



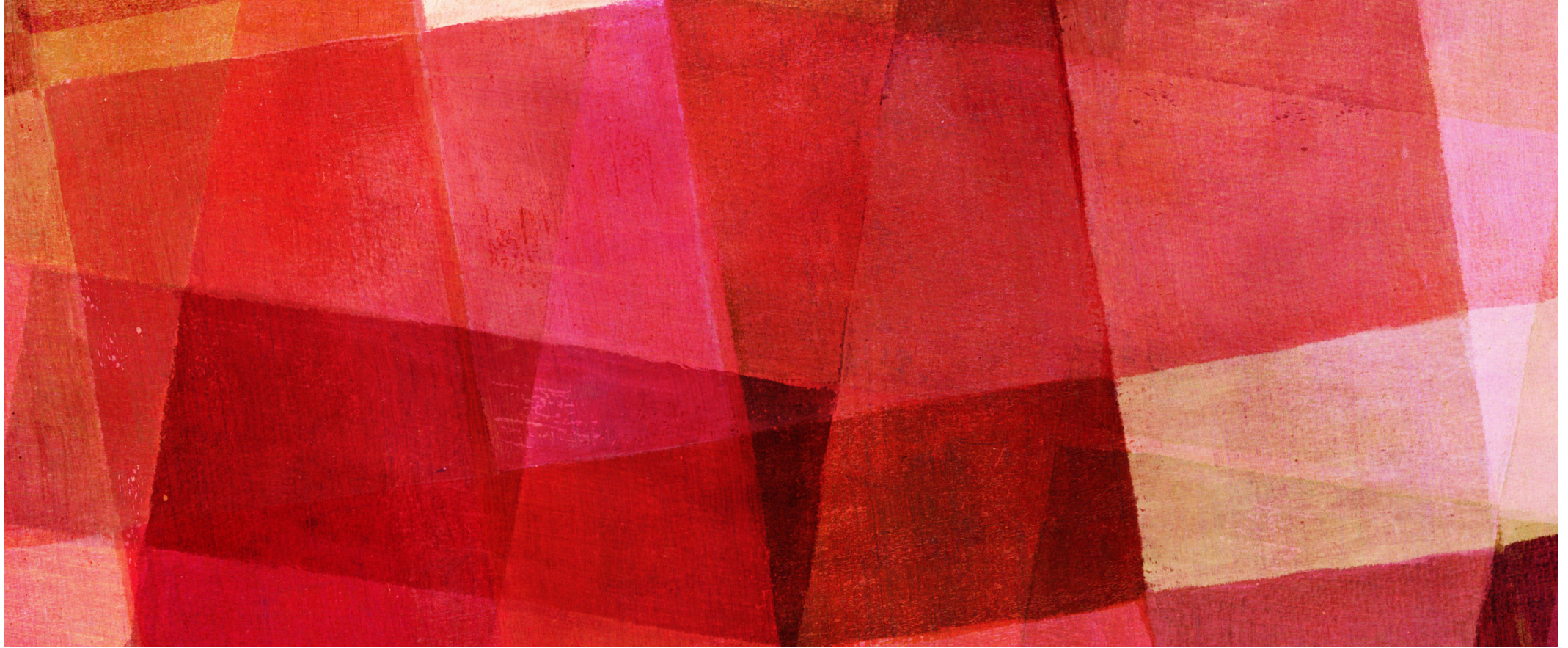
# Nonlinear Reconstruction

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*Yu Yu (余瑜), Shanghai Jiao Tong University  
06 Mar 2019@YITP, Kyoto*







# Nonlinear Reconstruction

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*Collaborate with Hong-Ming Zhu (Berkeley),  
Ue-Li Pen, Xin Wang (CITA)*



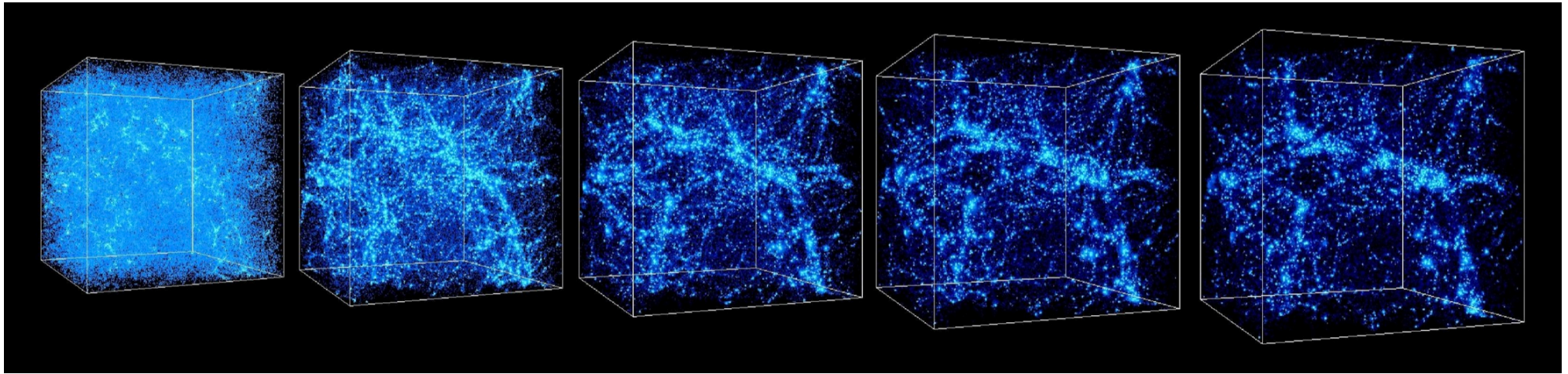


# Outline

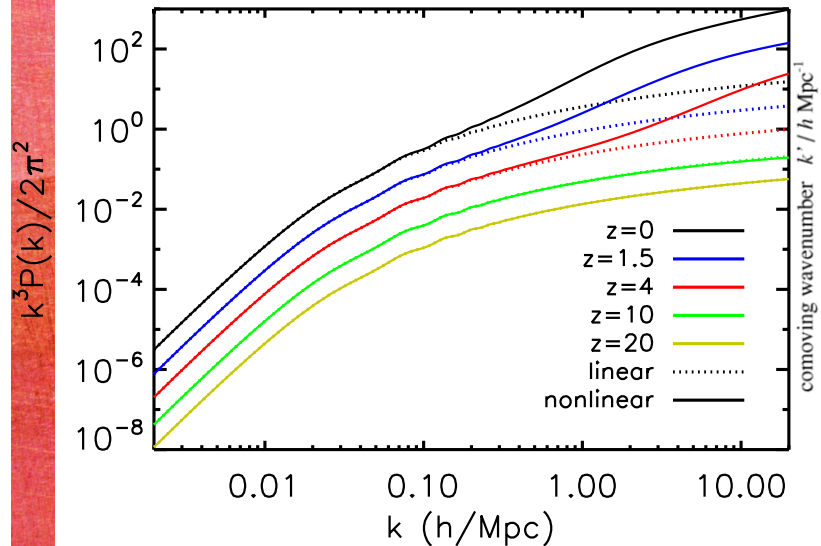
---

- Nonlinear evolution and standard reconstruction
- New reconstruction and performance
- Reconstruction with RSD effect
- In progress
- Conclusion

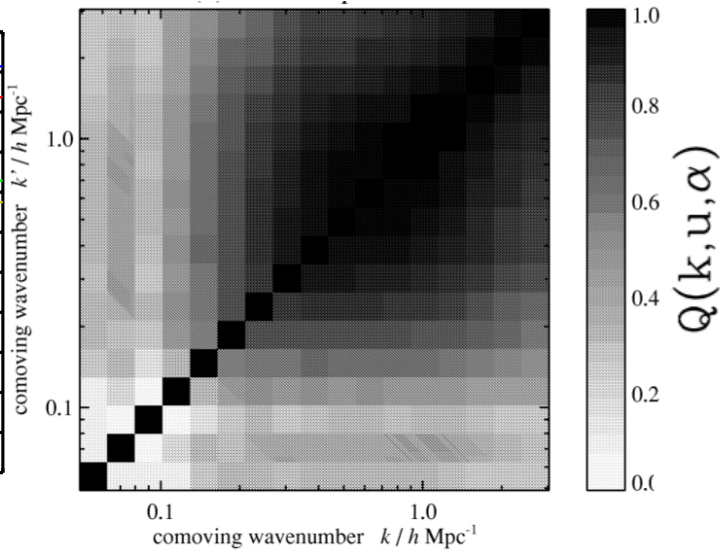
# Nonlinear evolution



*Boosted small scale power*

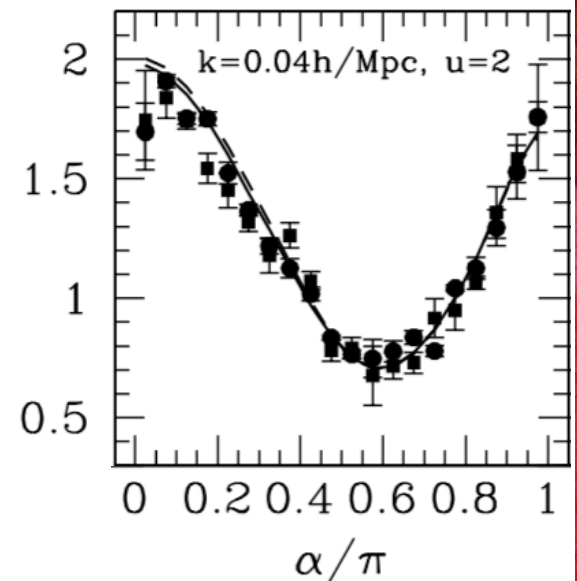


*correlation between scales*



Rimes & Hamilton 2005

*high-order statistics*

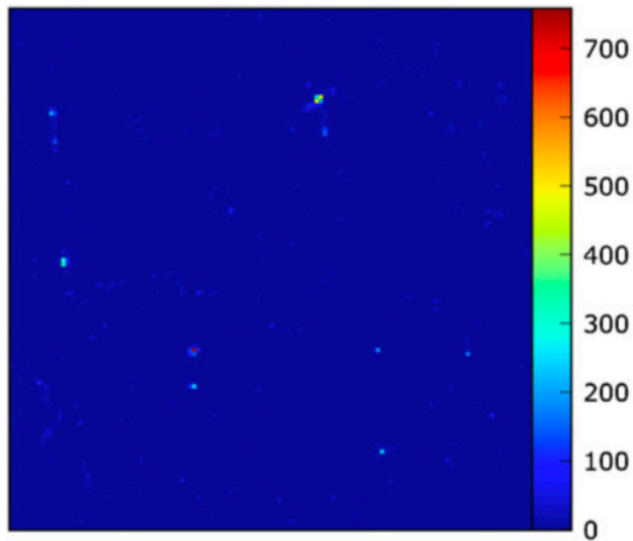


Guo & Jing 2009

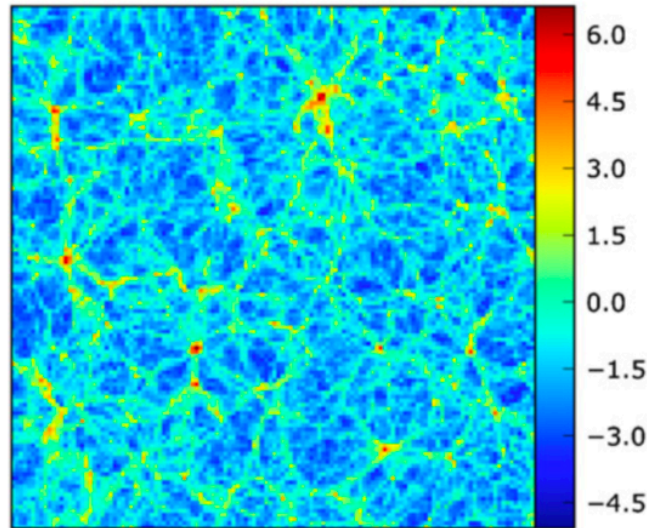


# Local transform helps

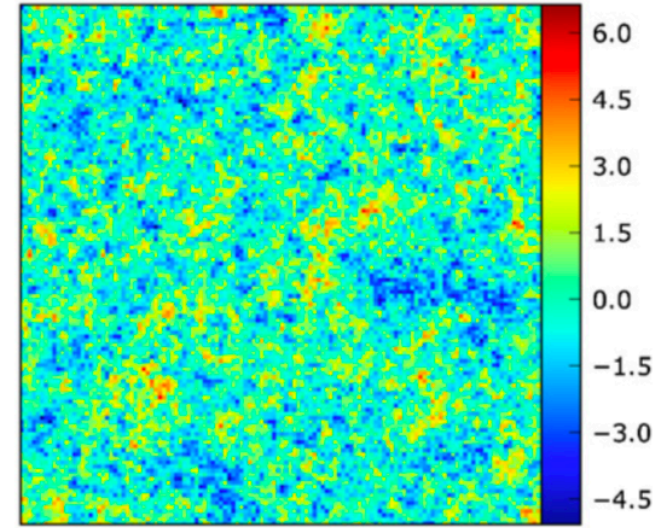
---



$\delta$



$\log(1 + \delta)$



$\delta_{\text{init}}$

Local transforms are

- Useful in analysis
- Useful in producing mocks (LogN)
- **Useless** in recovering the early state

