B-mode foregrounds removal: LiteBIRD study

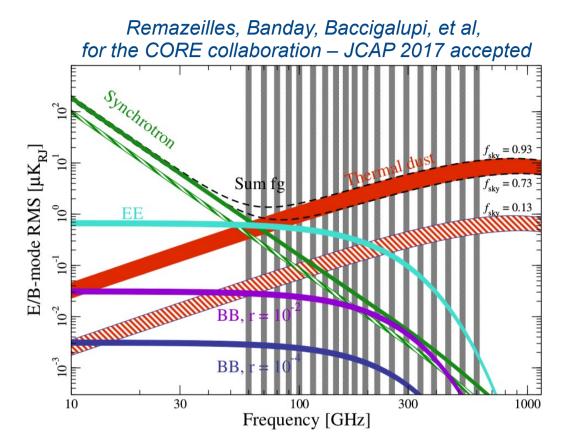
Mathieu Remazeilles



The University of Manchester

B-mode from Space workshop UC Berkeley, USA, 4-6 Dec 2017

CMB B-mode vs foregrounds



Polarization less complex than intensity (fewer components) but more challenging:

- \rightarrow larger dynamic range between CMB and foregrounds!
- \rightarrow a slight mis-modelling of foregrounds can have a dramatic impact on the CMB B-mode

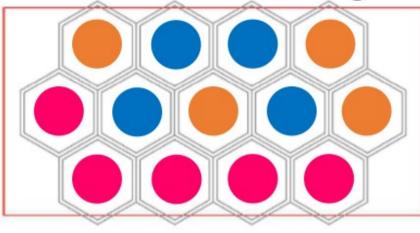
Foregrounds cannot be avoided just by limiting the frequency range of observations:

- \rightarrow At 300 GHz the synchrotron has same amplitude and color than the CMB B-mode r=10⁻² !
- \rightarrow Broad frequency range is essential to fight against spectral degeneracies

Example of focal plane for LiteBIRD

cross-Dragone, multi-chroic

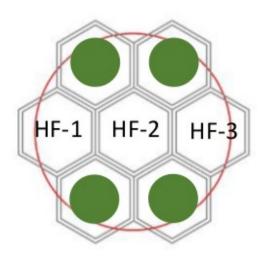
LFT - LF enhanced design



There is still some flexibility on the final design

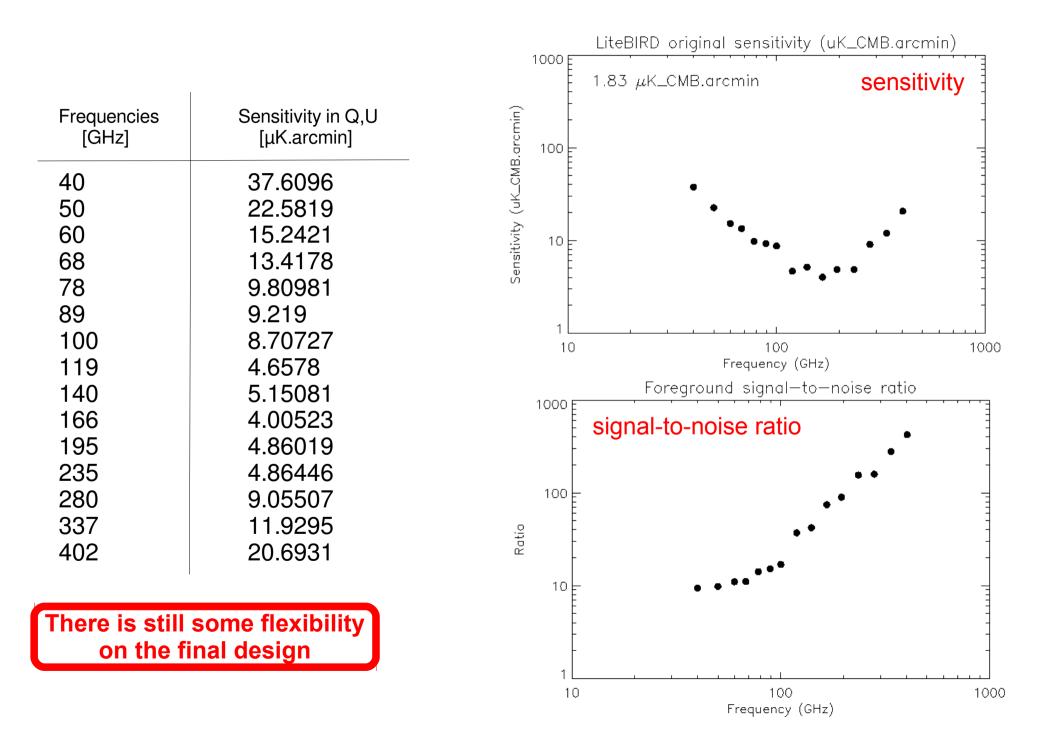
	Num Det	Num Pix	Pixel Diameter [mm]	Frac BW	Center Freq [GHz]	Band
19	1.4	a7 95	18	0.30	40	LF-1
1!	1.4	57 76	18	0.30	50	LF-2
19	1.4	57 95	18	0.23	60	LF-3
1	1.4	57 76	18	0.23	68	LF-4
1	114	§7 95	18	0.23	78	LF-5
1	114	57 76	18	0.23	89	LF-6
1	296	148	12	0.23	100	MF-1
1	222	111	10	0.00	110	ME o
1	296	148	12	0.30	140	MF-3
1		111	10	0.00	100	ME (
1	296	148	12	0.30	195	MF-5
1	000	111	10	0.00	0.95	MEC

