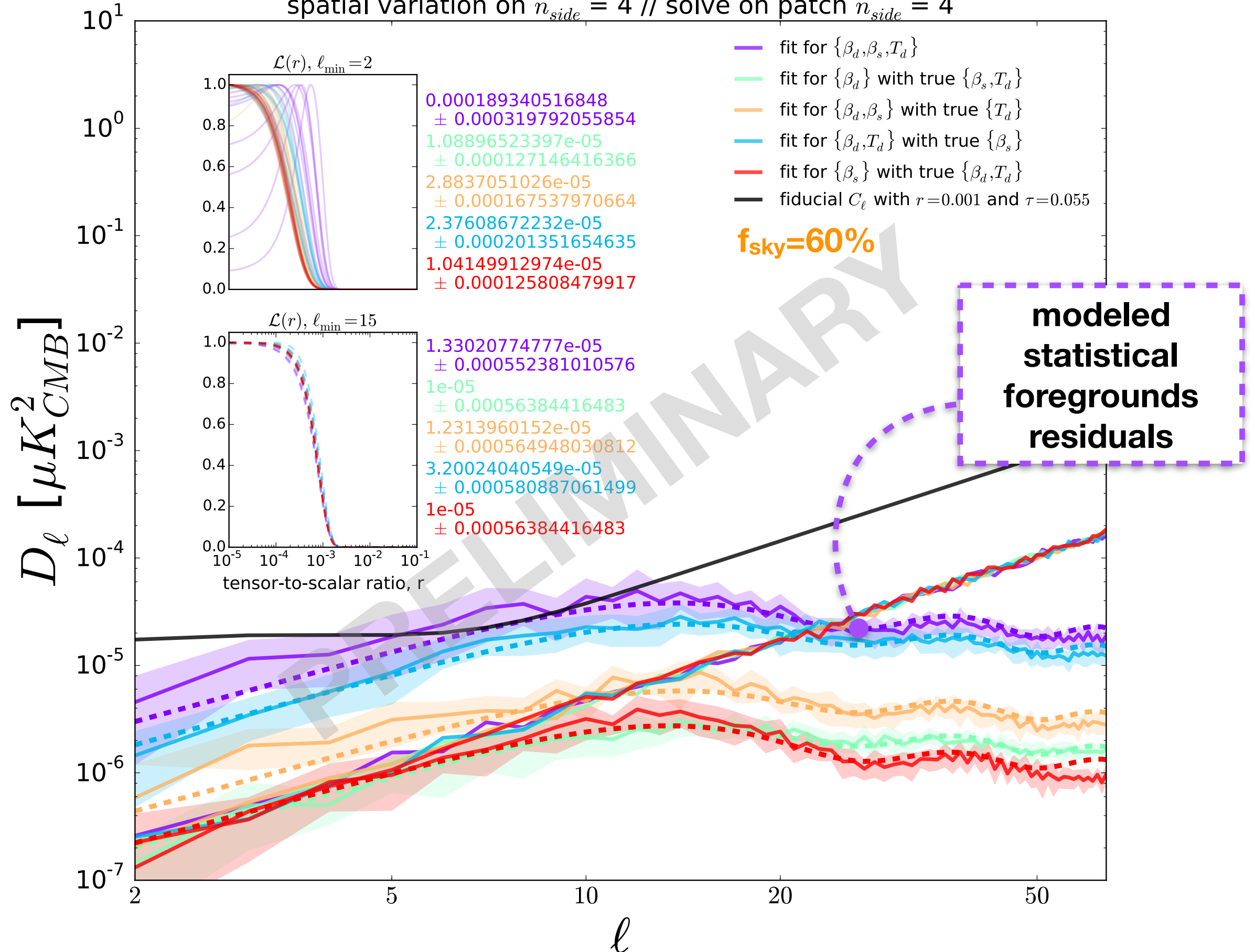
spatial variation on $n_{side} = 2$ // solve on patch $n_{side} = 2$