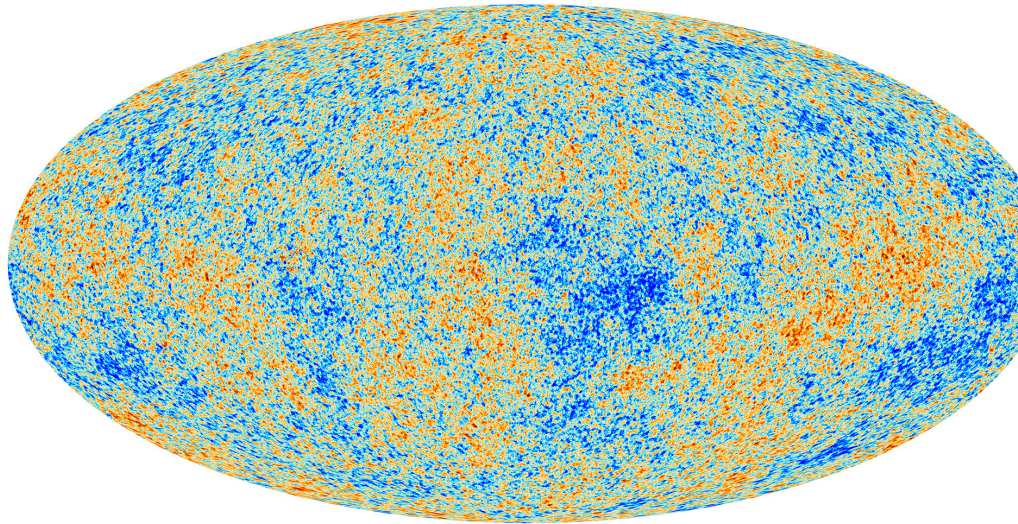
*For weak lensing*

*Yu et al. 2011, 2012*

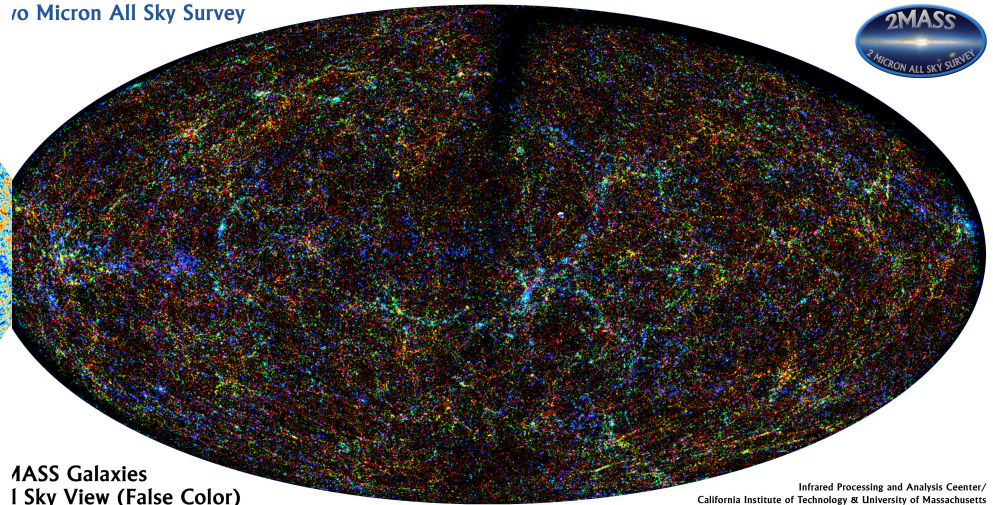
*Yu et al. 2015*



# Nonlinear evolution

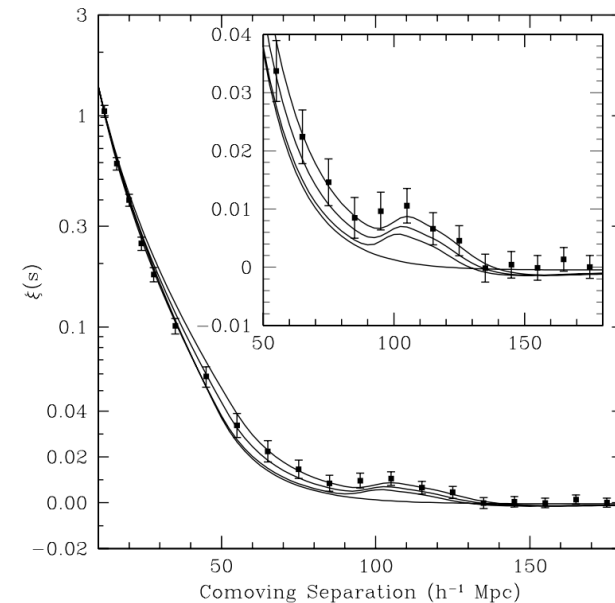
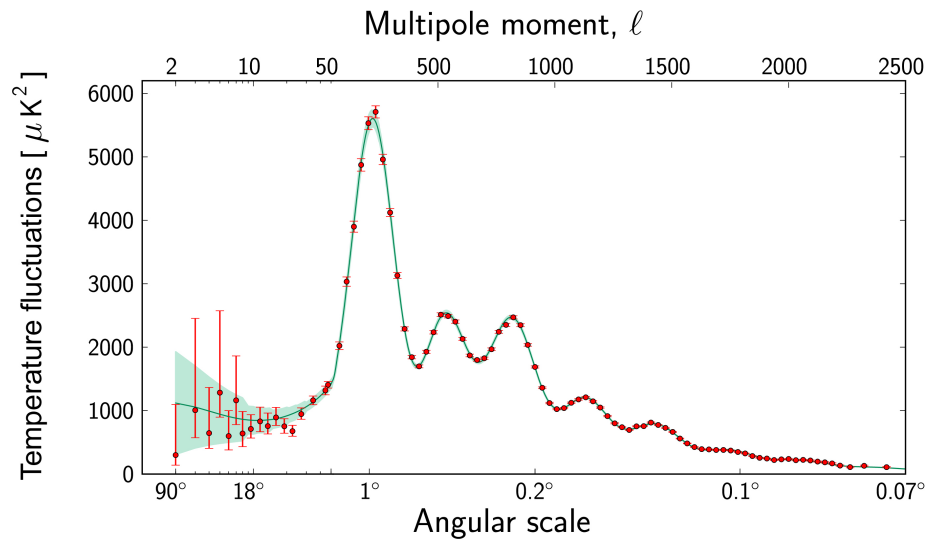


10 Micron All Sky Survey



2MASS Galaxies  
All Sky View (False Color)

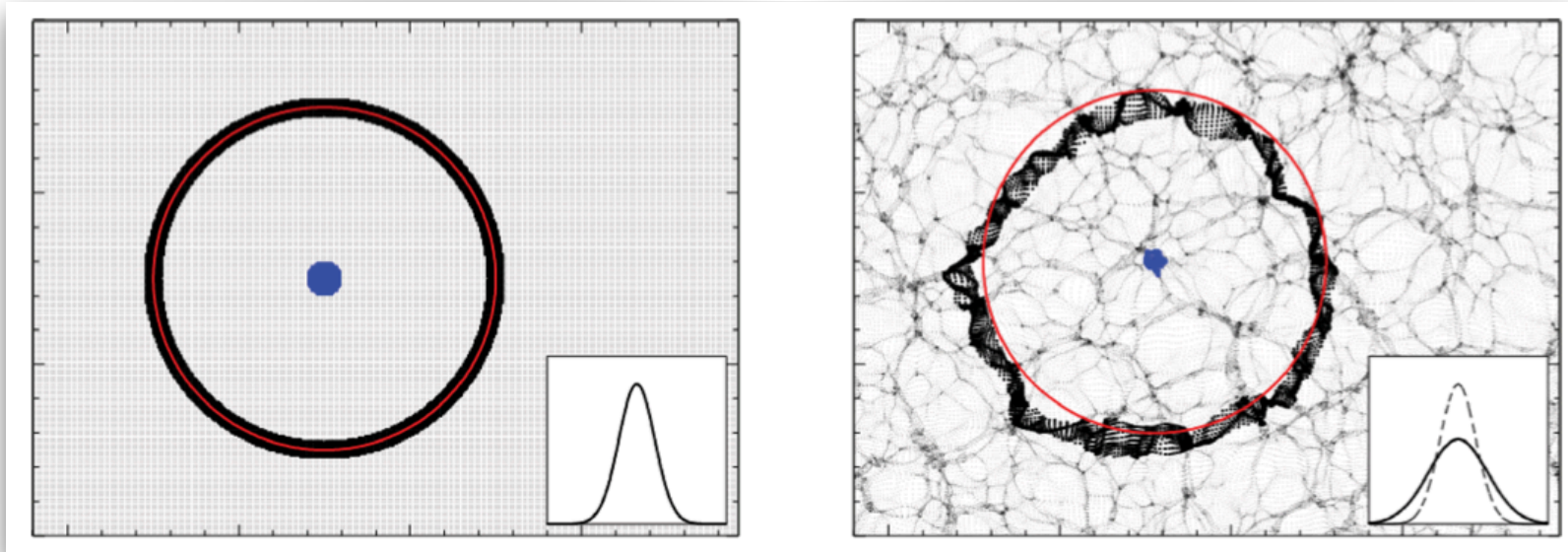
Infrared Processing and Analysis Center/  
California Institute of Technology & University of Massachusetts