HFT - LO-HFT300

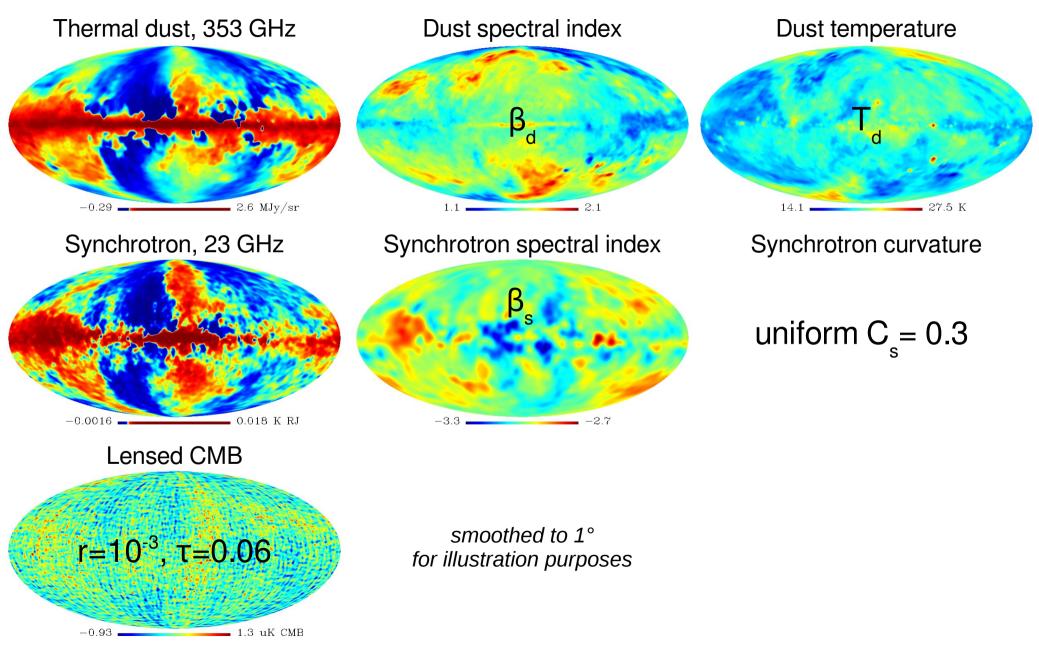


Band	Center Freq [GH z]	Freq BW	Pixel diameter [mm]	Num Pix	Num Det
MF-2	119	0.3	7.7	364	728
MF-4	166	0.3	7.7	364	728
MF-6	235	0.3	7.7	364	728
HF-1	280	0.3	3.9	271	542
HF-2	337	0.3	3.4	331	662
HF-3	402	0.23	2.7	469	938

LiteBIRD sensitivities



LiteBIRD PSM simulation: Stokes Q maps



Based on the Planck Sky Model (PSM) – *Delabrouille et al 2013*

Methodology

Eriksen et al 2004, 2008 Remazeilles et al 2016, 2017

1. Separation of components (COMMANDER fitting + Gibbs sampling):

$$\begin{array}{lll} \boldsymbol{s}^{(i+1)} & \leftarrow & P\left(\boldsymbol{s} | C_{\ell}^{(i)}, \boldsymbol{\beta}^{(i)}, \boldsymbol{d}\right), \\ C_{\ell}^{(i+1)} & \leftarrow & P\left(C_{\ell} | \boldsymbol{s}^{(i+1)}\right), \\ \boldsymbol{\beta}^{(i+1)} & \leftarrow & P\left(\boldsymbol{\beta} | \boldsymbol{s}^{(i+1)}, \boldsymbol{d}\right), \end{array}$$

Amplitudes (CMB, foregrounds) Power spectra (CMB) Spectral indices (foregrounds)

2. Likelihood estimation of r and A _{lens}:

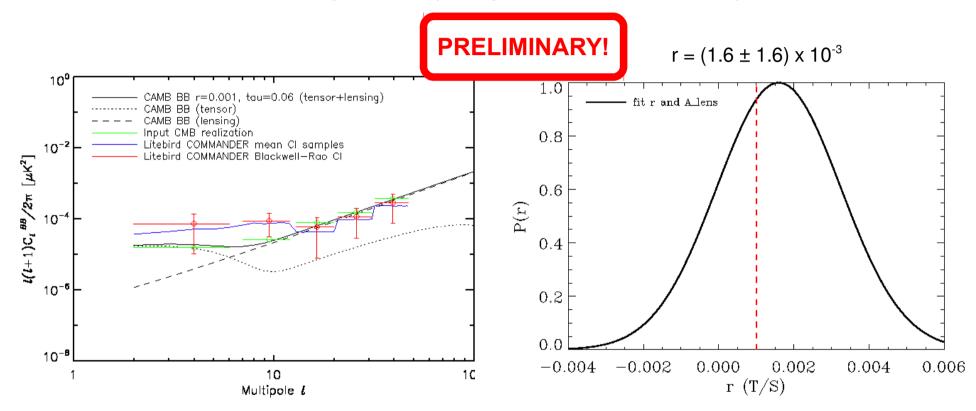
$$-2\ln\mathcal{L}\left[\widehat{C}_{\ell}|C_{\ell}^{th}\left(r,A_{lens}\right)\right] = \sum_{\ell} (2\ell+1)\left[\ln\left(\frac{C_{\ell}^{th}}{\widehat{C}_{\ell}}\right) + \frac{C_{\ell}^{th}}{\widehat{C}_{\ell}} - 1\right]$$

$$C_{\ell}^{th} = r C_{\ell}^{tensor}(r=1) + A_{lens} C_{\ell}^{lensing}(r=0),$$

3. Blackwell-Rao posterior: $\mathcal{P}(r, A_{lens}) \approx \frac{1}{N} \sum_{i=1}^{N} \mathcal{L}\left[\widehat{C}_{\ell}^{i} | C_{\ell}^{th}(r, A_{lens})\right]$

CMB B-mode reconstruction with Commander. r = 10^{-3} , <u>fitting everything</u>

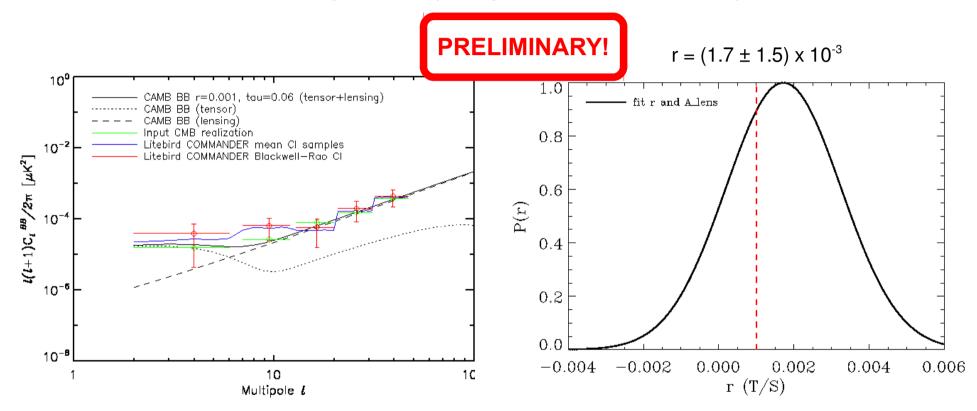
3D foregrounds (no synchrotron curvature)