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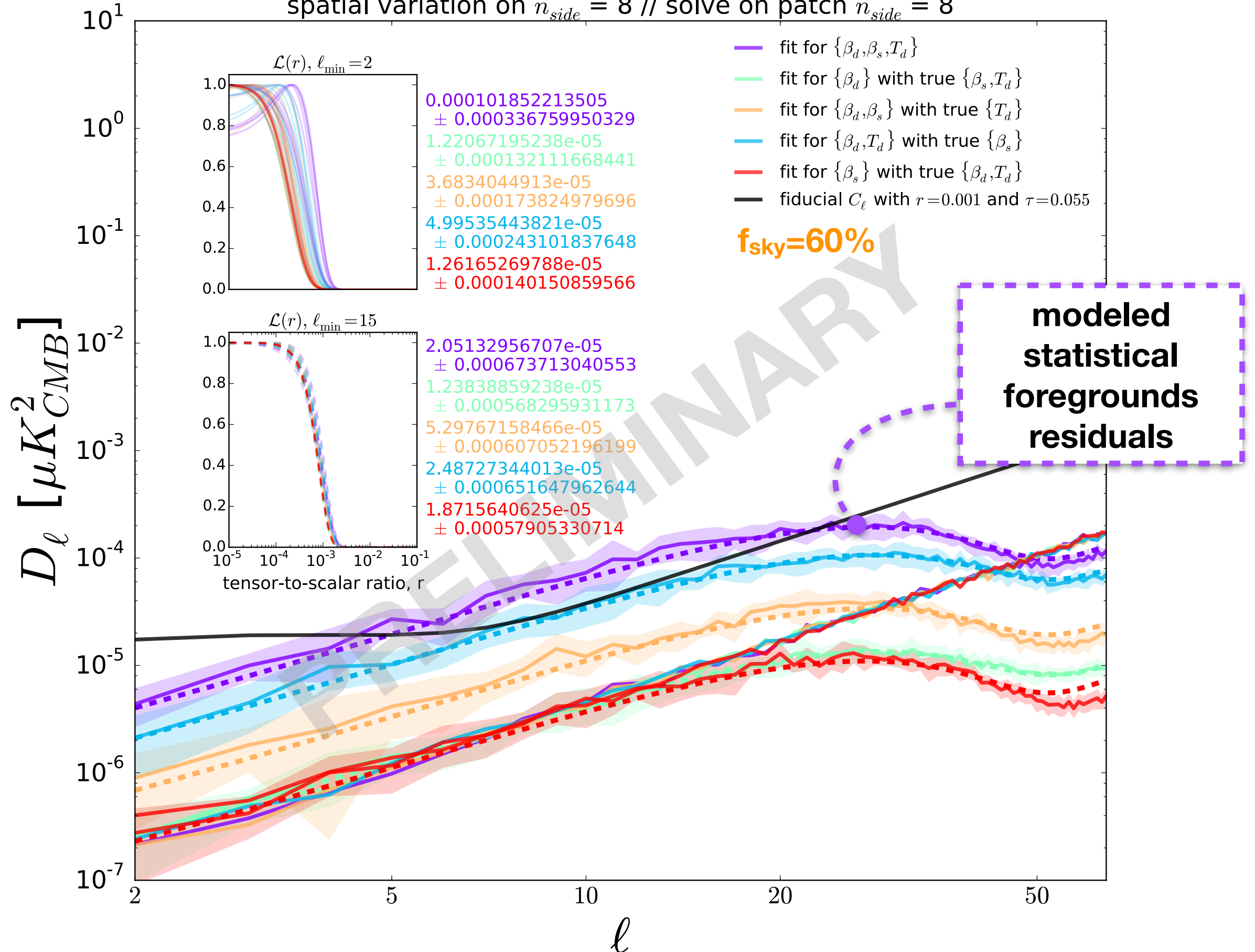
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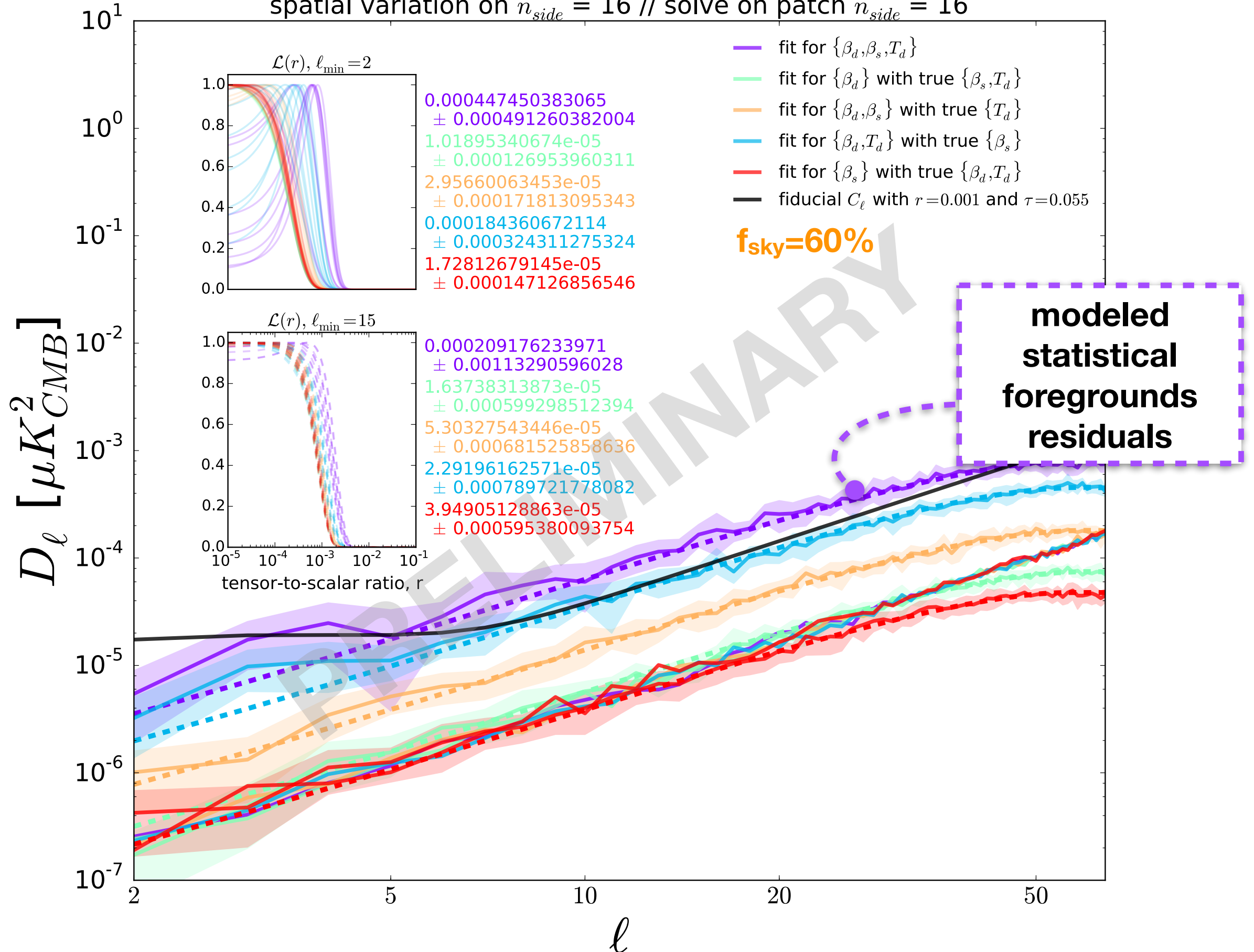
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variations of $\{\beta_d, \beta_s, T_d\}$ on this healpix resolution

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spatial variation on $n_{side} = 16$ // solve on patch $n_{side} = 16$



Results – multipatch when deprojecting statistical foregrounds residuals

 = $r_{\text{bias}} < \sigma(r) < 0.001$

PRELIMINARY

$$l_{\text{min}} \geq 2$$

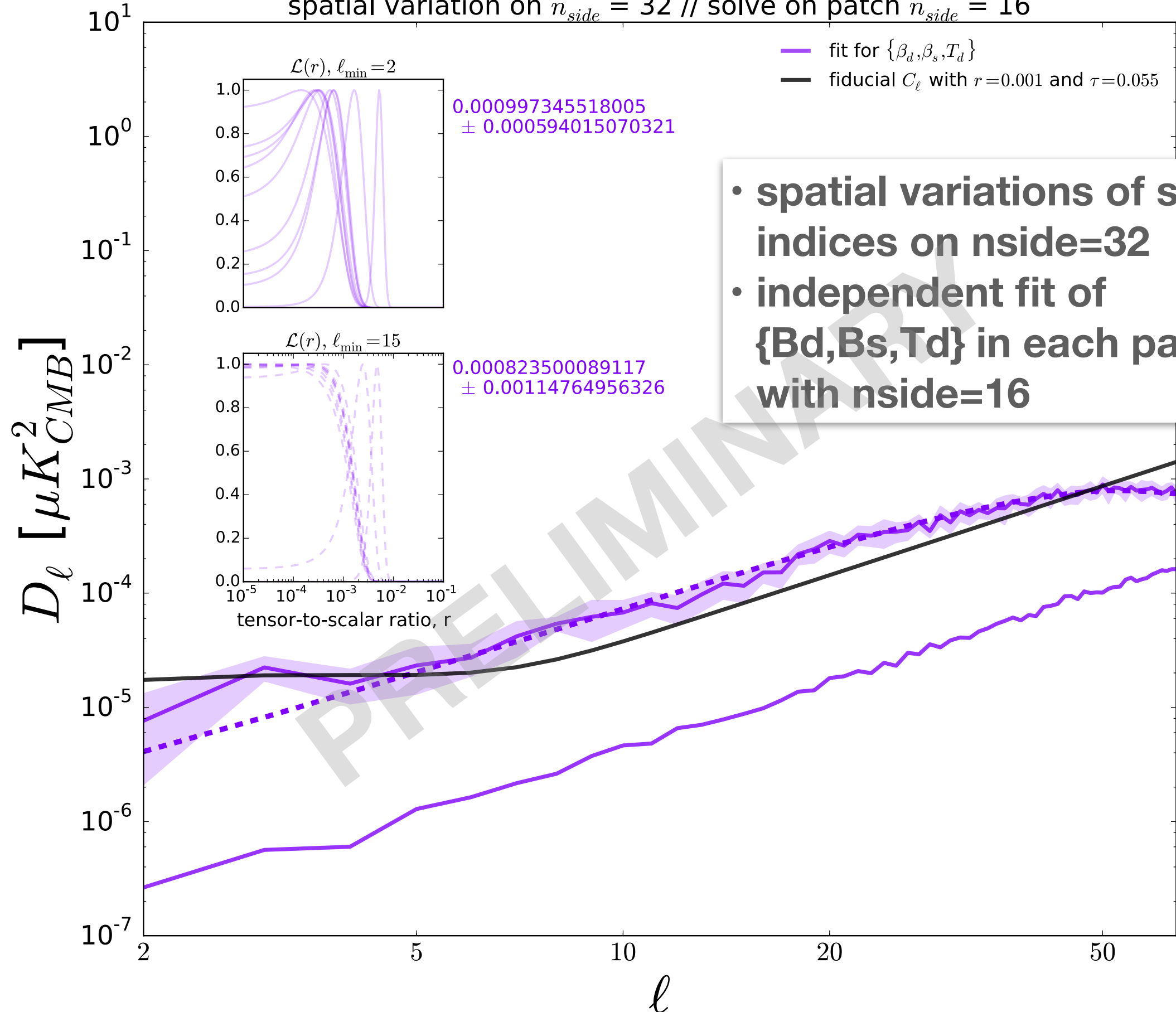
	previously ↓	after adding statistical foregrounds residuals model in the likelihood $\mathcal{L}(r)$
	fit for {Bd,Bs,Td}	fit for {Bd,Bs,Td}
nside = 2 (sim and cleaning)	0.000466 ± 0.000305	0.0000519 ± 0.000218
nside = 4 (sim and cleaning)	0.00183 ± 0.000505	0.000189 ± 0.000320
nside = 8 (sim and cleaning)	0.00755 ± 0.000727	0.000102 ± 0.000337
nside = 16 (sim and cleaning)	0.0217 ± 0.000894	0.000447 ± 0.000491