# Baryon Acoustic Oscillation

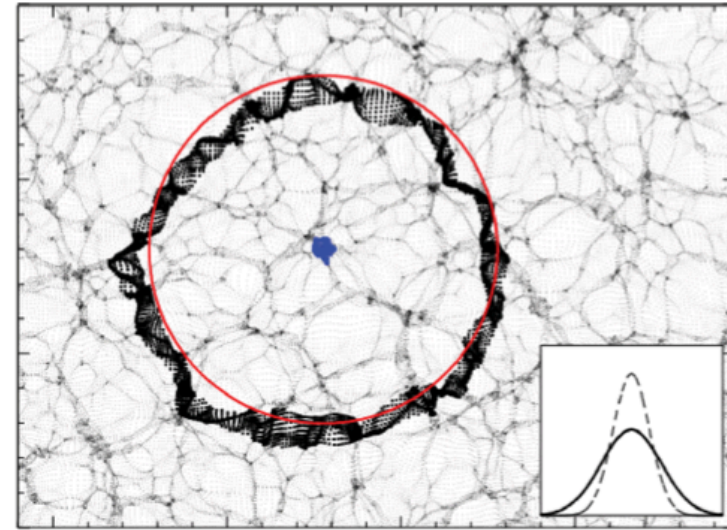
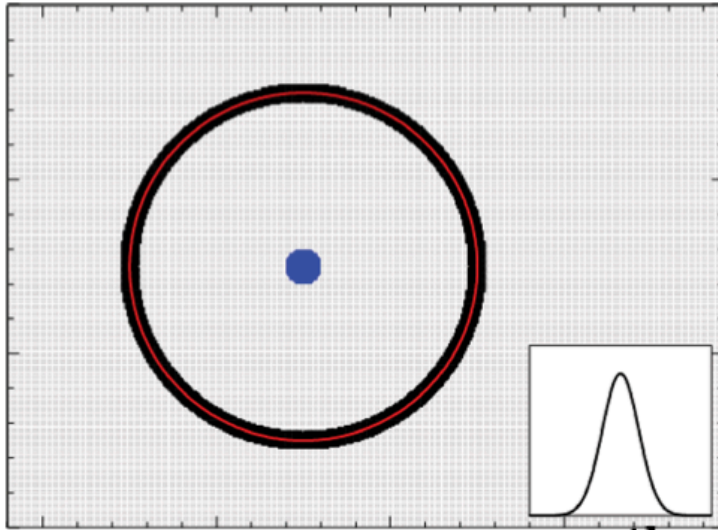
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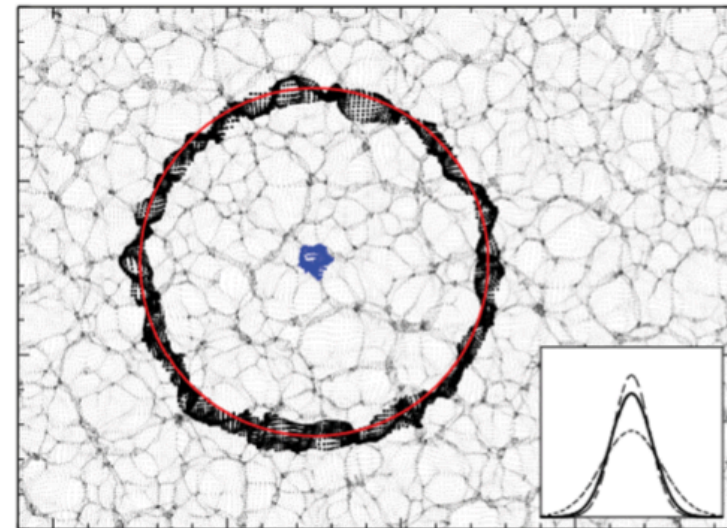
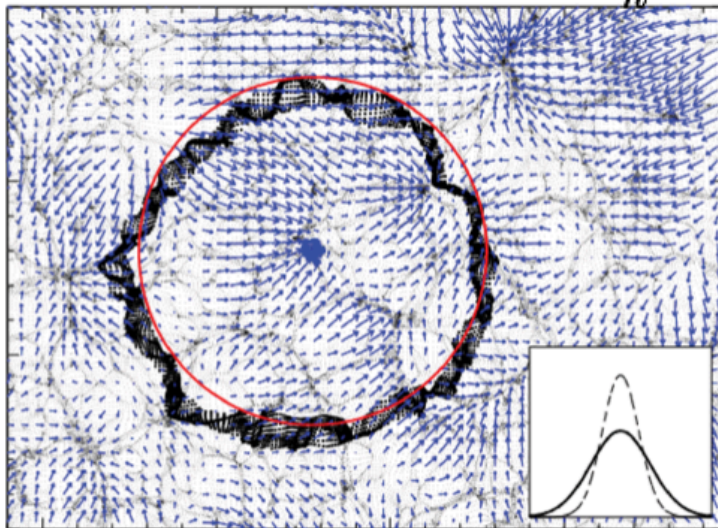
- bulk motion
- redshift space distortion
- nonlinear growth



# Standard BAO reconstruction



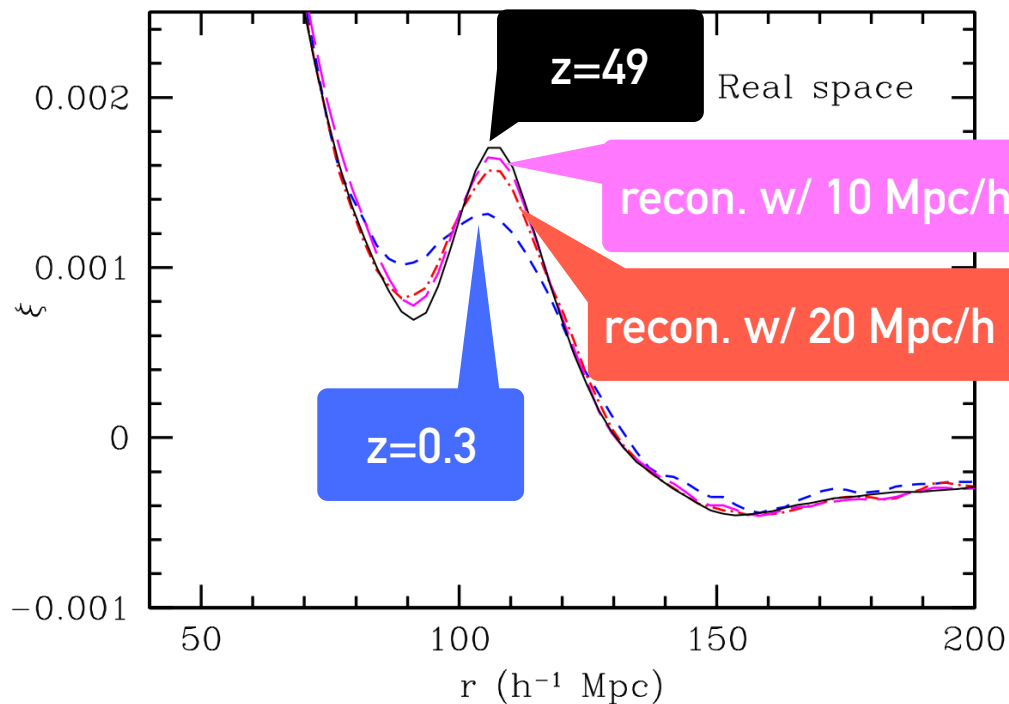
linear continuity equation  $s(\mathbf{k}) = -\frac{i\mathbf{k}}{k^2} S(k) \delta(k)$





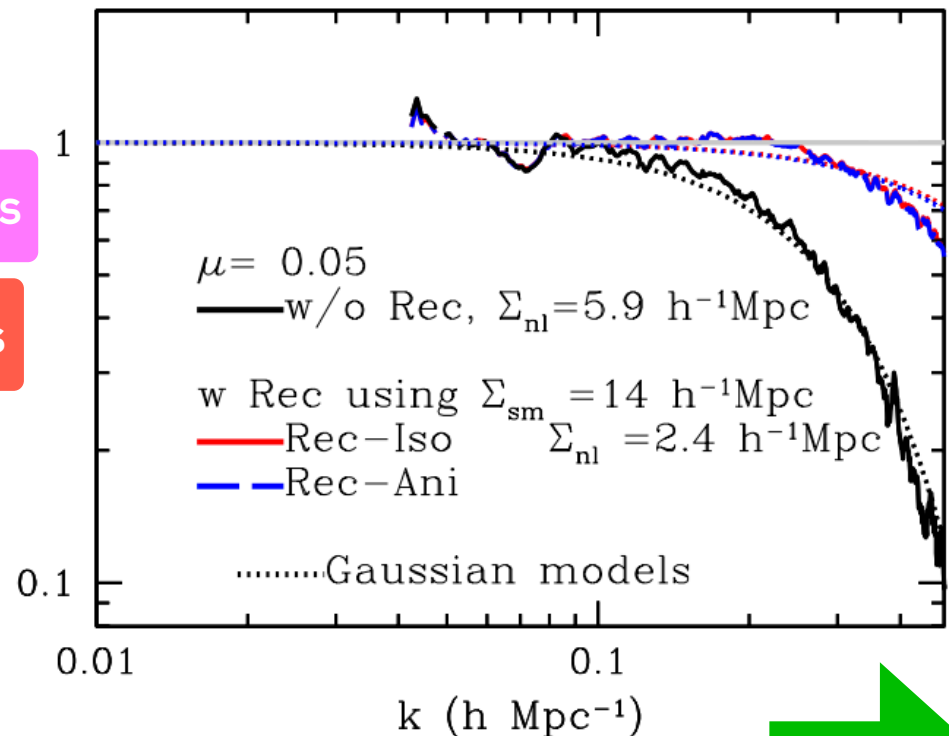
# Standard BAO reconstruction

- Sharper peak / weaker damping

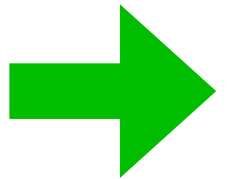


Eisenstein+ 2007

$$P(k) = D^2(k)P_L(k) + N(k)$$



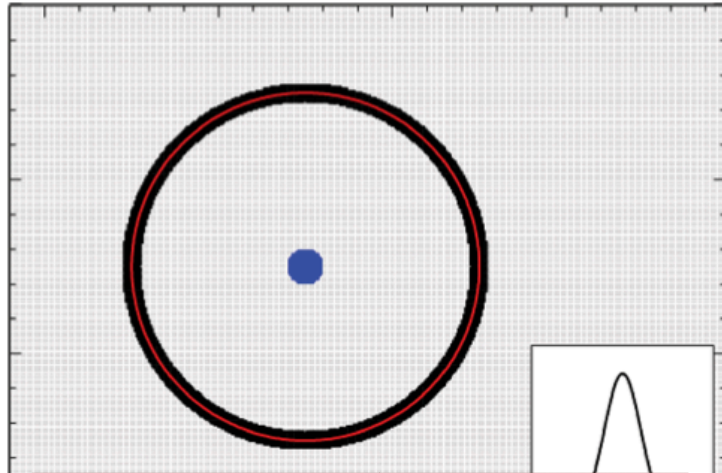
Seo+ 2016



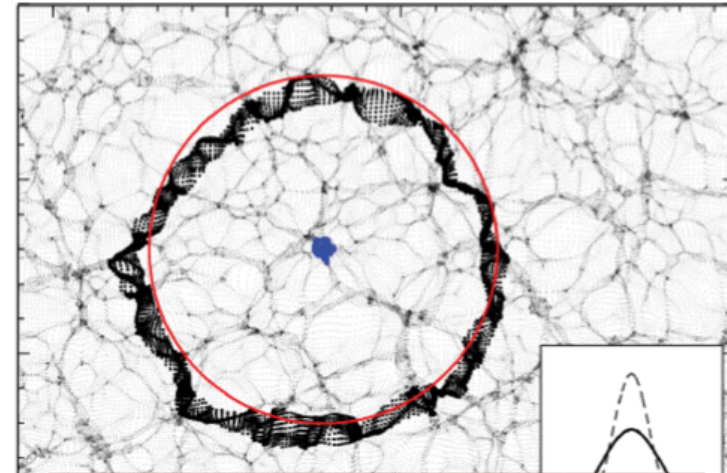
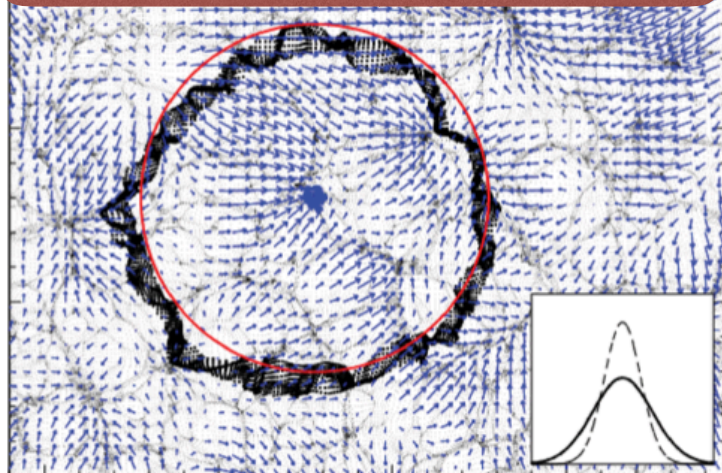