$$\beta_{d}, T_{d}, \beta_{s}$$
 locally fitted

CMB B-mode reconstruction with Commander. r = 10⁻³, fixing β_s and T_d

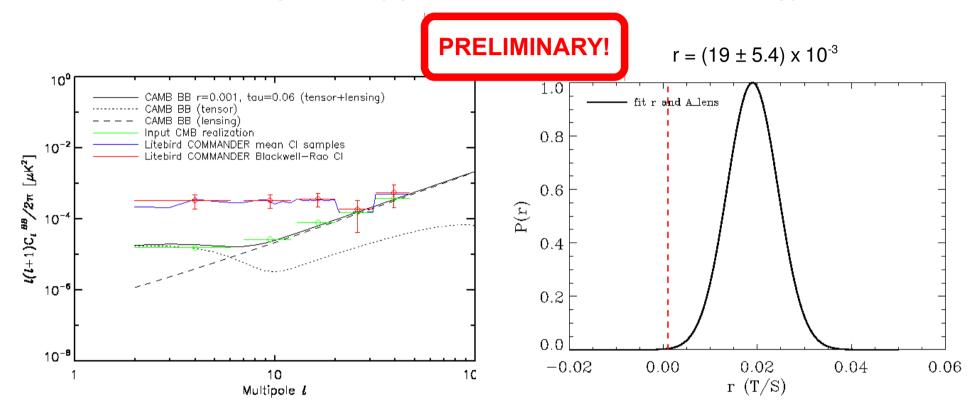
3D foregrounds (no synchrotron curvature)





CMB B-mode reconstruction with Commander. r = 10^{-3} , <u>fitting everything</u>

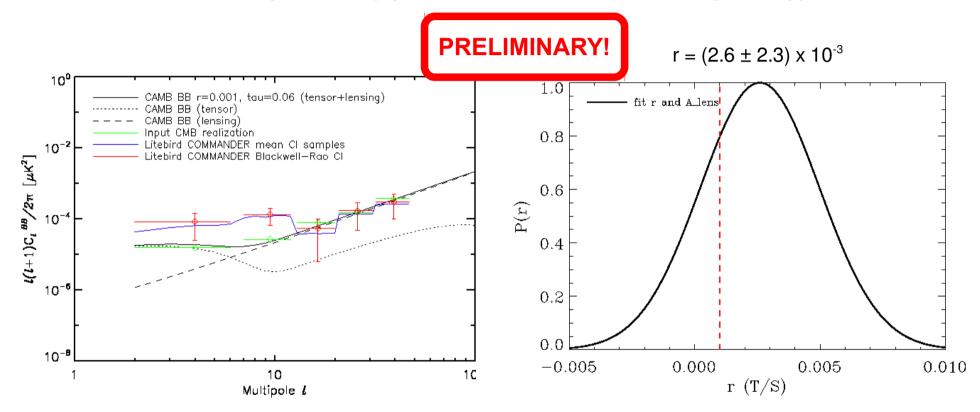
4D foregrounds (synchrotron curvature fitted locally)



β_{d} , T	$\beta_{d}, \beta_{s}, C_{s}$	locally	fitted
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CMB B-mode reconstruction with Commander. r = 10^{-3} , fitting everything

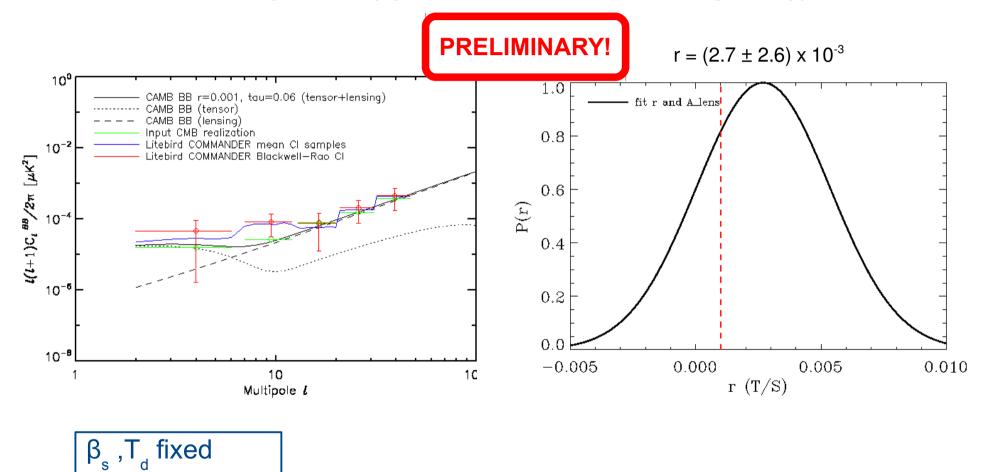
4D foregrounds (synchrotron curvature fitted globally)



$$\beta_{d}$$
, T_{d} , β_{s} locally fitted C_{s} globally fitted

CMB B-mode reconstruction with Commander. r = 10^{-3} , fixing β_s and T_d

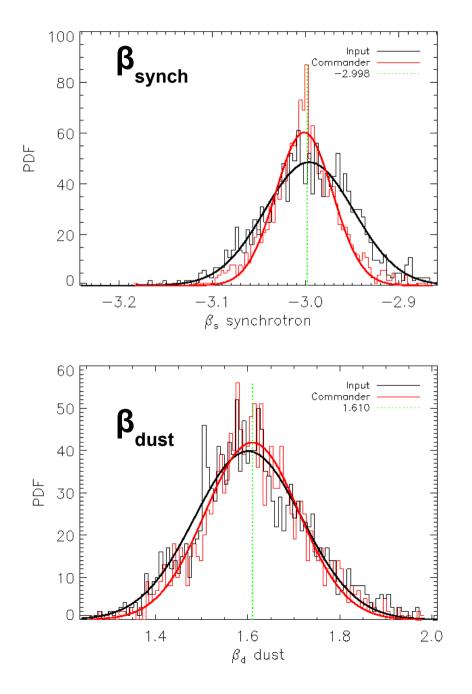
4D foregrounds (synchrotron curvature fitted globally)