what about **more**
complex skies?

variations of $\{\beta_d, \beta_s, T_d\}$ on this healpix resolution

we perform component separation independently on this healpix resolution

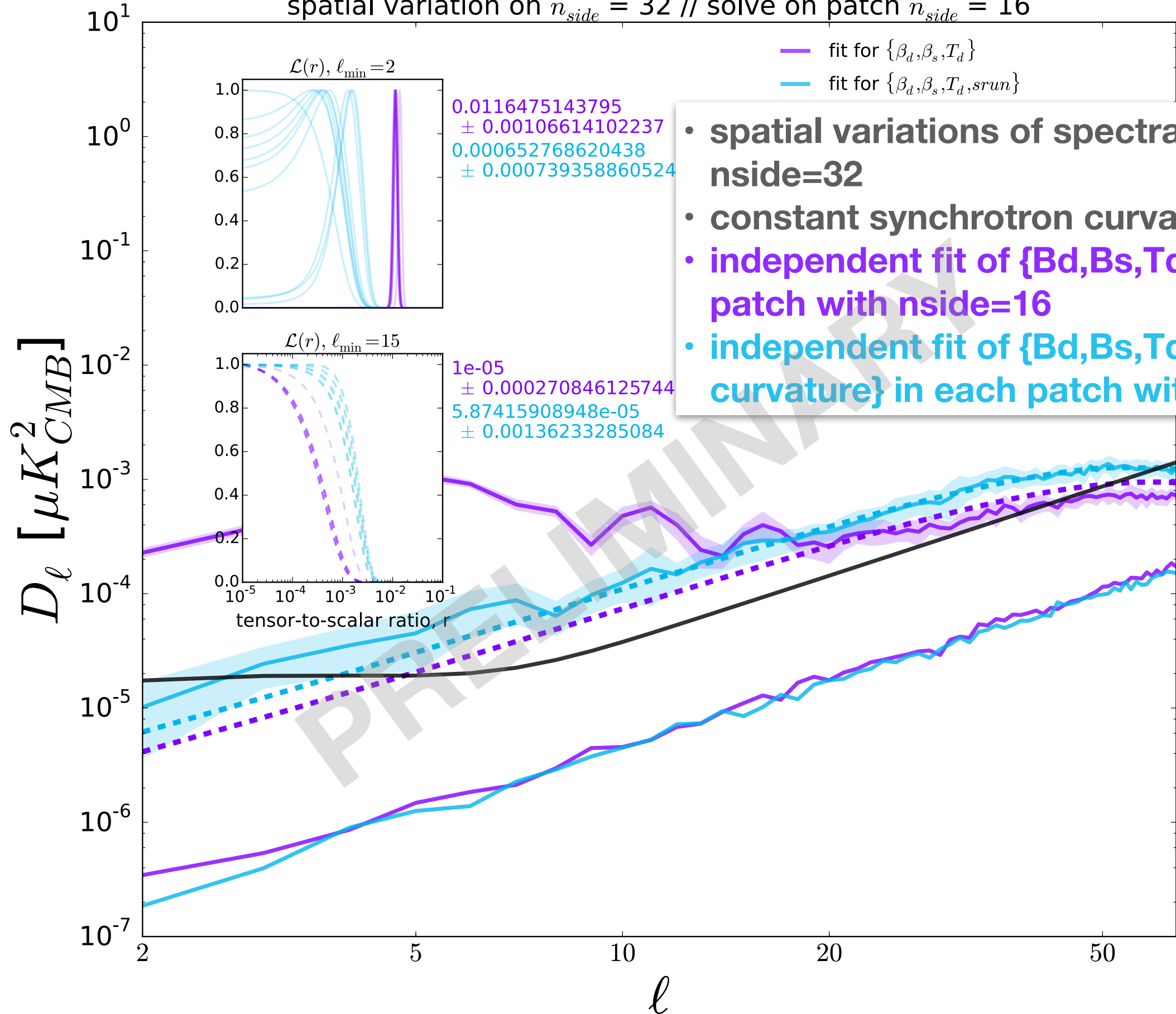
spatial variation on $n_{side} = 32$ // solve on patch $n_{side} = 16$



variations of $\{\beta_d, \beta_s, T_d\}$ on this healpix resolution

we perform component separation independently on this healpix resolution

spatial variation on $n_{side} = 32$ // solve on patch $n_{side} = 16$



- spatial variations of spectral indices on $n_{side}=32$
- constant synchrotron curvature in sims
- independent fit of $\{B_d, B_s, T_d\}$ in each patch with $n_{side}=16$
- independent fit of $\{B_d, B_s, T_d, \text{sync curvature}\}$ in each patch with $n_{side}=16$