# Standard BAO reconstruction

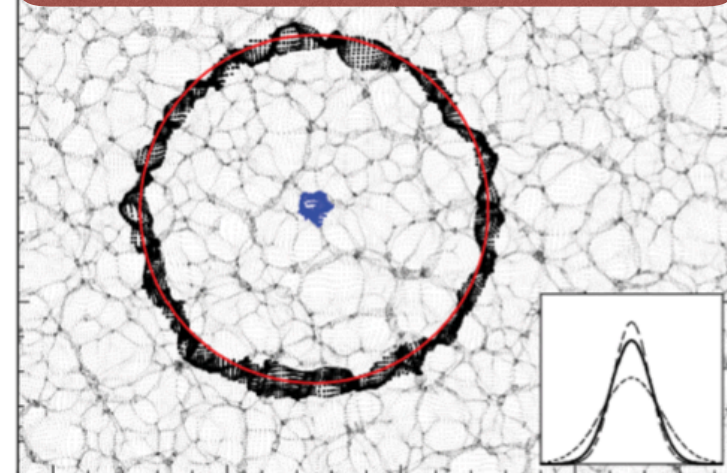
---



heavy smooth to validate the linear continuity equation



Linear displacement





# Outline

---

- Nonlinear evolution and standard reconstruction
- New reconstruction and performance
- Reconstruction with RSD effect
- In progress
- Conclusion



# NEW reconstruction method

---

- The initial condition of our Universe is homogeneous, isotropic, and **UNIFORM** ( $\sim 10^{-5}$  at  $z=1100$ ).
- How about solving for a curvilinear coordinate, in which the mass per grid is constant.

$$\rho(\boldsymbol{x}) \quad \rho(\boldsymbol{\xi}) d^3 \boldsymbol{\xi} = \text{constant}$$



# NEW reconstruction method

- solve for a curvilinear coordinate, in which the mass per grid is constant.



# Algorithm

---

- Originally used in moving mesh simulation (N-body and hydrodynamic; see Pen 1995 & 1998)
    - solve for a mesh **following** the nonlinear density evolution **at each time step**
    - to keep (approximately) constant mass/energy resolution
- 
- In our case, we need solve for a mesh consistent with the **highly** nonlinear density field, **perturbatively and iteratively**.
  - POTENTIAL ISOBARIC GAUGE/COORDINATE



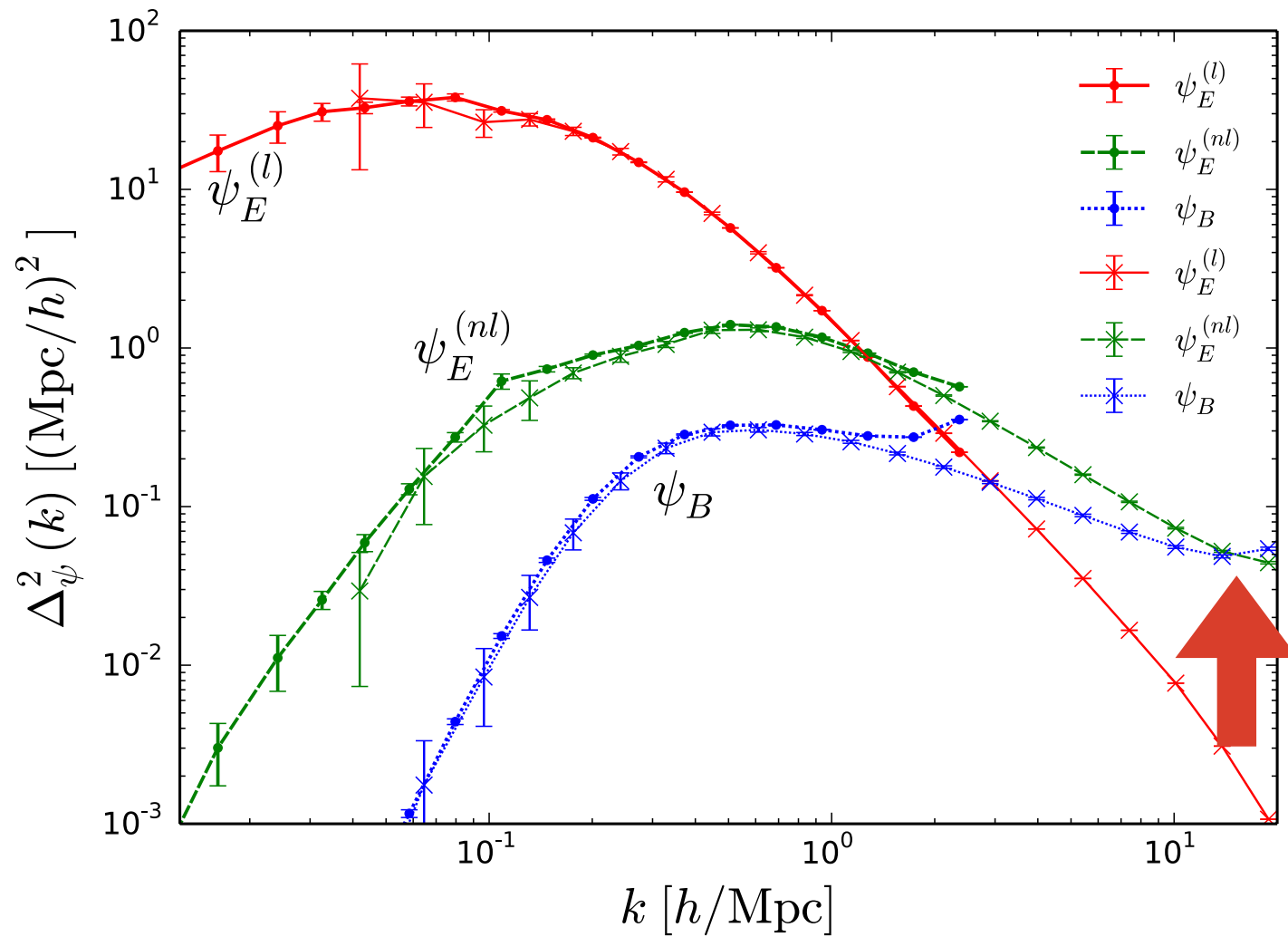
# NEW reconstruction method

- Provide us an estimate of the E-mode displacement.