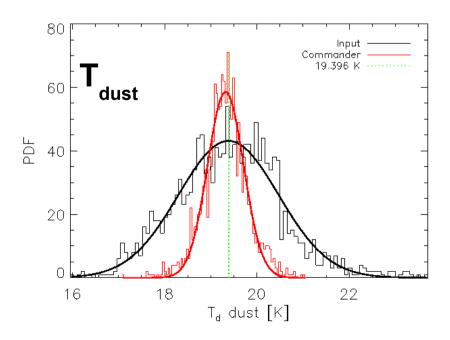


 β_d locally fitted

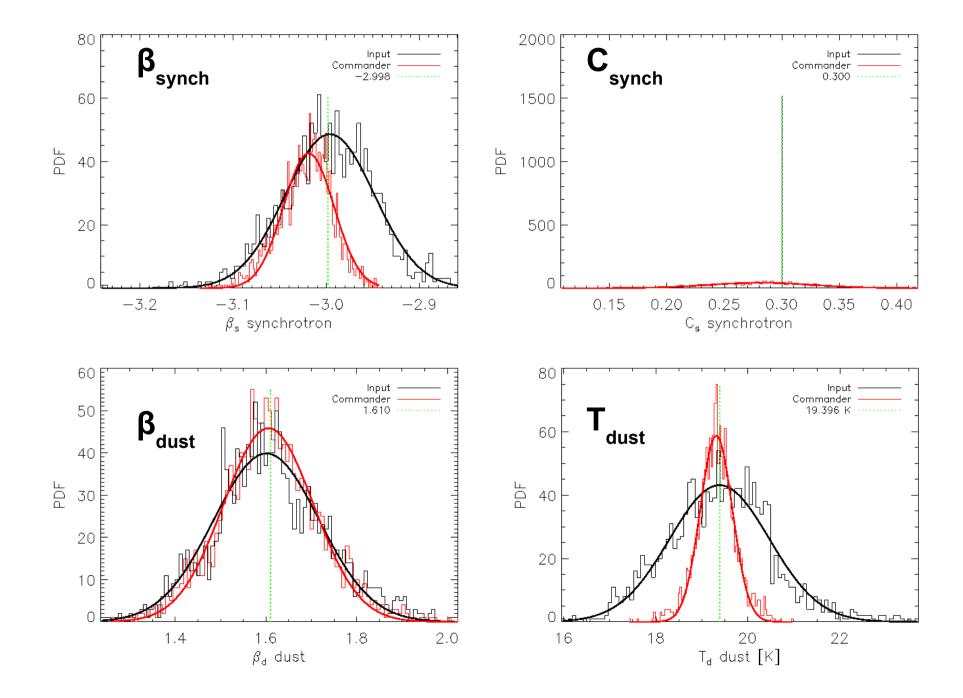
C globally fitted

Results for 3D foregrounds

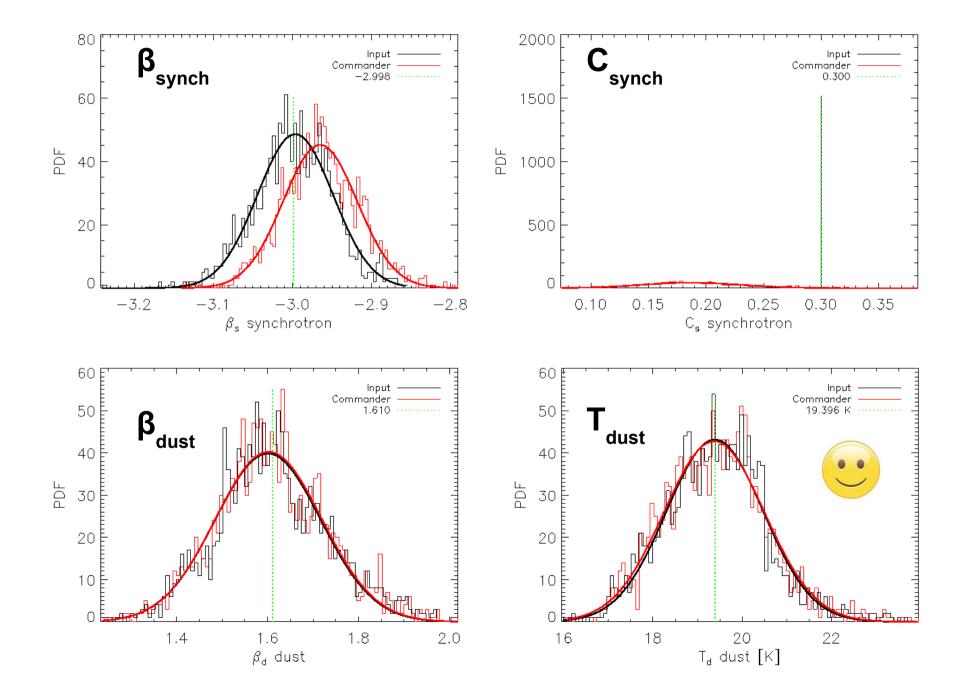


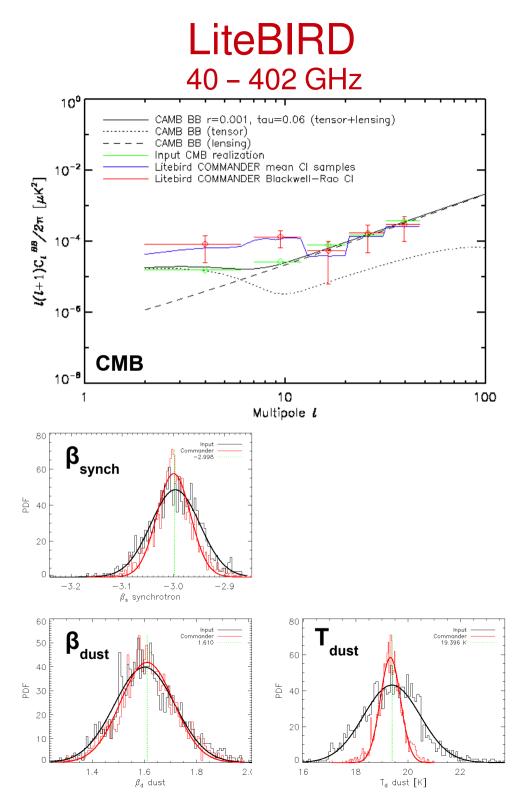


Results for 4D foregrounds

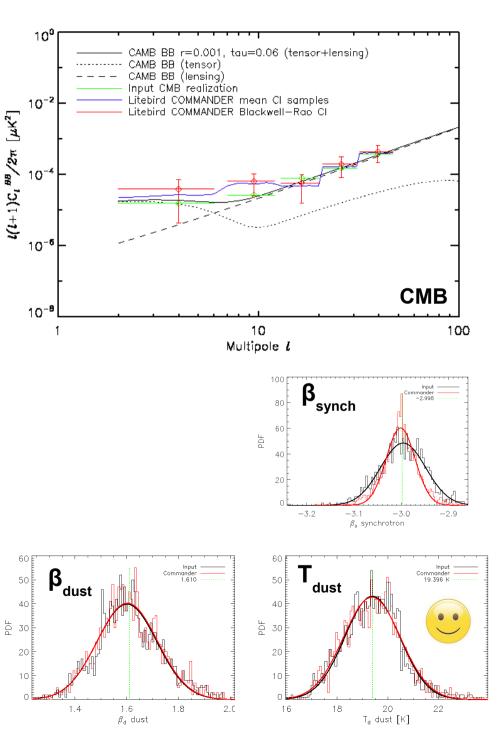


Adding a 600 GHz channel?