0.0116475143795
 ± 0.00106614102237
 0.000652768620438
 ± 0.000739358860524

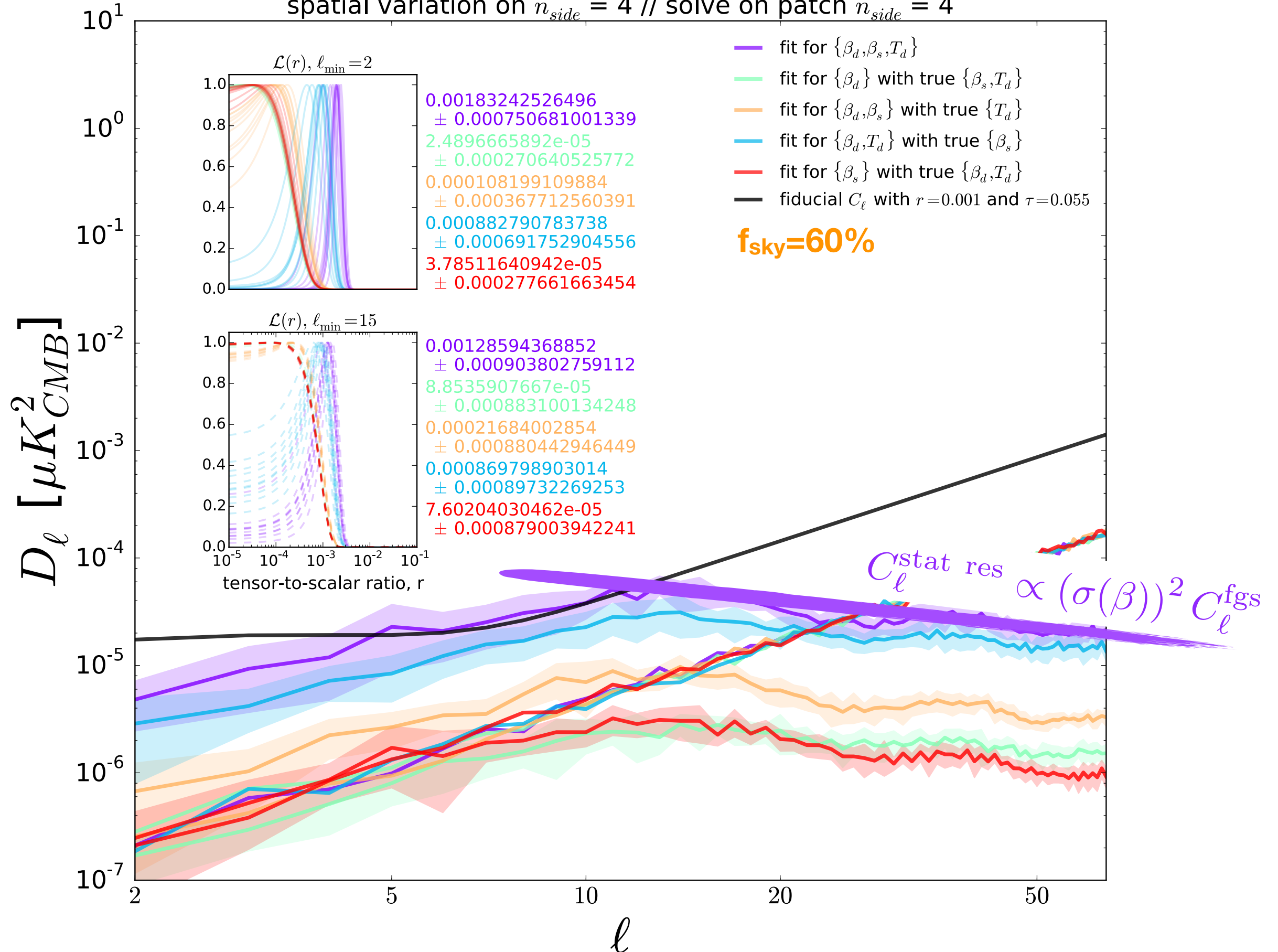
1e-05
 ± 0.000270846125744
 5.87415908948e-05
 ± 0.00136233285084

is it possible to
optimize the focal
plane to reduce the
foregrounds residuals?