$$x = q + \Psi(q)$$



# Displacement components



$$\psi = \psi_E^L + \psi_E^{\text{NL}} + \psi_B$$



# Definition

---

Reconstructed density field

$$\delta_R = -\nabla \cdot \Psi_R$$

Linear density field

$$\delta_L$$

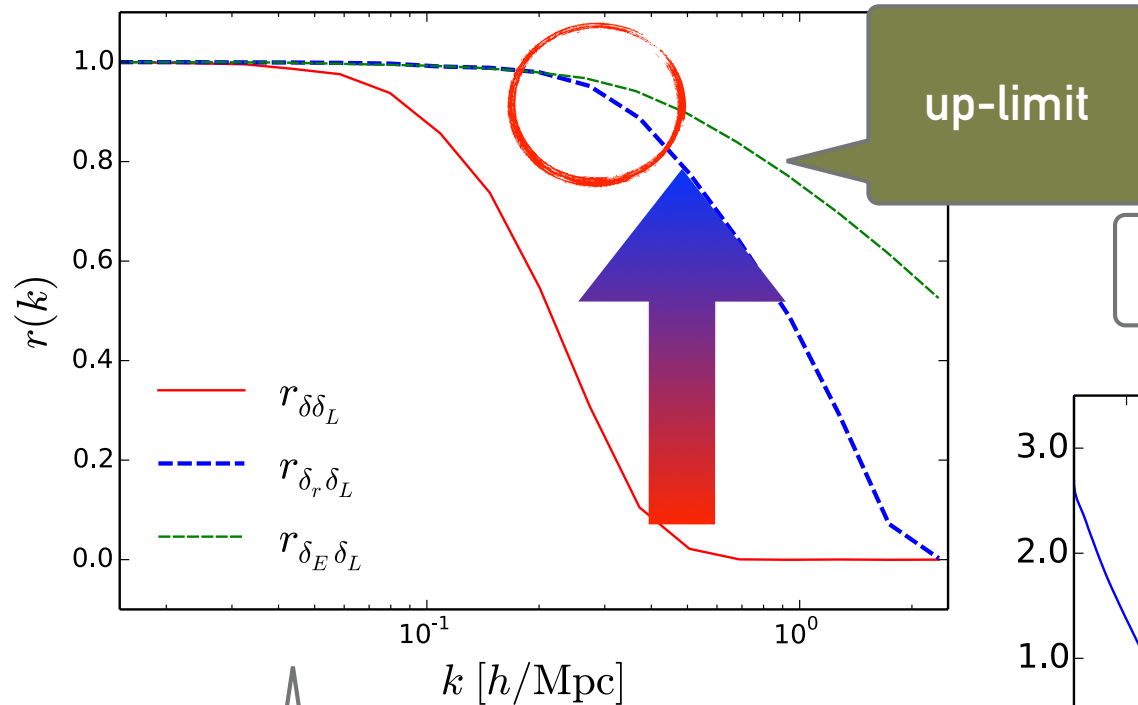
Reconstruction by real displacement

$$\delta_E = -\nabla \cdot \Psi_E$$

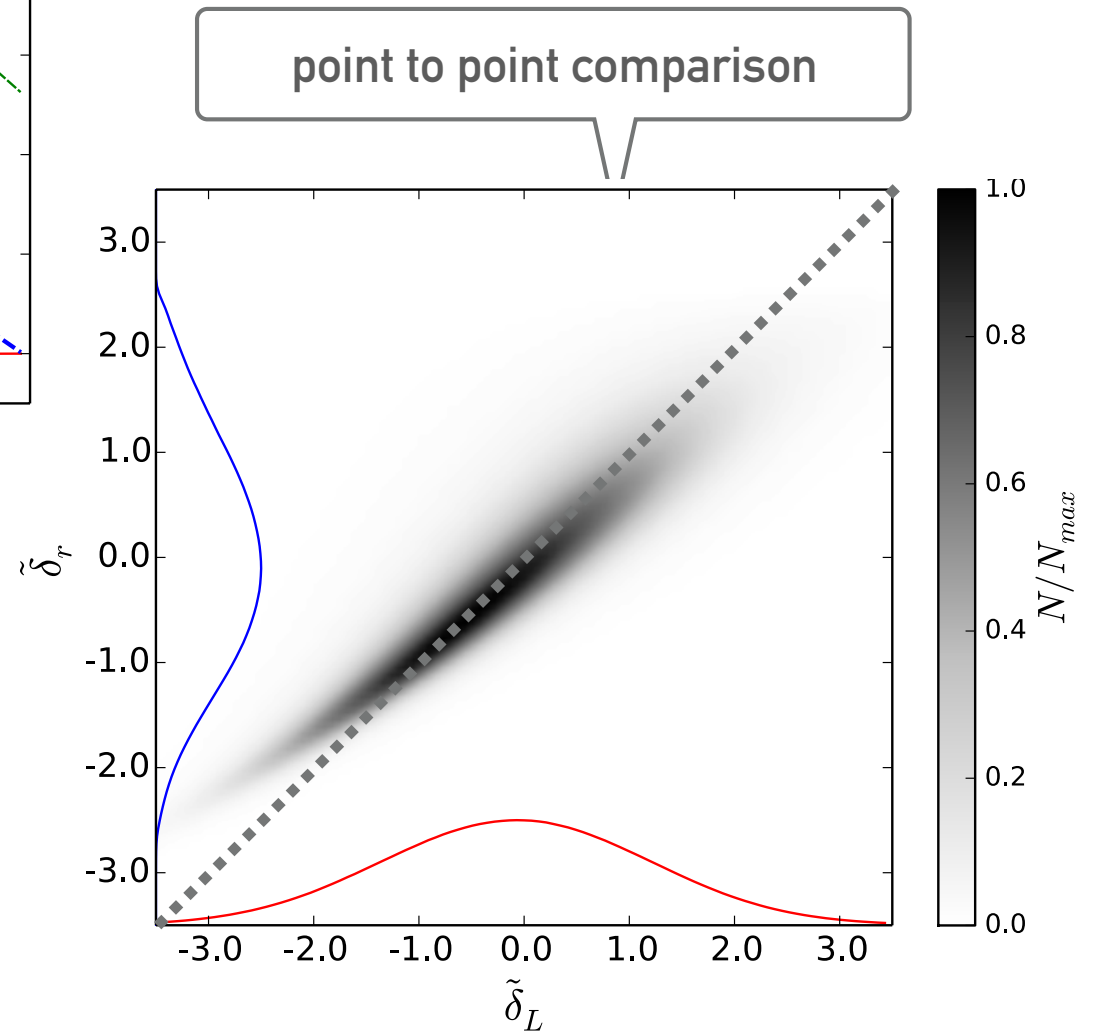


# Correlation with initial condition

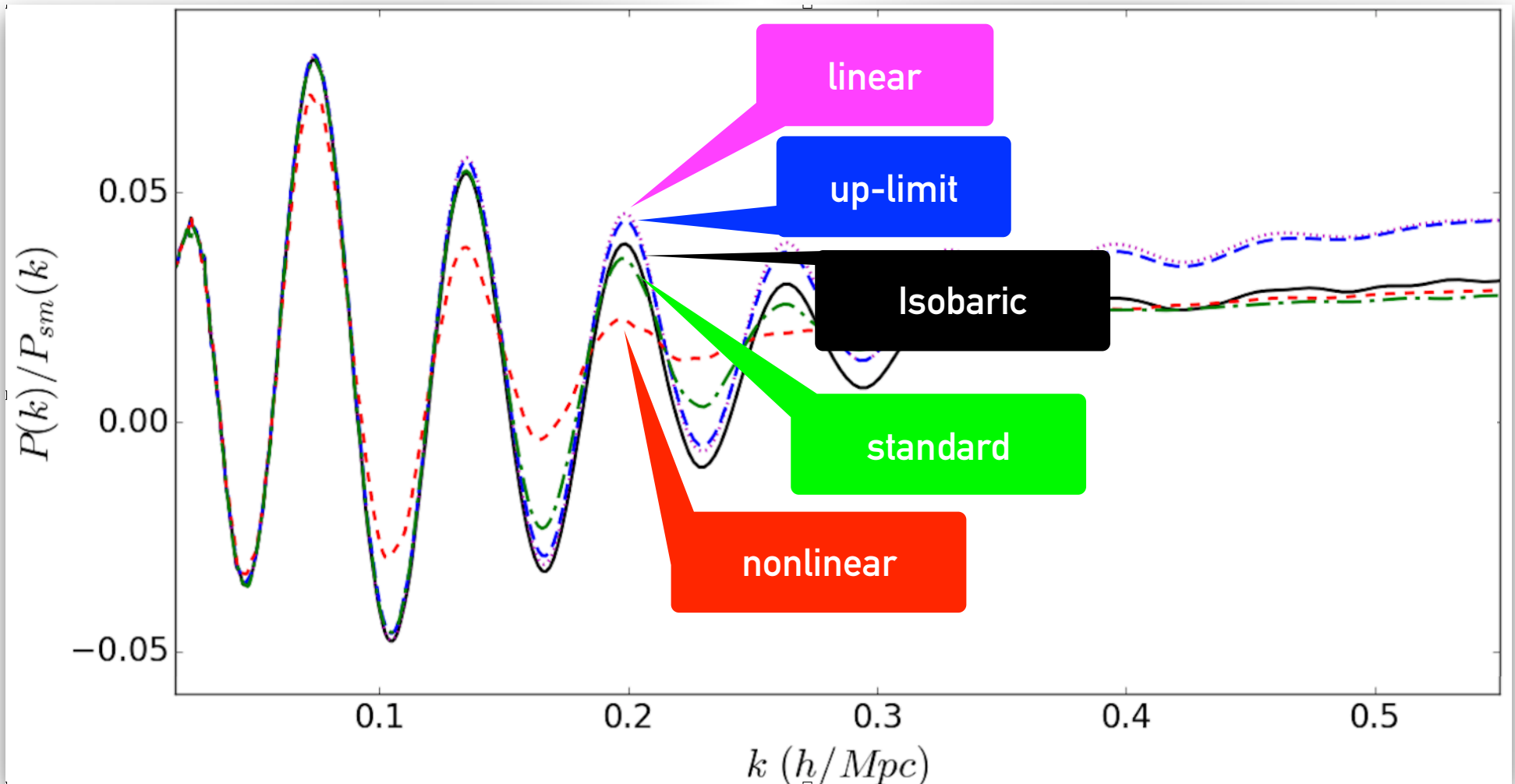
Zhu, YU and Pen (2016)