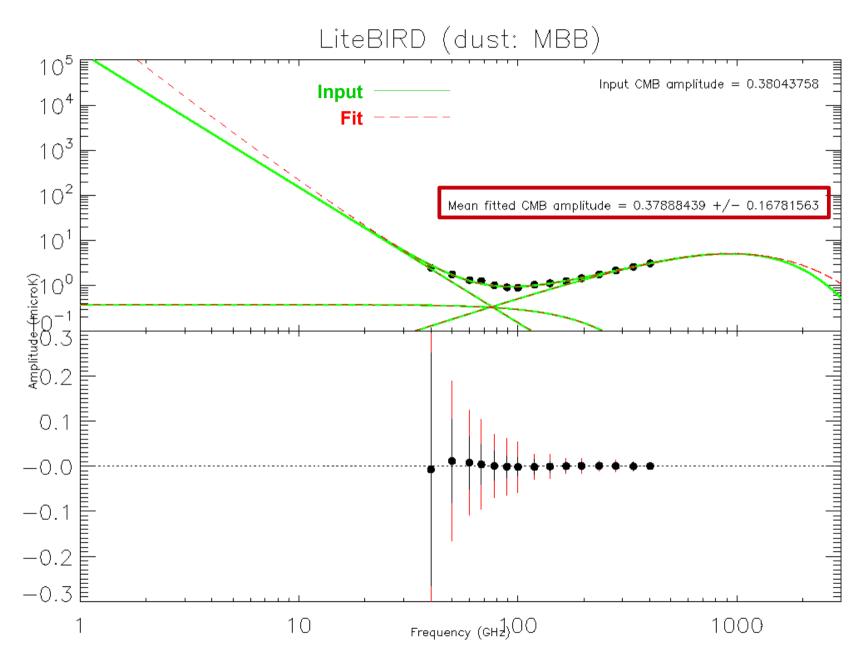




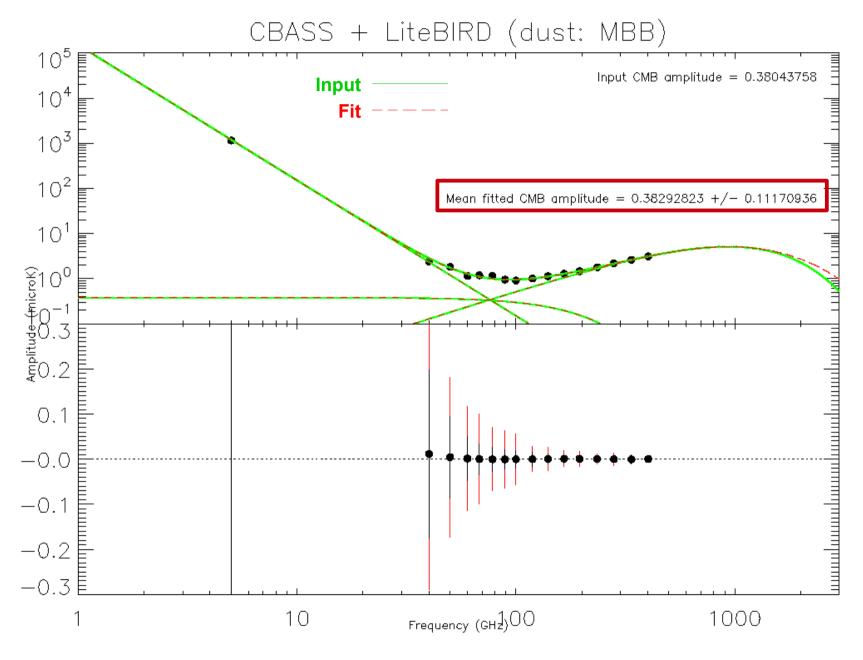
LiteBIRD + 600 GHz



Without C-BASS

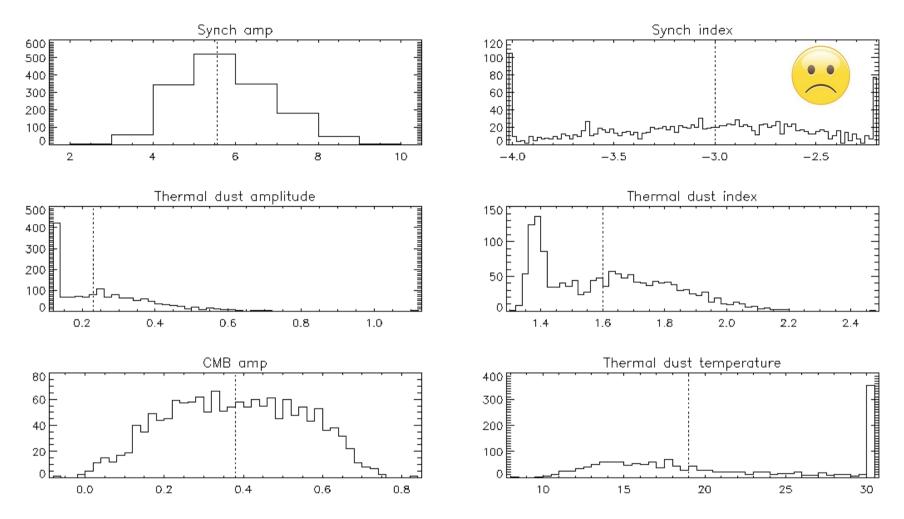


With C-BASS

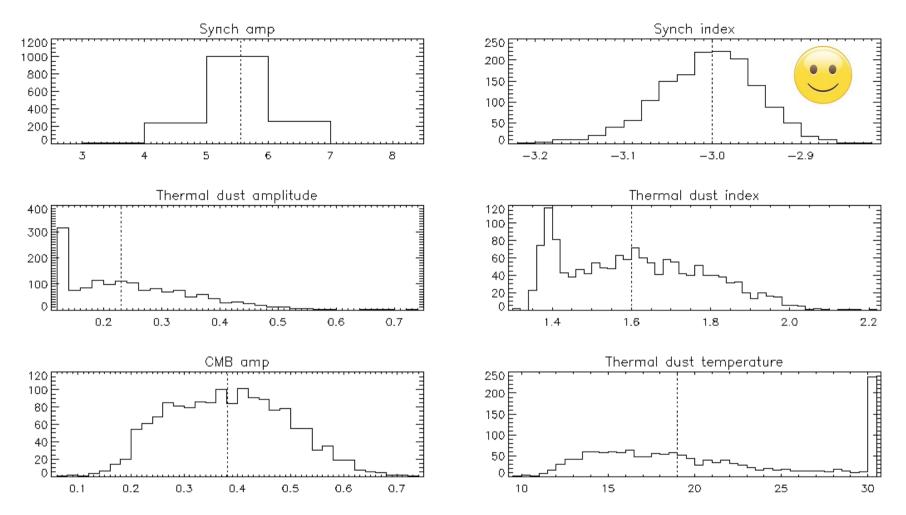


Uncertainty $\sigma(A_CMB)$ decreased by 30% !