variations of $\{\beta_d, \beta_s, T_d\}$ on this healpix resolution

we perform component separation independently on this healpix resolution

spatial variation on $n_{side} = 4$ // solve on patch $n_{side} = 4$



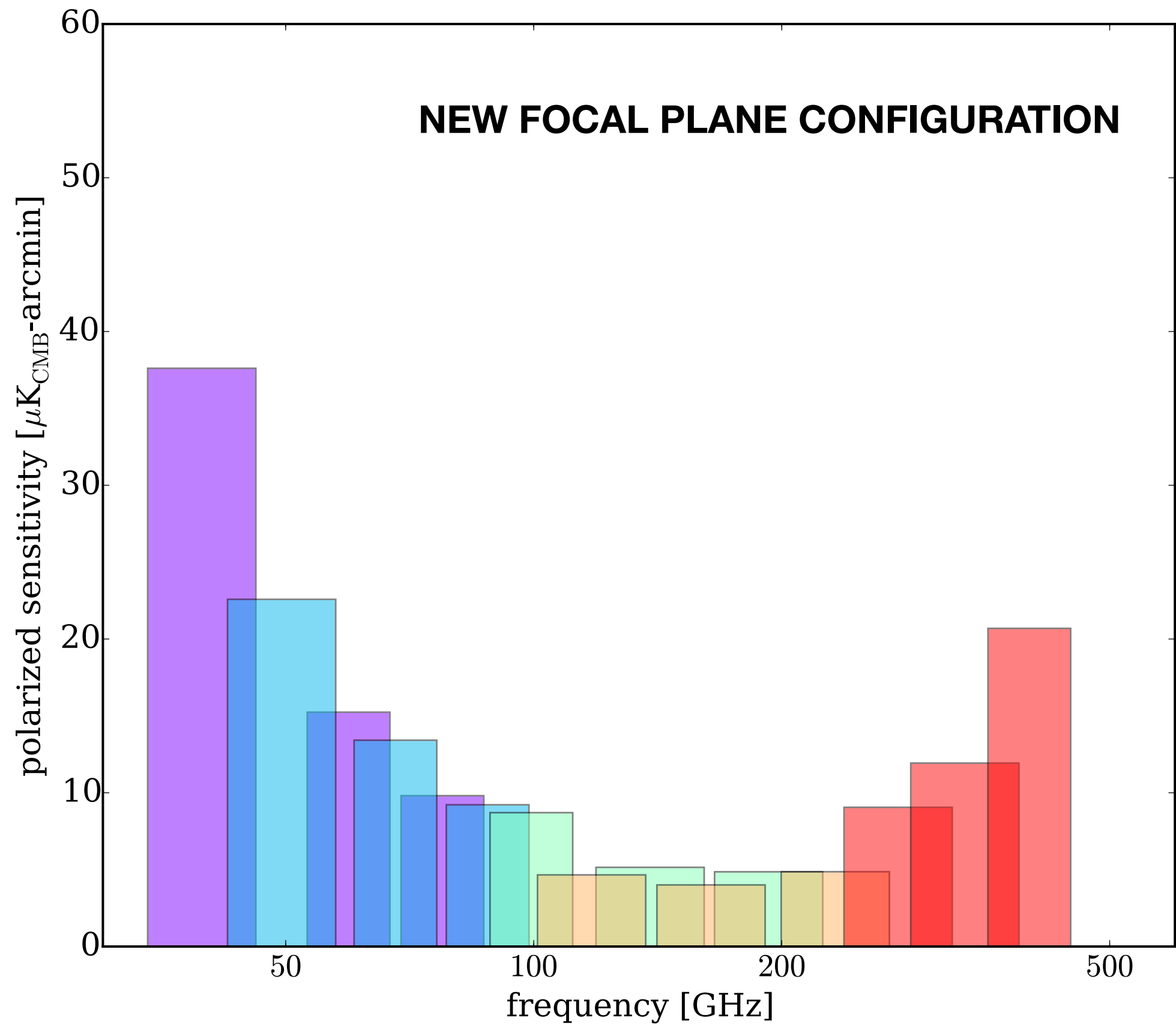
Method — optimization of focal plane

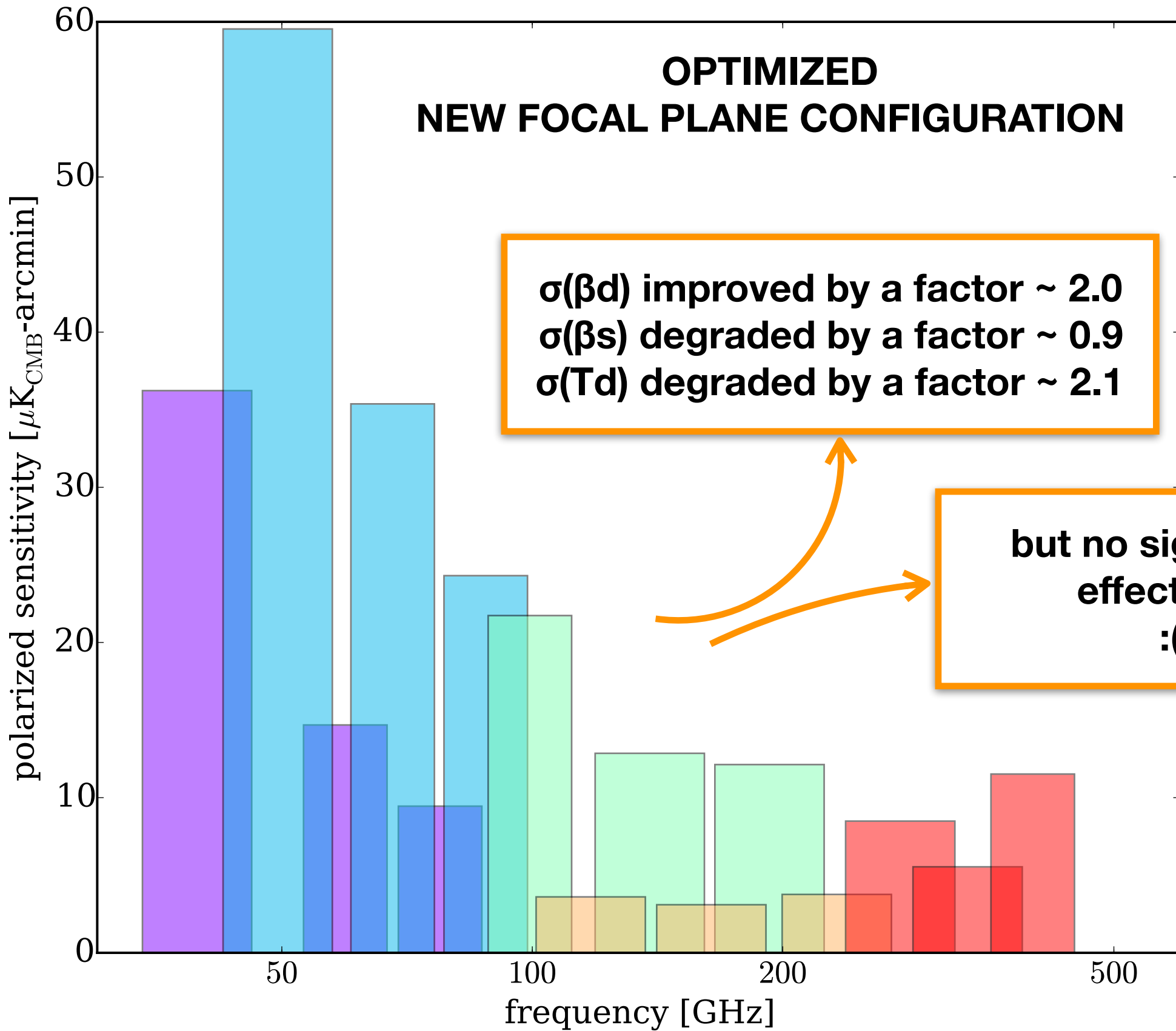
- minimization of $\|\Sigma(\beta)\|$ in each patch of the sky, for each simulations
- variable is the number of pixels i.e. {LF-1, LF-2, MF-1, MF-2, HF-1, HF-2, HF-3}
- we keep the area of the focal plane constant

$\|\Sigma(\beta)\|$ is the norm (I took it as the determinant) of the error covariance on spectral indices.

$$\Sigma \equiv \begin{bmatrix} \sigma(\beta_d)^2 & \sigma(\beta_d)\sigma(\beta_s) & \sigma(\beta_d)\sigma(T_d) \\ \star & \sigma(\beta_s)^2 & \sigma(\beta_s)\sigma(T_d) \\ \star & \star & \sigma(T_d)^2 \end{bmatrix}$$

We approximate Σ using the analytical form of the spectral likelihood curvature (Errard+ 2012) — this is why the optimization is numerically easy.





Conclusion - discussion

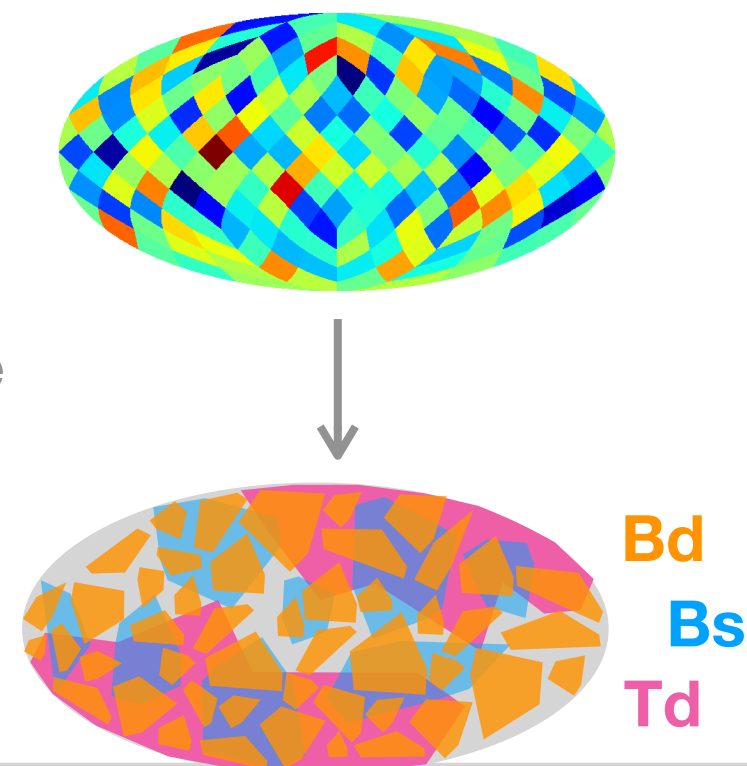
- current LiteBIRD focal plane design can reach **bias on $r < \sigma(r) < 0.001$** — considering input sky simulations with spatial variations of spectral indices over $n_{\text{side}}=16$ scales:
 - SMICA and xForecast agree on a **$r \sim 0.0006 \pm 0.0007$** when considering scales $\ell \geq 15$
 - Multipatch approach, combined with a deprojection of the statistical residuals, leads to **$r \sim 0.0004 \pm 0.0005$** ($\ell \geq 2$)
- complicating the sky (spatial variations on $n_{\text{side}}=32$ with synchrotron curvature) leads to **$r = 0.0007 \pm 0.0007$** ($\ell \geq 2$). **NB:** synchrotron curvature leads to a strong bias if not fitted for in the modeling.