Cross-correlation coefficient

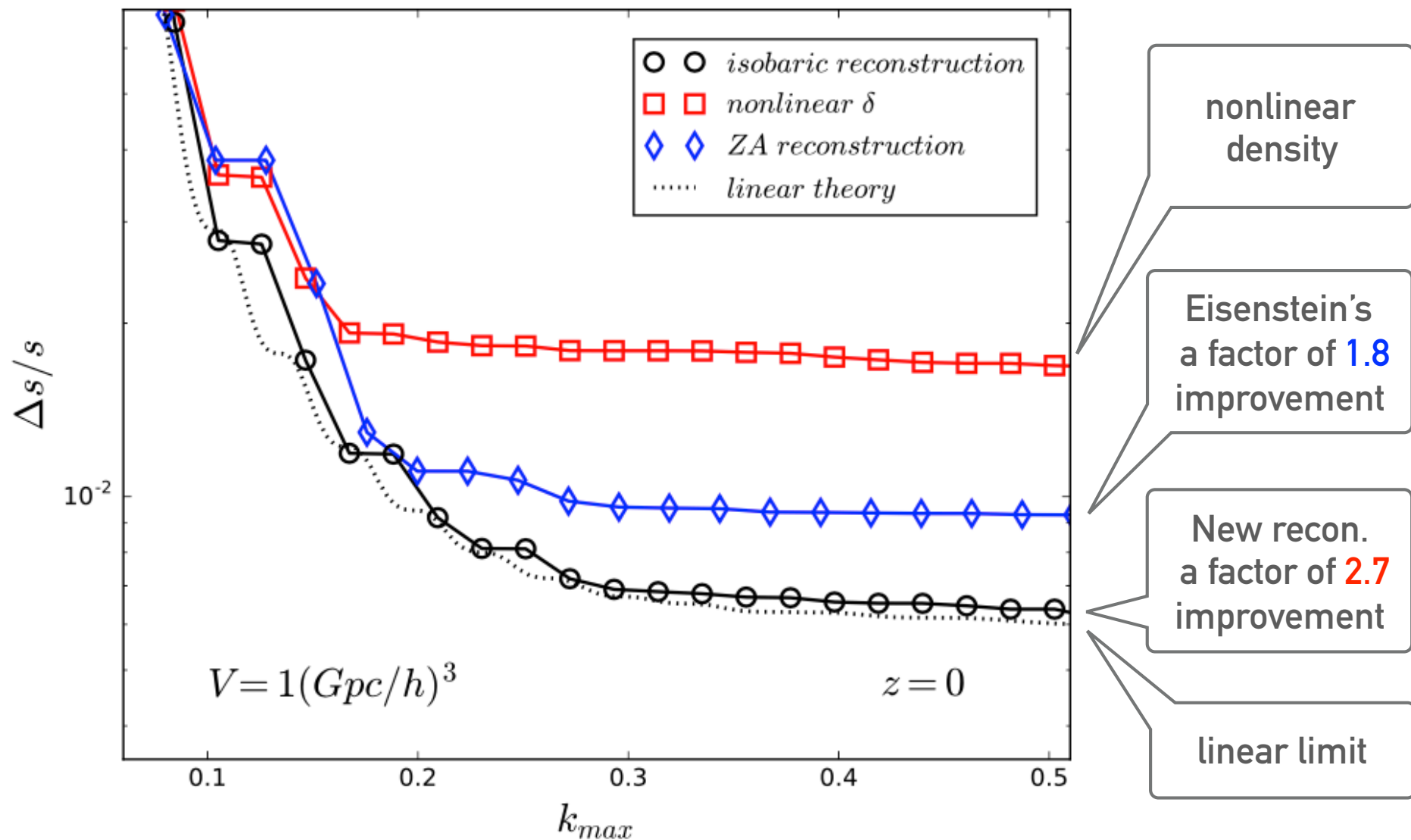


# Acoustic peak recovery

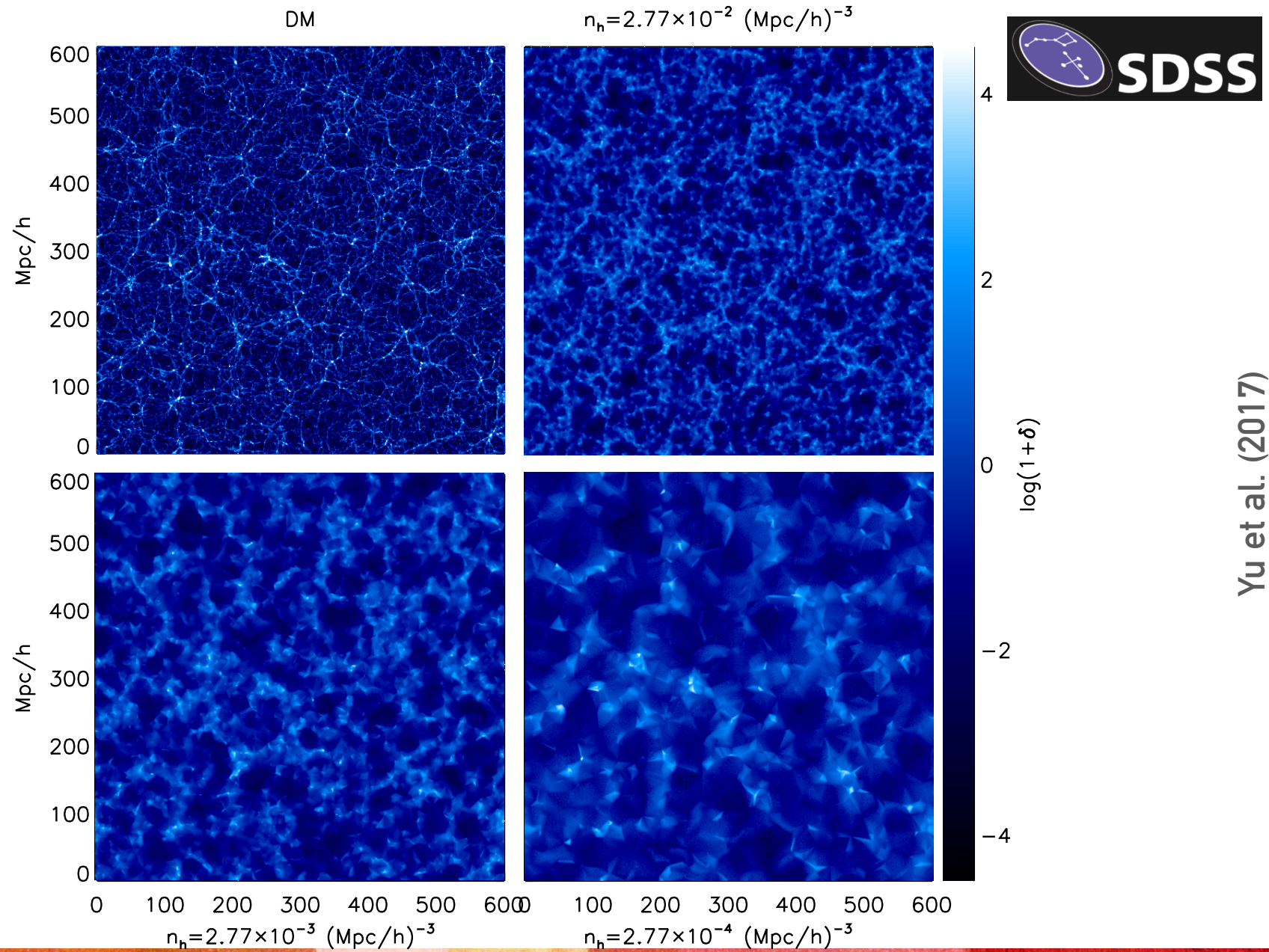




# Fractional error on the distance measurement

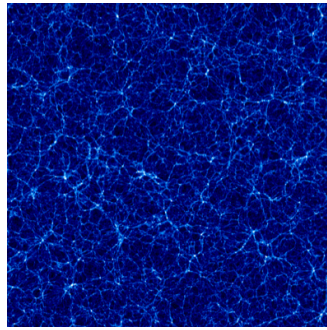


# Halo fields

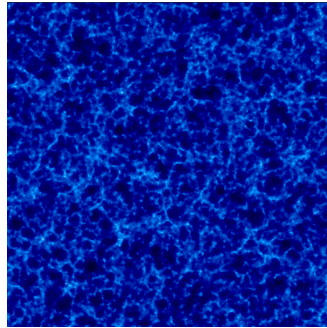




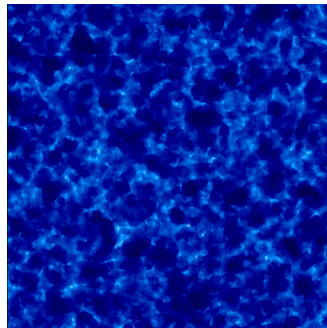
dark matter



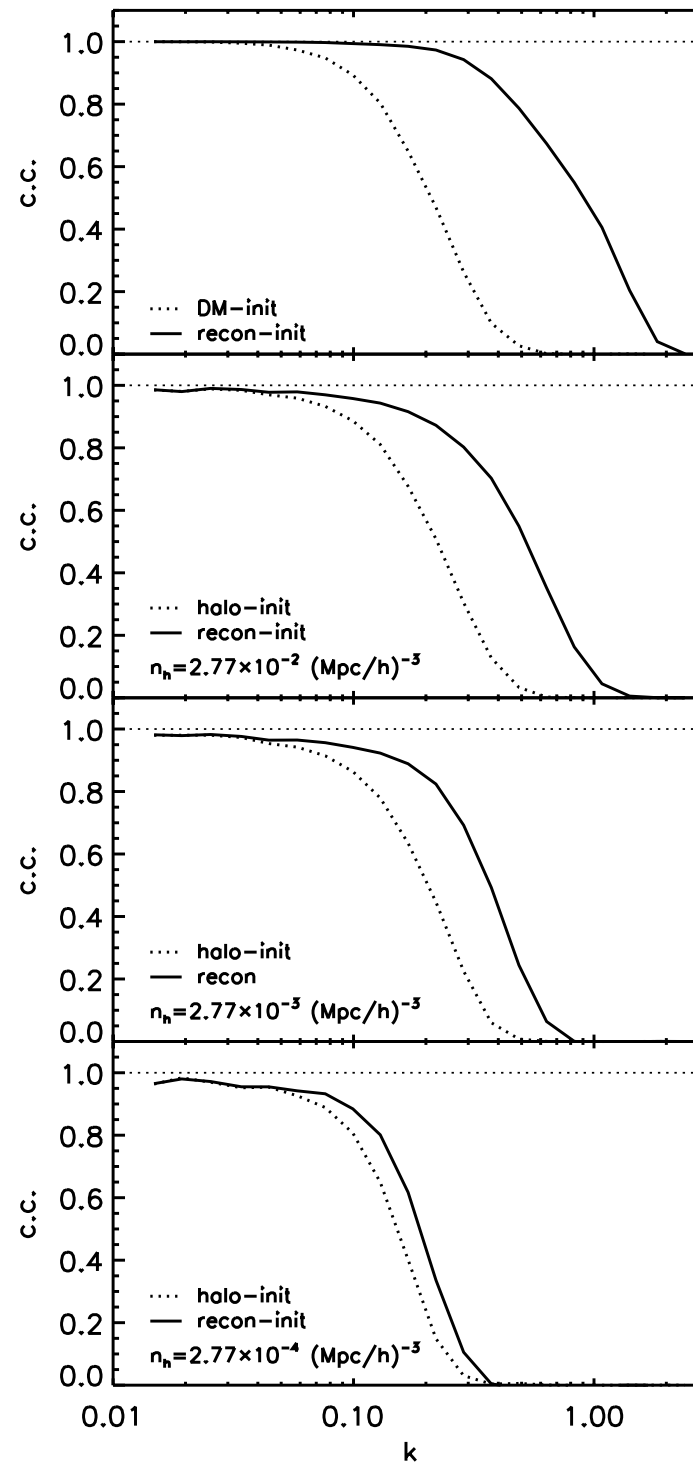
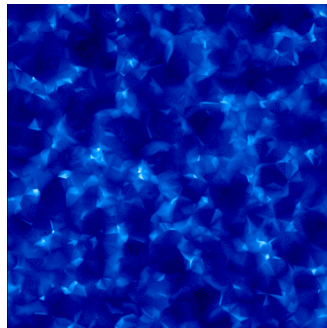
$$n_h = 2.77 \times 10^{-2} \text{ (h/Mpc)}^3$$