Without C-BASS



With C-BASS



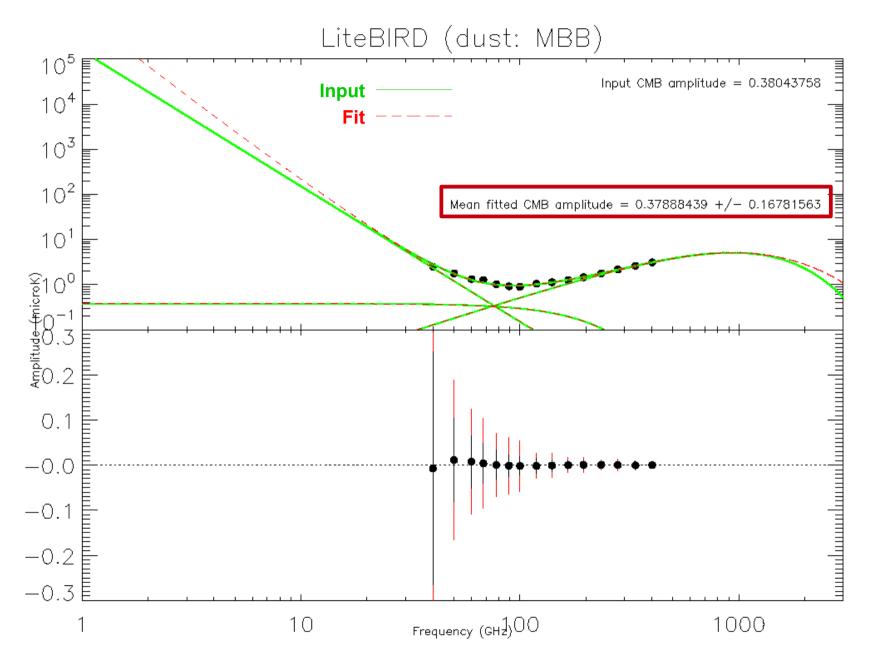
Synchrotron index is much better constrained with C-BASS 5GHz band, so the CMB is.

Physics versus Mathematics

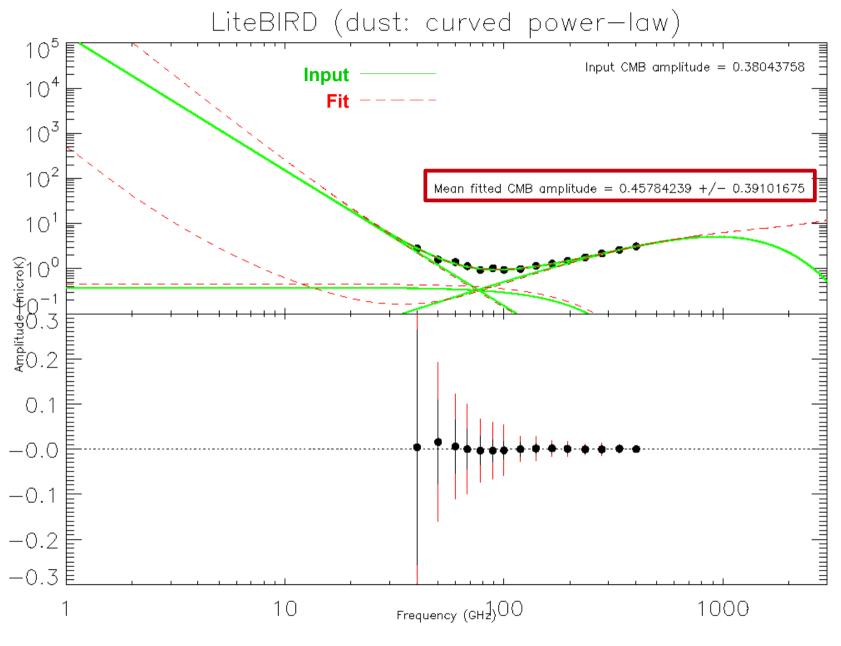
How to deal with foreground complexity over a limited frequency range?

- Over a limited frequency range, we suffer from a lack of high-frequency data points to constrain the dust temperature T_{dust} at the required precision $\sigma(r) < 10^{-3}$
 - \rightarrow This translates into a biased CMB B-mode by extrapolation.
- Can we get more <u>precision</u> by fitting a dust <u>curvature</u> (local) instead of a dust <u>temperature</u> (non-local) over the limited frequency range, without lack of <u>accuracy</u>?