Conclusion - discussion

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Next steps:

- unique and integrated framework including the estimation of $\{\beta\}$ and the marginalization of $\mathcal{L}(r)$ over statistical foregrounds residuals
- iterative patch finder — find optimal regions for each spectral index which would both optimize the statistical errors while minimizing the systematic bias. They would likely follow the morphology of the galactic foregrounds.
- build a consistent and common framework for SMICA and parametric pixel-based methods

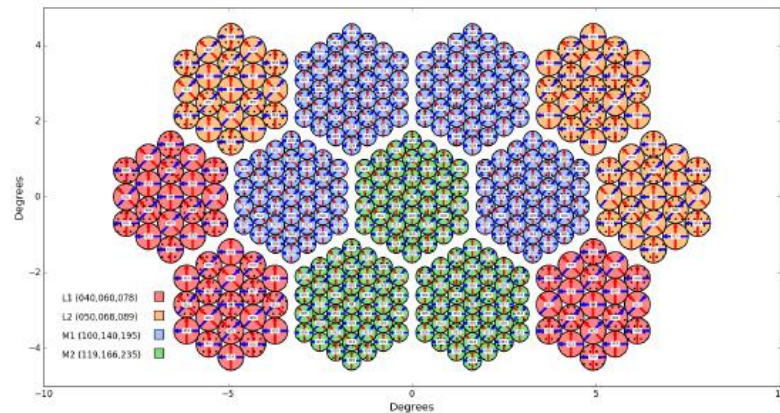


BACKUP

LiteBIRD assumed specifications

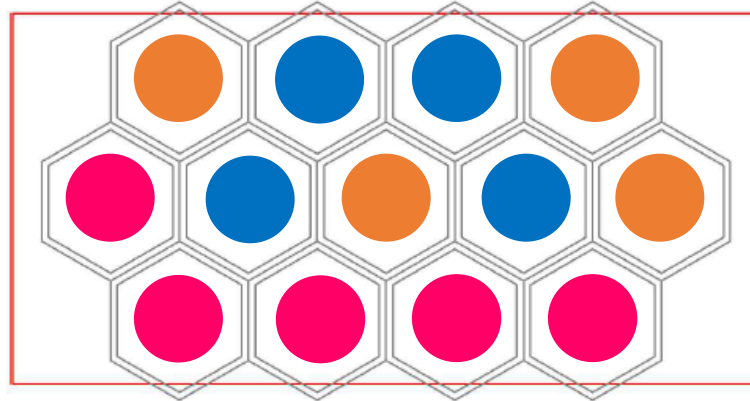
Proposal for Focal Plane Design

LFT - baseline design



Band	Center Freq [GHz]	Frac BW	Pixel Diameter [mm]	Num Pix	Num Det
LF-1	40	0.30	18	57	114
LF-2	50	0.30	18	57	114
LF-3	60	0.23	18	57	114
LF-4	68	0.23	18	57	114
LF-5	78	0.23	18	57	114
LF-6	89	0.23	18	57	114
MF-1	100	0.23	12	148	296
MF-2	119	0.30	12	111	222
MF-3	140	0.30	12	148	296
MF-4	166	0.30	12	111	222
MF-5	195	0.30	12	148	296
MF-6	235	0.30	12	111	222

LFT - LF enhanced design

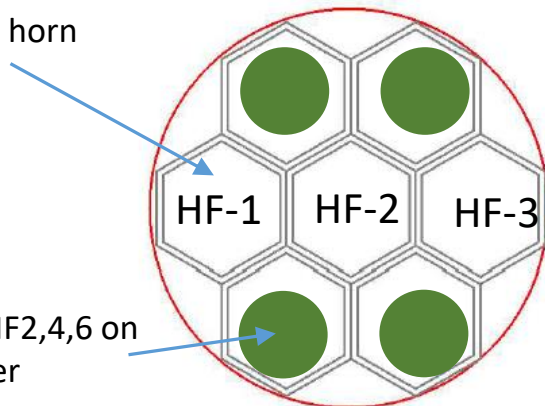


Band	Center Freq [GHz]	Frac BW	Pixel Diameter [mm]	Num Pix	Num Det
LF-1	40	0.30	18	57 95	114
LF-2	50	0.30	18	57 76	114
LF-3	60	0.23	18	57 95	114
LF-4	68	0.23	18	57 76	114
LF-5	78	0.23	18	57 95	114
LF-6	89	0.23	18	57 76	114
MF-1	100	0.23	12	148	296
MF-2	119	0.30	12	111	222
MF-3	140	0.30	12	148	296
MF-4	166	0.30	12	111	222
MF-5	195	0.30	12	148	296
MF-6	235	0.30	12	111	222