$$n_h = 2.77 \times 10^{-3} \text{ (h/Mpc)}^3$$



$$n_h = 2.77 \times 10^{-4} \text{ (h/Mpc)}^3$$

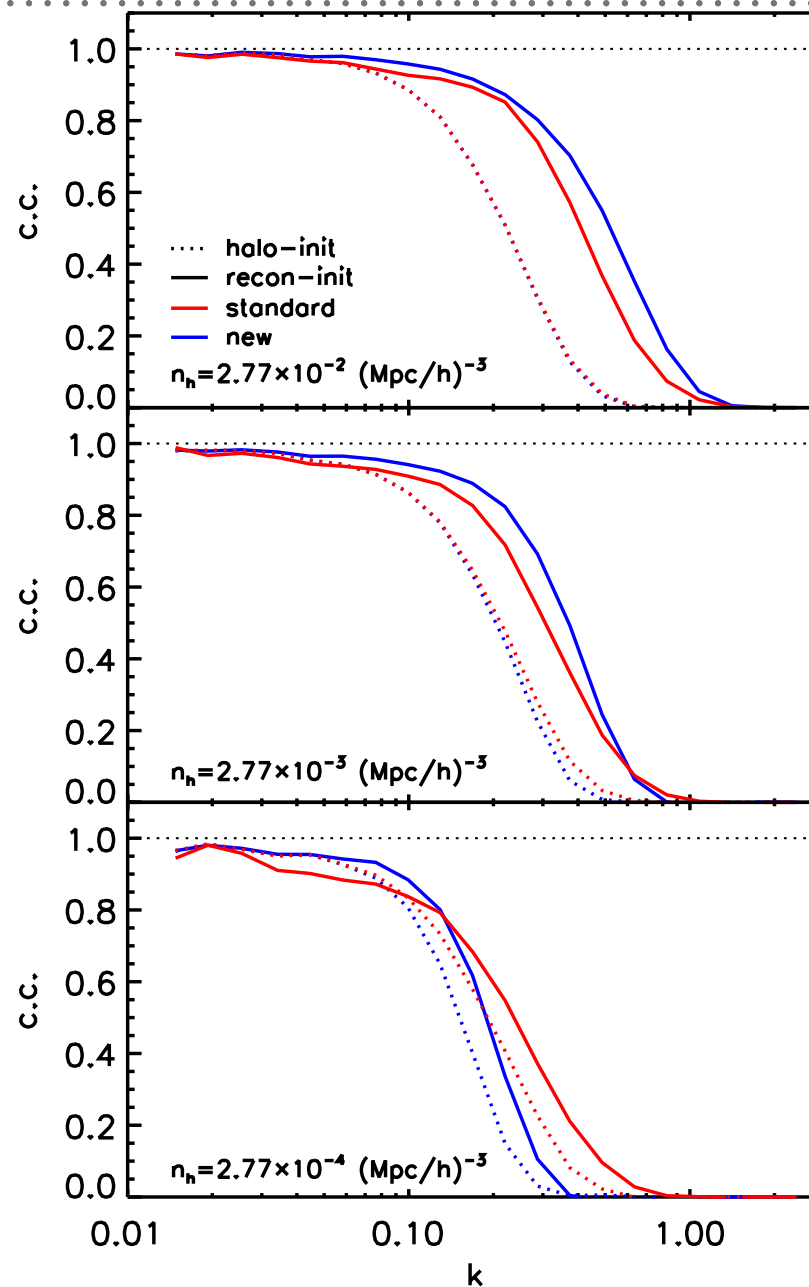


Cross-correlation coefficient



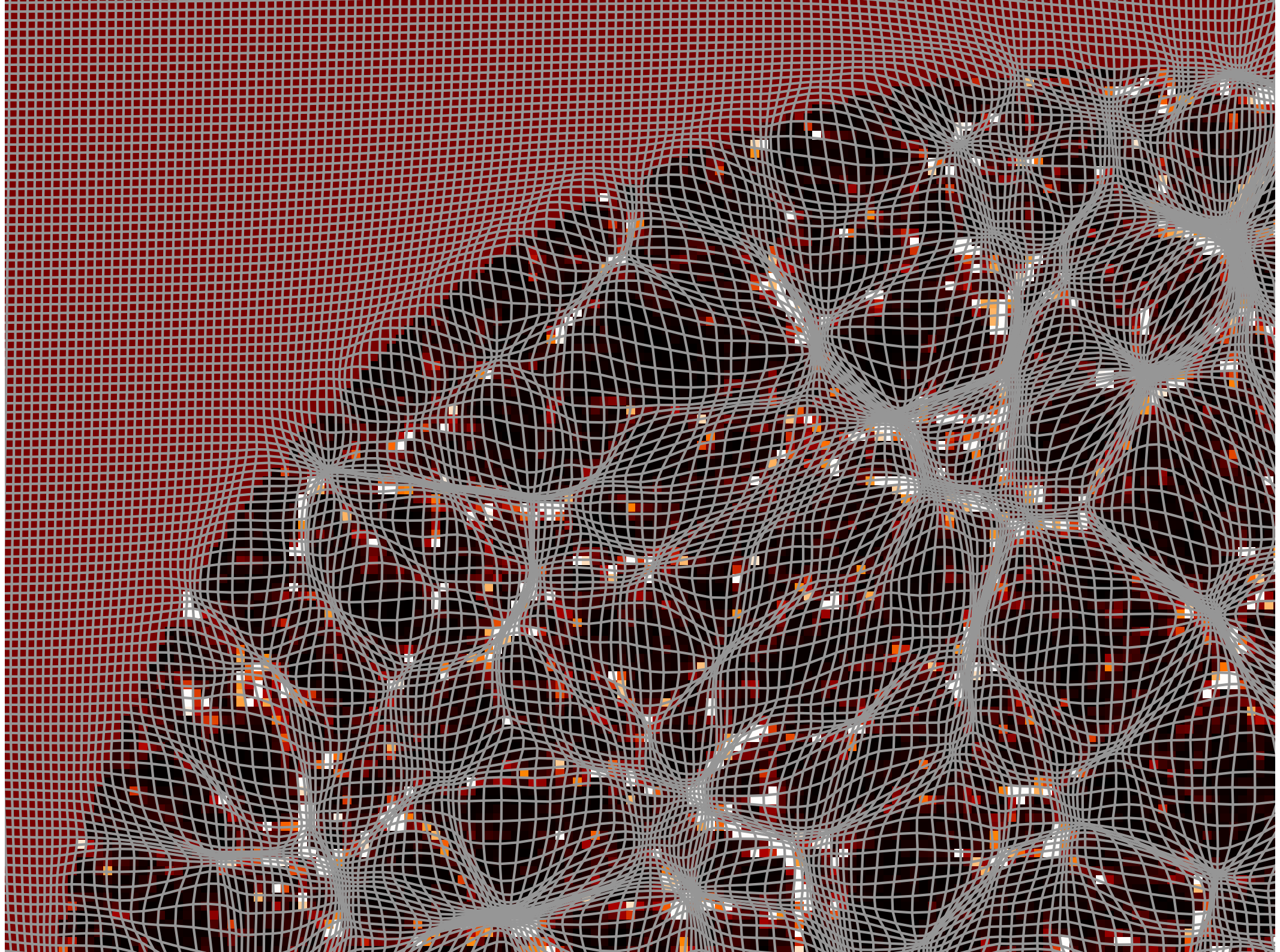
# v.s. standard reconstruction

- indeed outperform over the standard BAO reconstruction method for dense sample ( $n_g > 10^{-3} (\text{Mpc}/h)^{-3}$ ).



Yu et al. (2017)





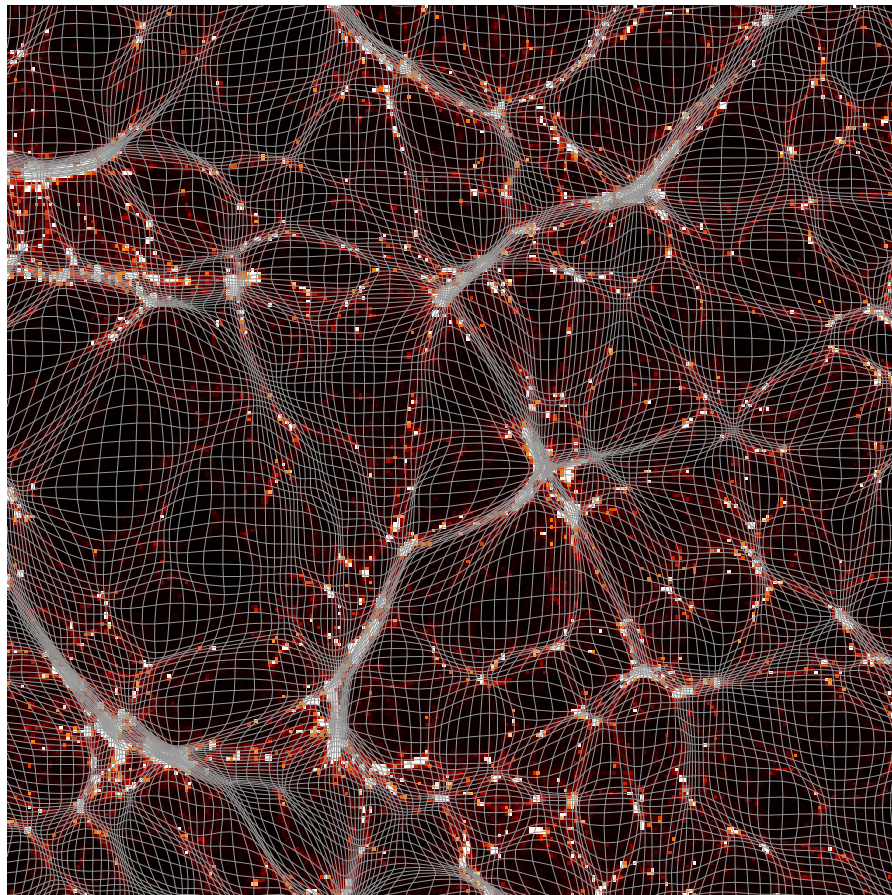
# Outline

---

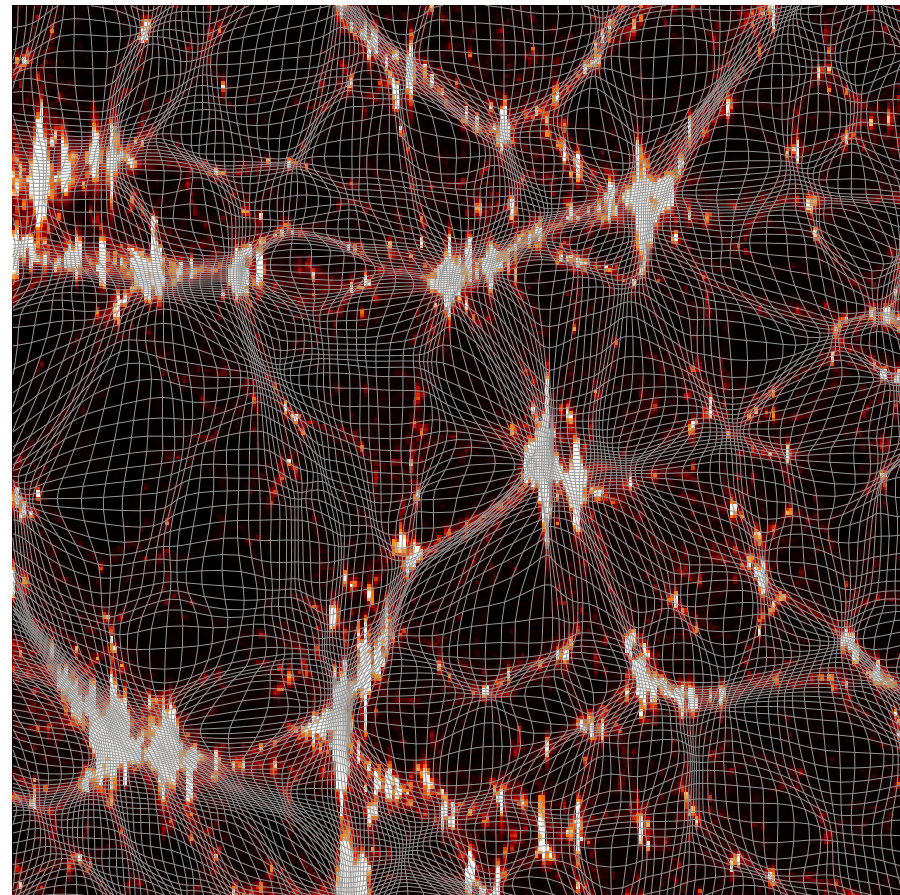
- Nonlinear evolution and standard reconstruction
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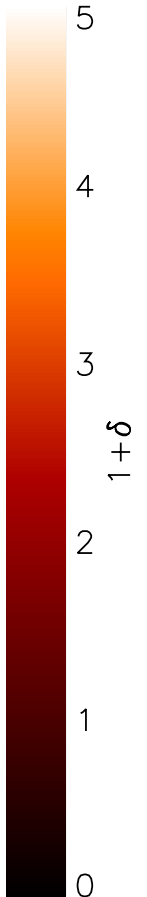
# Reconstruction with RSD



150 Mpc/h



150 Mpc/h



$$z^{\text{obs}} = z^{\text{hubble}} + z^{\text{pv}}$$

Algorithm works with RSD

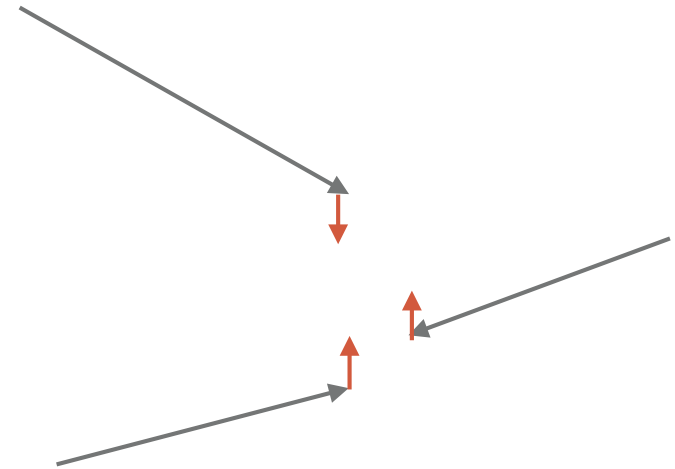


# Reconstruction with RSD

---

$$\vec{x}(t) = \vec{q} + \vec{\Psi}(\vec{q}, t)$$

$$\vec{x}(t) = \vec{q} + \boxed{\vec{\Psi}(\vec{q}, t) + v_z \vec{z} / aH}$$

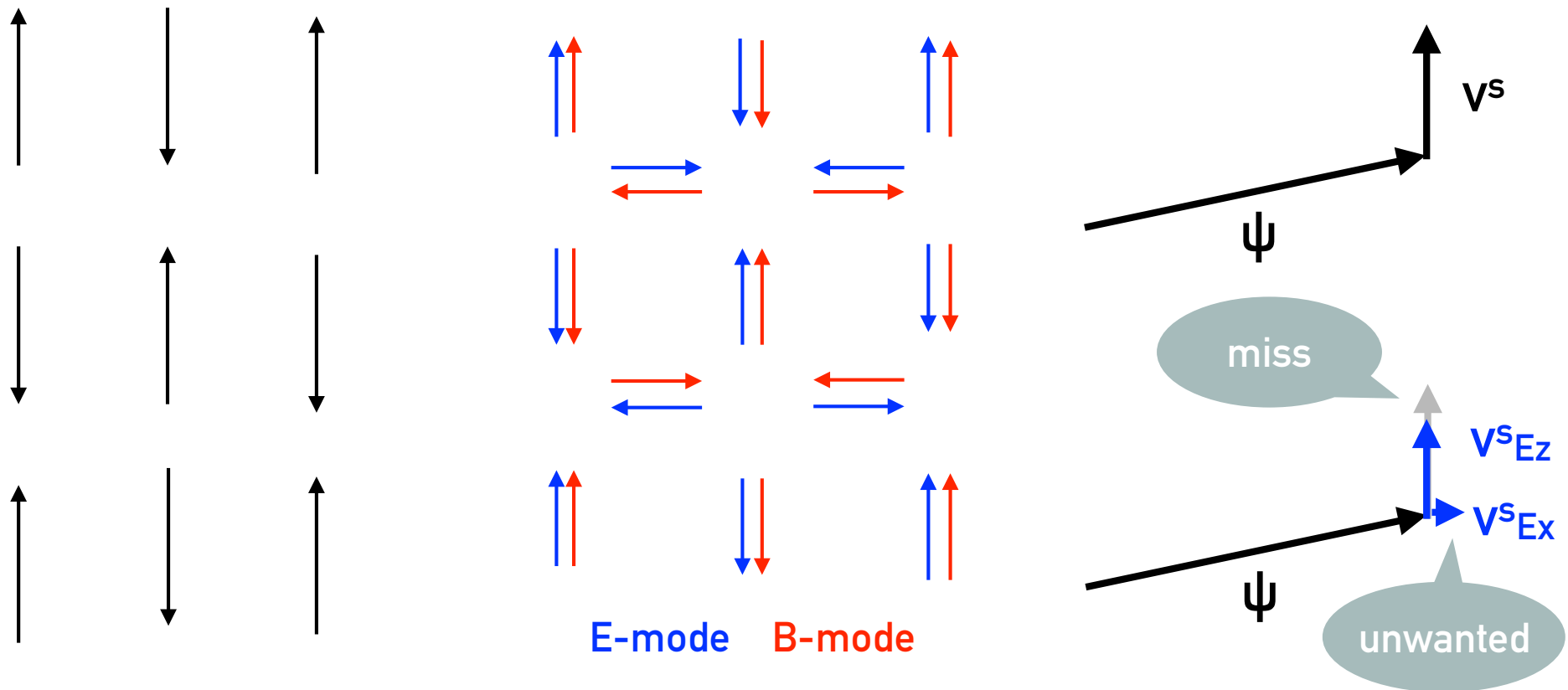


- Thus, RSD resides in the reconstructed density field.
- Before reconstruction: nonlinear density + nonlinear RSD
- After reconstruction: more linear density + **more linear RSD?**