LiteBIRD dust: fit a MBB

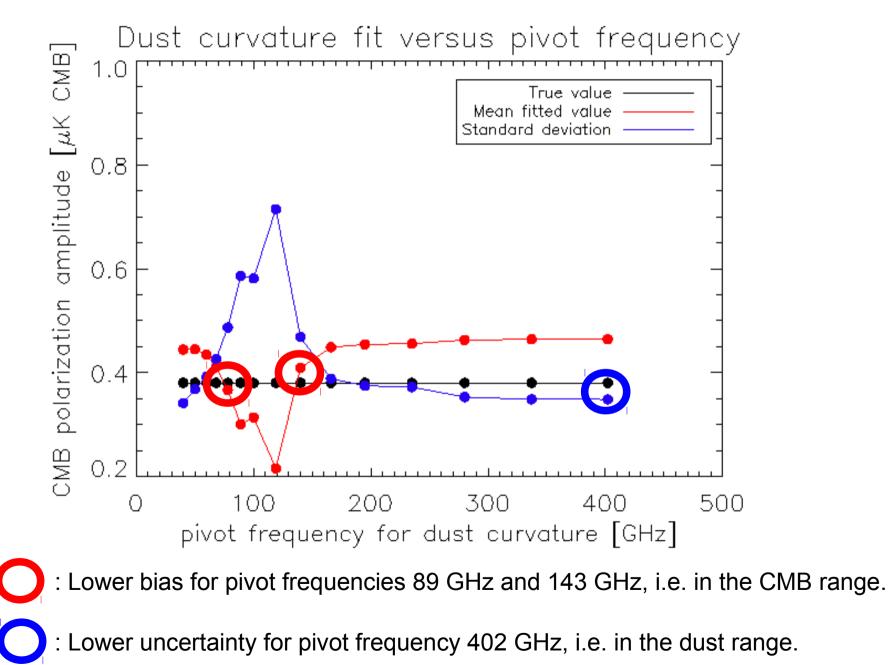


LiteBIRD dust: fit a curved power-law



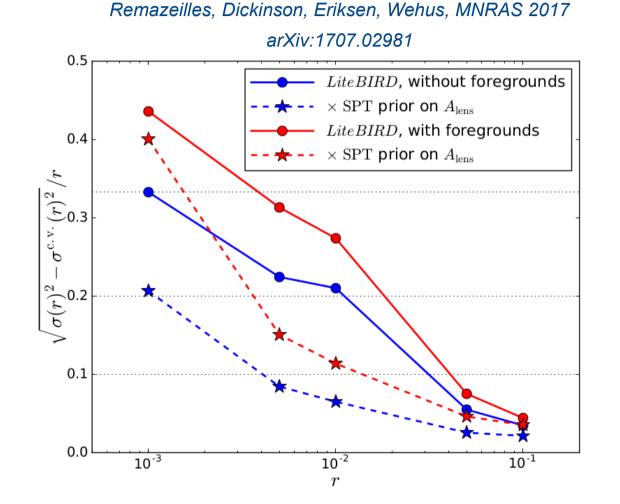
Pivot frequency: 400 GHz

What's the best pivot frequency?



 \rightarrow no ideal choice of pivot frequency!

Joint Bayesian estimation of tensor, lensing, and foreground B-modes

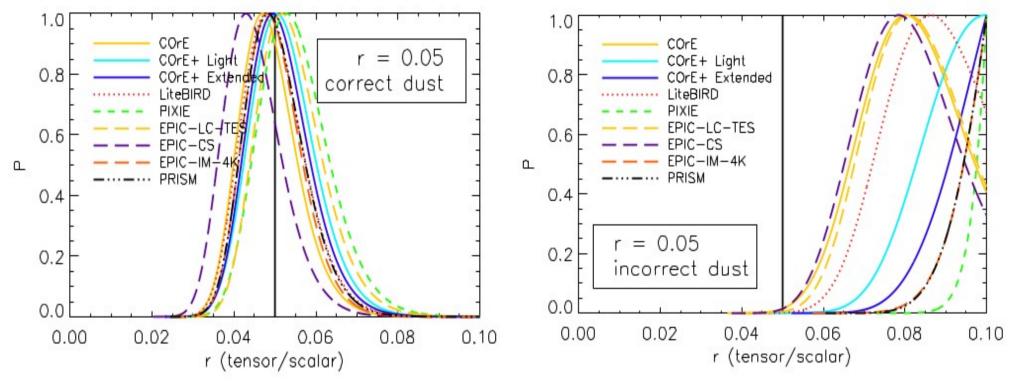


 $\mathcal{P}(r, A_{lens}) \approx \frac{1}{N} \sum_{i=1}^{N} \mathcal{L}\left[\widehat{C}_{\ell}^{i} | C_{\ell}^{th}(r, A_{lens})\right] \mathcal{P}^{prior}(A_{lens})$

Subtle issues on B-mode foregrounds

#1. Impact on r of foreground mismodelling

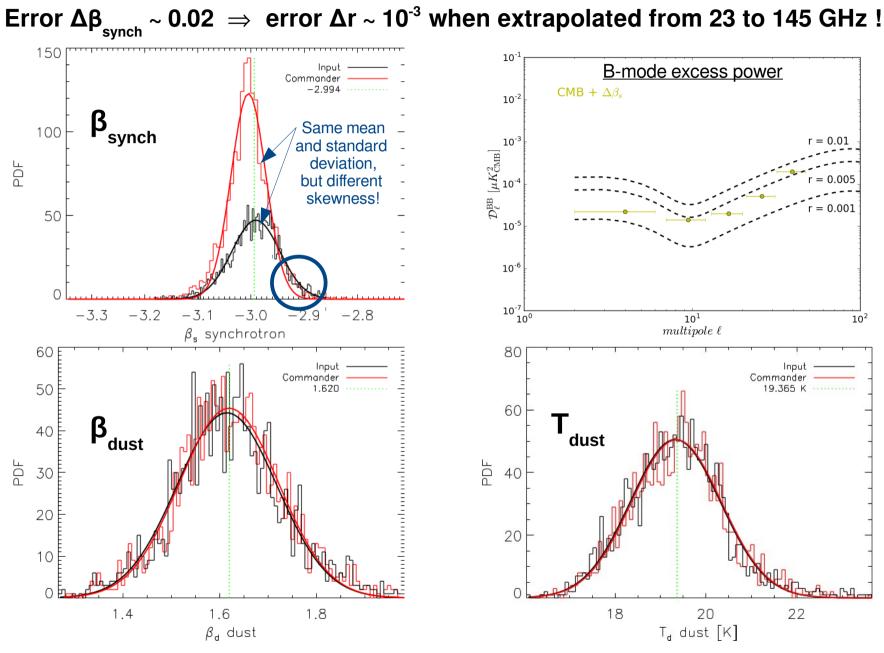




Remazeilles et al, MNRAS 2016

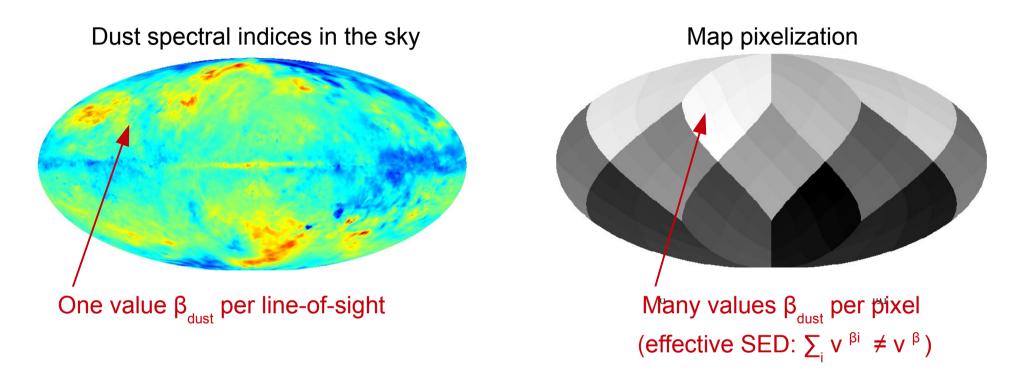
- How many dust components in the sky? But do we really care?
- Most important, what is the actual dust spectrum in the 70 140 GHz frequency range?
- Any extrapolation is obsolete because of decorrelation effects