190
152
190
152
190
152

HFT - LO-HFT300

Single band horn

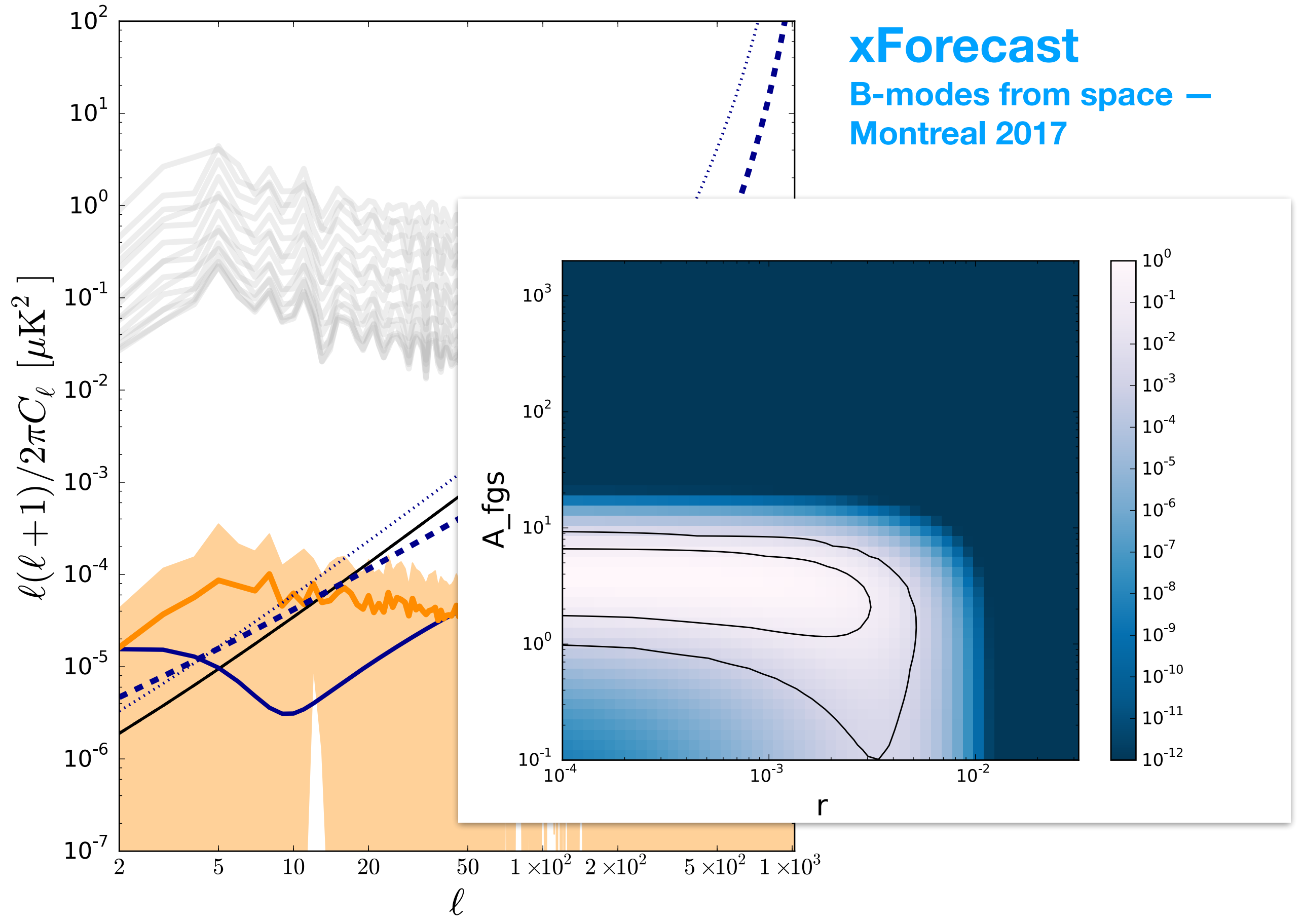


3bands MF2,4,6 on each wafer

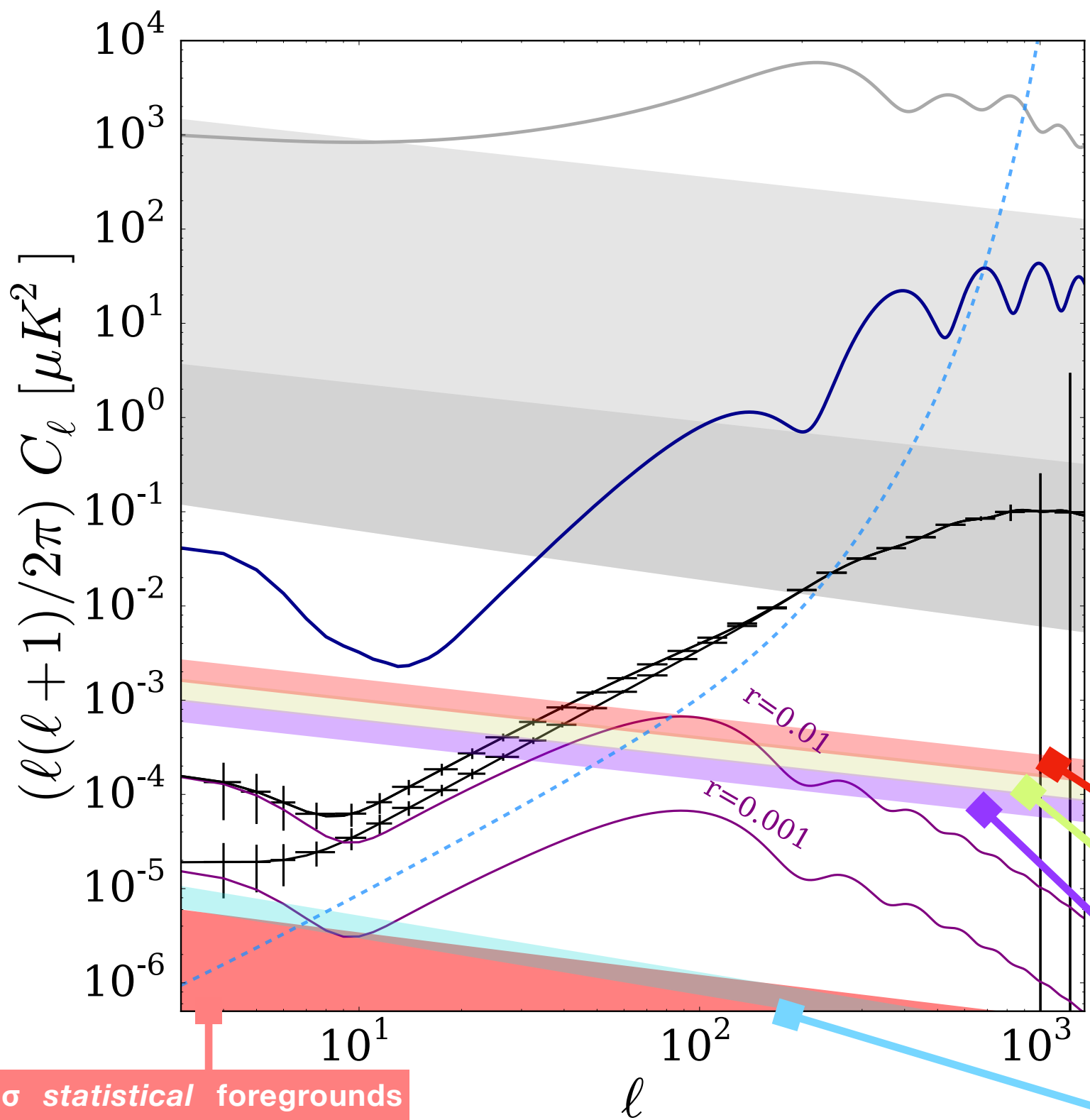
Band	Center Freq [GHz]	Freq BW	Pixel diameter [mm]	Num Pix	Num Det
MF-2	119	0.3	7.7	364	728
MF-4	166	0.3	7.7	364	728
MF-6	235	0.3	7.7	364	728
HF-1	280	0.3	3.9	271	542
HF-2	337	0.3	3.4	331	662
HF-3	402	0.23	2.7	469	938

xForecast

B-modes from space —
Montreal 2017



Foregrounds residuals due spatial variability of spectral indices, in the case of LiteBIRD



$$s^{\text{est.}} \equiv \mathbf{W} d^{\text{in}}$$

$$\Rightarrow \text{residuals} \equiv s^{\text{est.}} - s^{\text{in}}$$

$$\simeq \delta\beta \left. \frac{\partial \mathbf{W}}{\partial \beta} \right|_{\beta^{\text{true}}} d^{\text{in}}$$

- total B-modes
- primordial B-modes
- TT
- EE
- synchrotron + dust
- simple statistical residual
- syst. res. Bd
- syst. res. Bs
- syst. res. Td
- syst. res. BdBsTd
- - - N_ℓ after simple comp. sep.

if one does not taken into account the spatial variations of spectral indices!

from β_d, β_s, T_d

from T_d

from β_d

from β_s

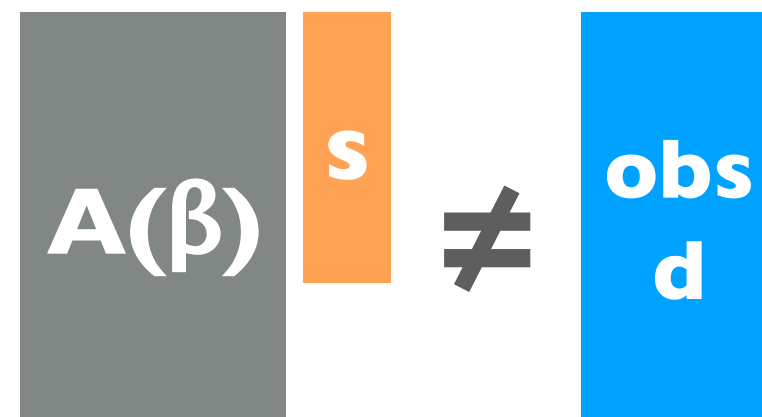
1- σ statistical foregrounds residuals when fitting for dust and synchrotron spectral indices, $\{\beta_d, \beta_s\}$, in each pixel of a healpix sky with $n_{\text{side}}=4$

Balance between statistical and systematic errors

$$\Sigma \equiv \begin{bmatrix} \sigma(\beta_d)^2 & \sigma(\beta_d)\sigma(\beta_s) & \sigma(\beta_d)\sigma(T_d) \\ \star & \sigma(\beta_s)^2 & \sigma(\beta_s)\sigma(T_d) \\ \star & \star & \sigma(T_d)^2 \end{bmatrix}$$

STATISTICAL error bars on spectral parameters

- better signal-to-noise (instrumental sensitivity, more sky pixels to count on for a given spectral index, etc.)
- broad frequency range
- large sky area (more pixels!)



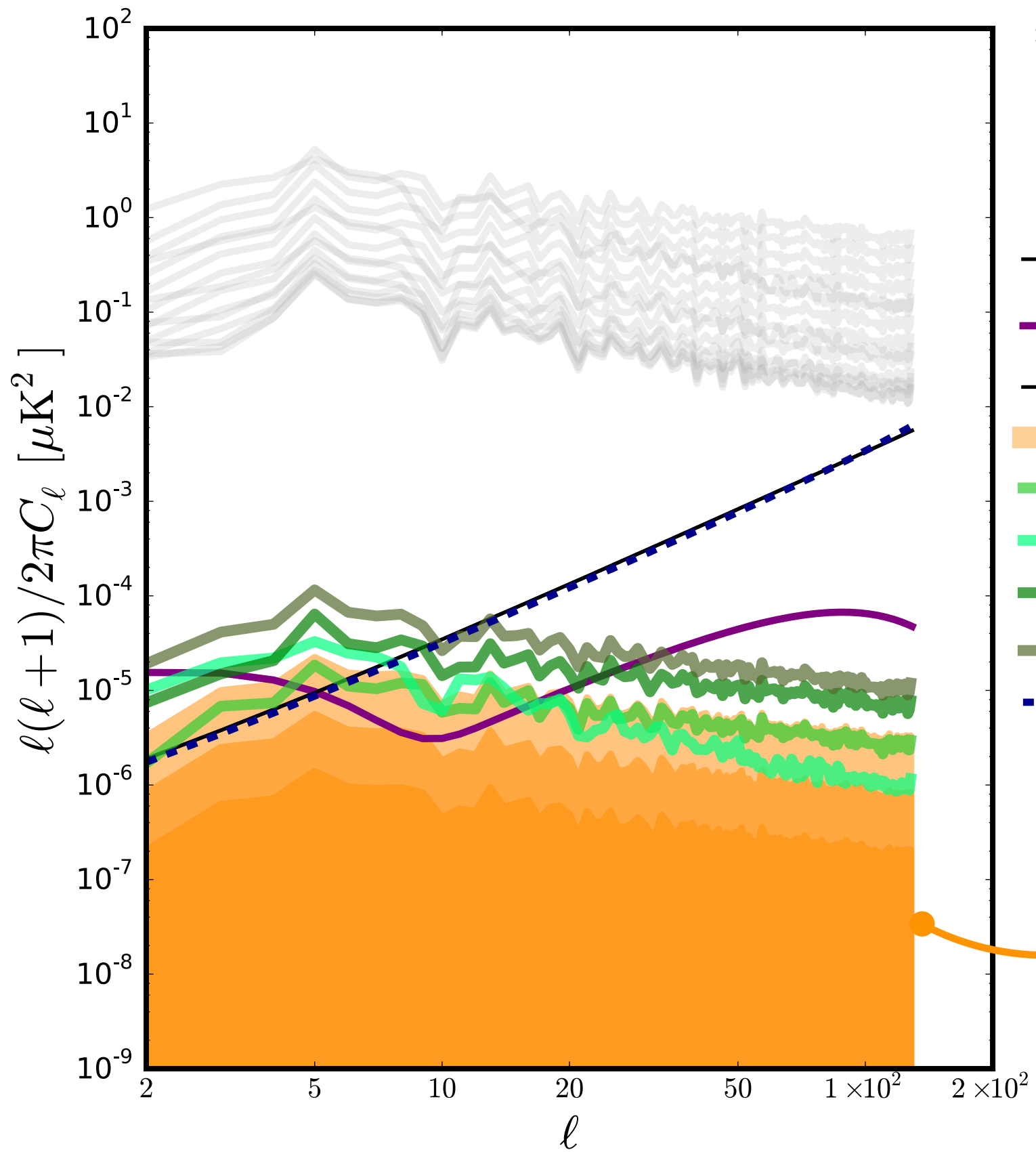
SYSTEMATIC error bars on spectral parameters

- more internal degrees of freedom (free spectral parameters, sky templates, etc.)
- reduced frequency range
- small sky area (less complexity!)

$$s^{\text{est.}} \equiv \mathbf{W} d^{\text{in}}$$

$$\Rightarrow \text{residuals} \equiv s^{\text{est.}} - s^{\text{in}}$$

$$\simeq \delta\beta \left. \frac{\partial \mathbf{W}}{\partial \beta} \right|_{\beta^{\text{true}}} d^{\text{in}}$$



- total B-modes
- primordial B-modes
($r=0.001, \tau=0.055$)
- lensing B-modes
- xF average residuals $\pm 2-\sigma$
- sys. res. from β_d spat. var.
- sys. res. from β_s spat. var.
- sys. res. from T_d spat. var.
- sys. res. from $\{\beta_d, \beta_s, T_d\}$ spat. var.
- - - N_ℓ

1- σ statistical foregrounds residuals when fitting for dust and synchrotron spectral indices, $\{\beta_d, \beta_s, T_d\}$, in each pixel of a healpix sky with nside=16

$$l_{\min} \geq 15$$

■ = $\sigma(r) < 0.001$ and $r_{\text{bias}} < \sigma(r)$

	fit for {Bd} true {Bs,Td}	fit for {Bd,Bs} true {Td}	fit for {Bd,Bs,Td}	fit for {Bd,Td} true {Bs}	fit for {Bs} true {Bd,Td}
nside = 2 (sim and cleaning)	1.53e-05 ± 0.000562	3.11e-05 ± 0.000570	0.000207 ± 0.000579	0.000160 ± 0.000572	1.22e-05 ± 0.000562
nside = 4 (sim and cleaning)	8.85e-05 ± 0.000563	0.000217 ± 0.000572	0.00129 ± 0.000600	0.000870 ± 0.000574	7.60e-05 ± 0.000565
nside = 8 (sim and cleaning)	0.000937 ± 0.000583	0.000141 ± 0.000595	0.00737 ± 0.000670	0.00381 ± 0.000643	0.000498 ± 0.000581
nside = 16 (sim and cleaning)	0.00169 ± 0.000608	0.00558 ± 0.000795	0.0221 ± 0.00132	0.0104 ± 0.00107	0.00187 ± 0.000626

Excerpt of our conclusions in Montreal 2017

- we show **consistency** between xForecast and SMICA on constant spectral indices and PySM simulations
- **spatial variability of dust is important to characterize, and high frequency channels are crucial**