#2. Lack of frequency range / sensitivity to β_s , T_d



Remazeilles et al, for the CORE collaboration, JCAP 2017

#3. Averaging effects of spectral indices within pixels / beams



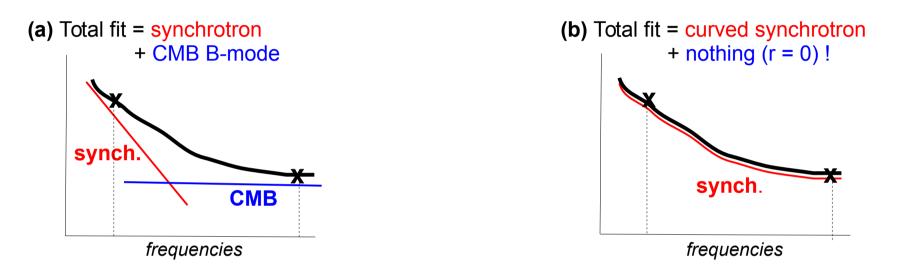
- Averaging / pixelization creates spurious curvatures on the foreground SED !
- The assumed SED might differ from the effective SED in the maps!
 - \rightarrow source of bias on r = 10⁻³ for parametric / template fitting methods
 - \rightarrow similar to decorrelation effects, but not physical

Chluba, Hill, Abitbol, 2017

Remazeilles et al 2017, for the CORE collaboration

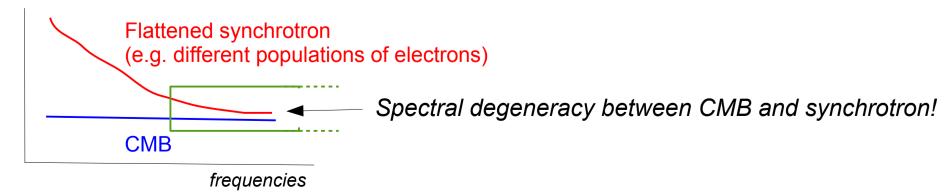
#4. Frequency range & spectral degeneracies

• A bias on r may result from a lack of frequency bands

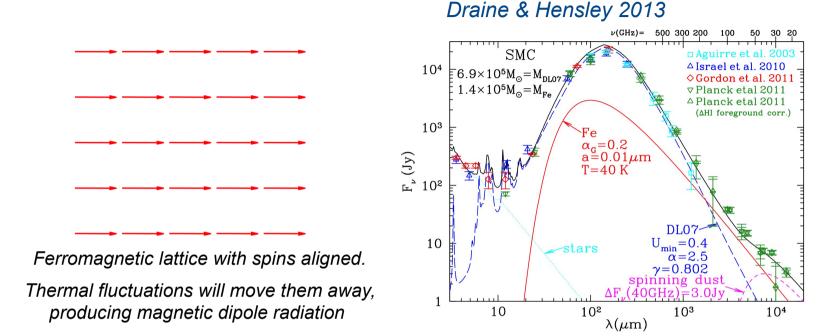


→ Same goodness-of-fit and no chi-square evidence for incorrect modelling!
→ Accurate fit of the total sky emission does not mean correct CMB fit!

• A bias on r may result from a limited frequency range



#5. What about magnetic dust (MD)?

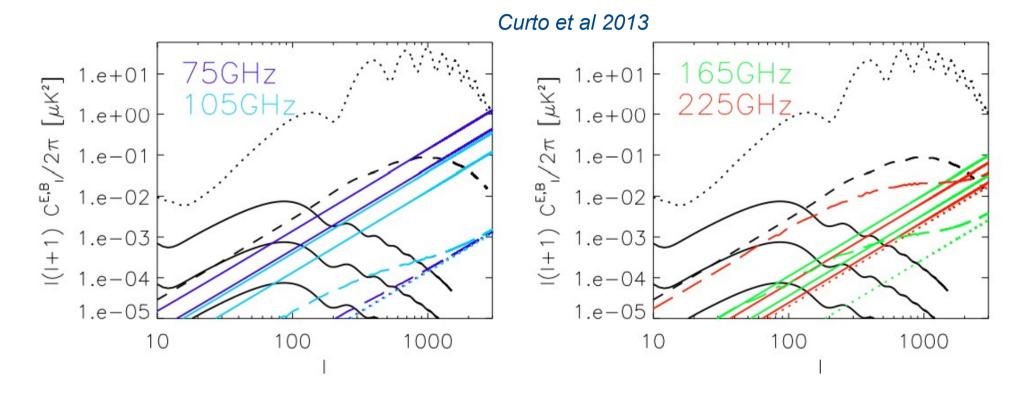


- Diffuse MD not yet observed!
- Theoretically, MD is <u>highly polarized</u> ~35%
- MD shows <u>spectral degeneracy with the CMB</u> around 100 GHz!

 \rightarrow can be a killer for component separation

#6. Extragalactic compact foregrounds

Polarized radio and IR compact sources at ~100 GHz dominate the primordial CMB B-mode at r = 10^{-3} on large angular scales $\ell \gtrsim 50$!



- Detect compact sources in intensity (easier), mask the relevant ones in polarization?
- "Inpainting" of sources in frequency maps prior to component separation?

A few remarks

To claim for a robust detection of the primordial B-mode, we will need:

- → to recover the reionization (I ~ 12) and the recombination (I ~ 100) peaks in order to recognize false detections due to power spectra degeneracies between CMB and foreground residuals
- \rightarrow to check that the recovered signal is stable when varying the Galactic masking and / or the set of frequency channels
- → to get consistent results between independent component separation techniques (parametric and blind)

How to deal with foreground complexity?

- → On a limited frequency range, we have a lack of data points to constrain the dust temperature T_{dust} at the required precision for $\sigma(r) < 10^{-3}$
- \rightarrow This translates into a bias on the CMB B-mode by extrapolation
- → So can we get more precision by fitting a dust <u>curvature</u> (local) instead of a dust <u>temperature</u> (non-local) on a limited frequency range, without lack of <u>accuracy</u>?