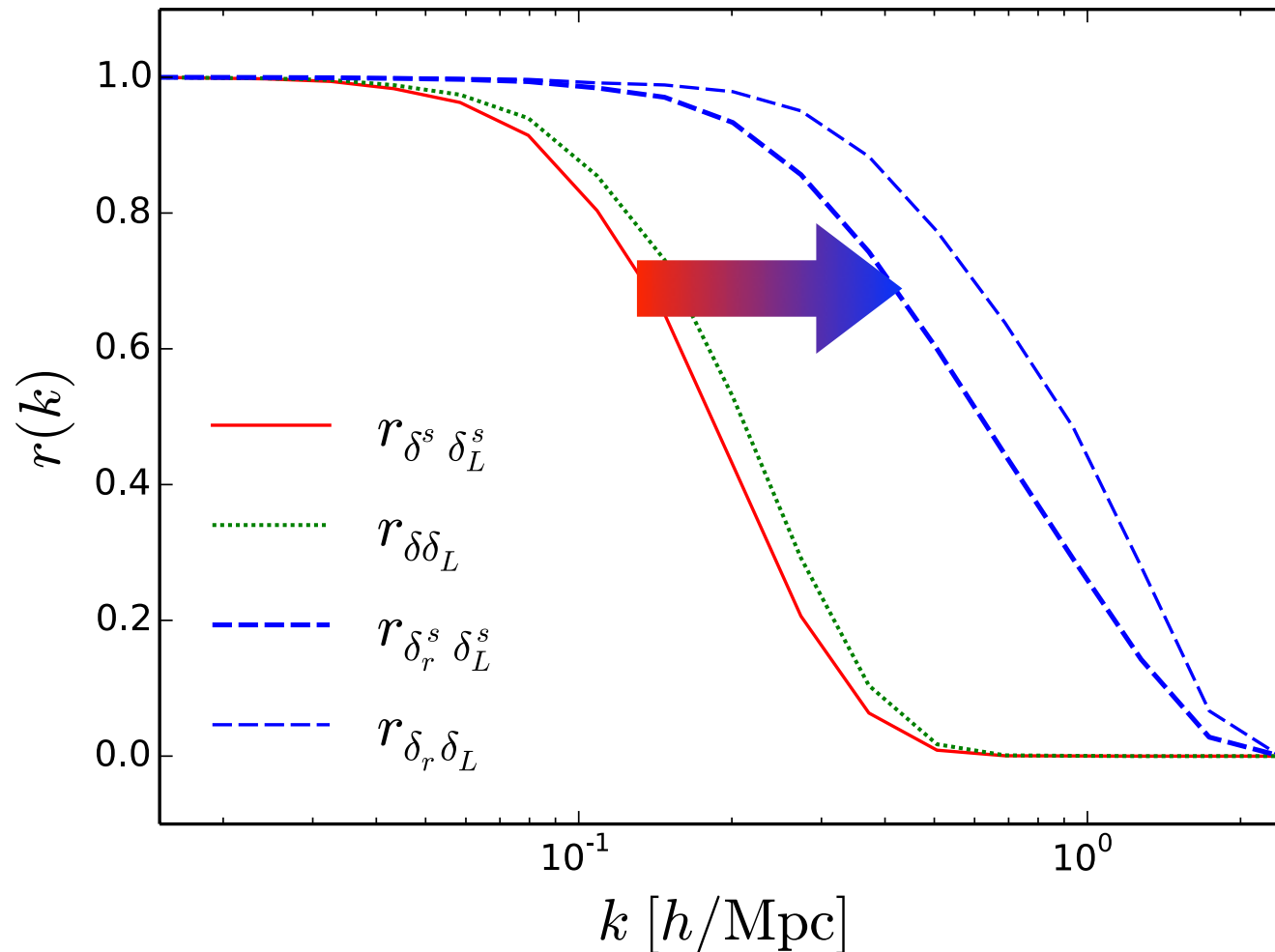
# Shift velocity

$$v_z \vec{z} \equiv \vec{v}^s = \vec{v}_E^s + \vec{v}_B^s$$



- The E-mode part of shift velocity could be reconstruction ( $v^s_{Ez}$ ).
- Unwanted byproducts,  $v^s_{Ex}$ ,  $v^s_{Ey}$

# 1D Cross-correlation coefficient

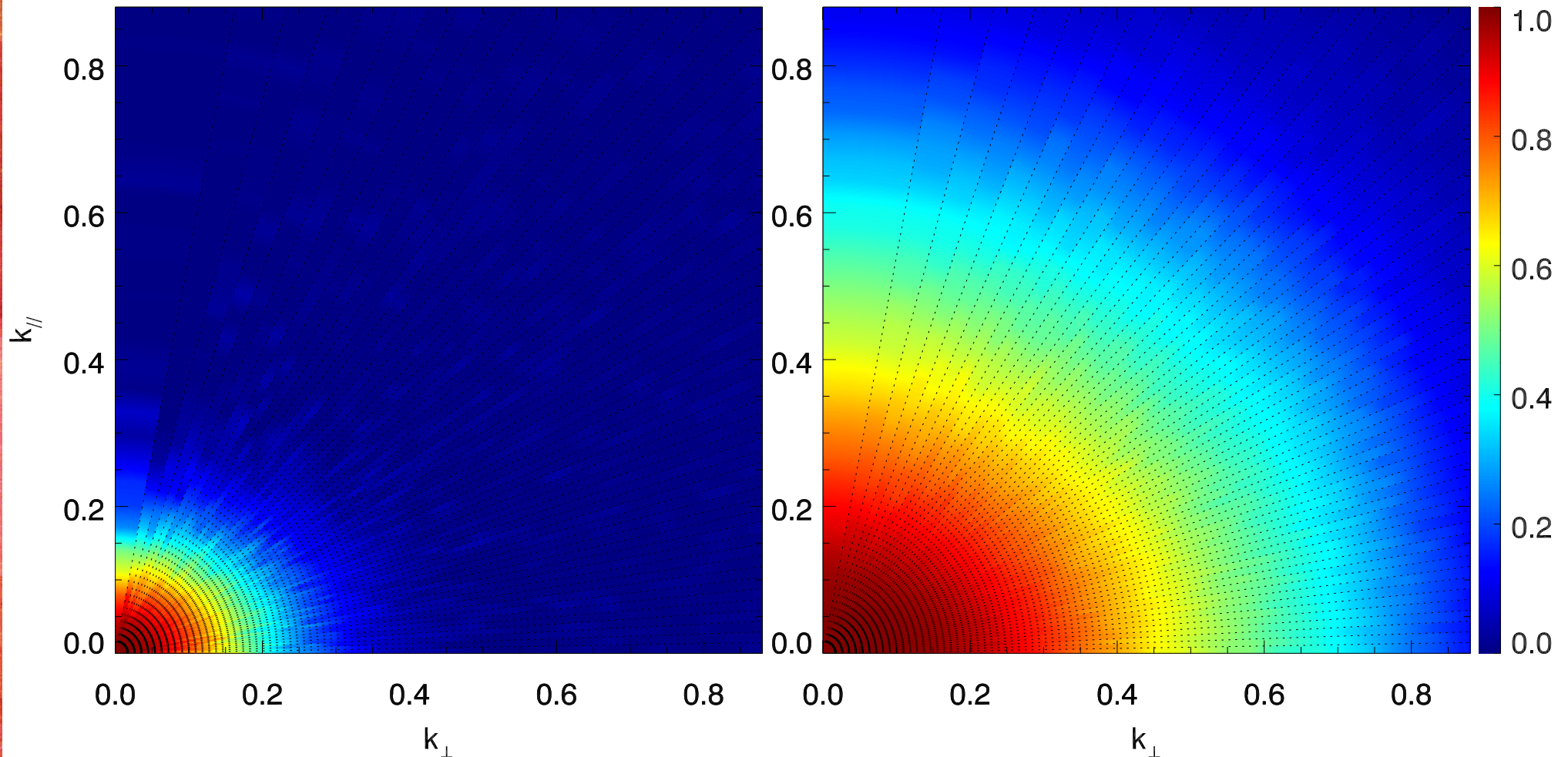


- 1D cross-correlation coefficient with linear field + linear RSD, i.e.,  $\langle \delta_{\text{NL}} (1 + f\mu^2) \delta_L \rangle$  and  $\langle \delta_{\text{recon}} (1 + f\mu^2) \delta_L \rangle$



# 2D Cross-correlation coefficient

---



- 2D cross-correlation coefficient with linear field + linear RSD, i.e.,  $\langle \delta_{\text{NL}} (1 + f\mu^2) \delta_L \rangle$  and  $\langle \delta_{\text{recon}} (1 + f\mu^2) \delta_L \rangle$

# Reconstruction with RSD

---

- Usually we use upto  $k=0.1 \text{ h/Mpc}$ , since nonlinear RSD is not well understood.
- RSD is more linear in the reconstructed ANISOTROPIC density field.
- In principal, RSD could be modeled better. (not shown here)
- More linear RSD means more robust constraints on modified gravity?

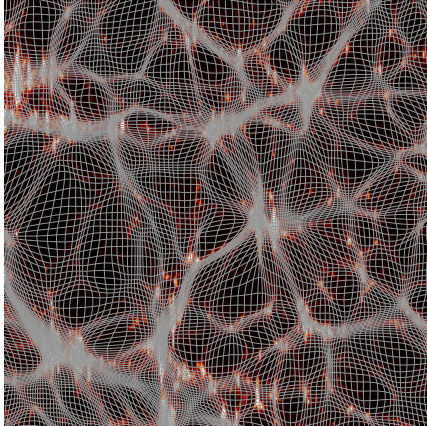


# Outline

---

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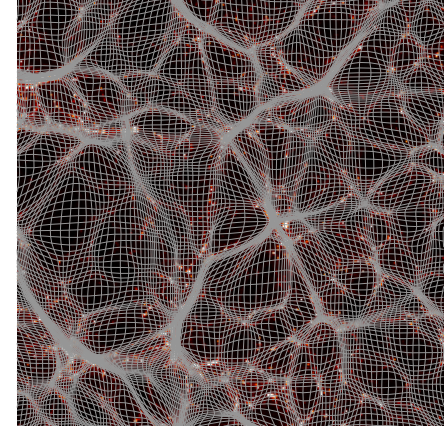
# Multipole moments



150 Mpc/h

$$\delta^s(k) = \delta(k)(1 + \beta\mu^2)$$

$$P_l^s(k) = \frac{2l+1}{2} \int_{-1}^1 P(k, \mu) L_l(\mu) d\mu$$



150 Mpc/h

►  $l=0, 2, 4$  (monopole, quadrupole, hexadecapole)

$$\begin{pmatrix} P_0(k) \\ P_2(k) \\ P_4(k) \end{pmatrix} = P_{\delta\delta}(k) \begin{pmatrix} 1 + \frac{2}{3}\beta + \frac{1}{5}\beta^2 \\ \frac{4}{3}\beta + \frac{4}{7}\beta^2 \\ \frac{8}{35}\beta^2 \end{pmatrix}$$

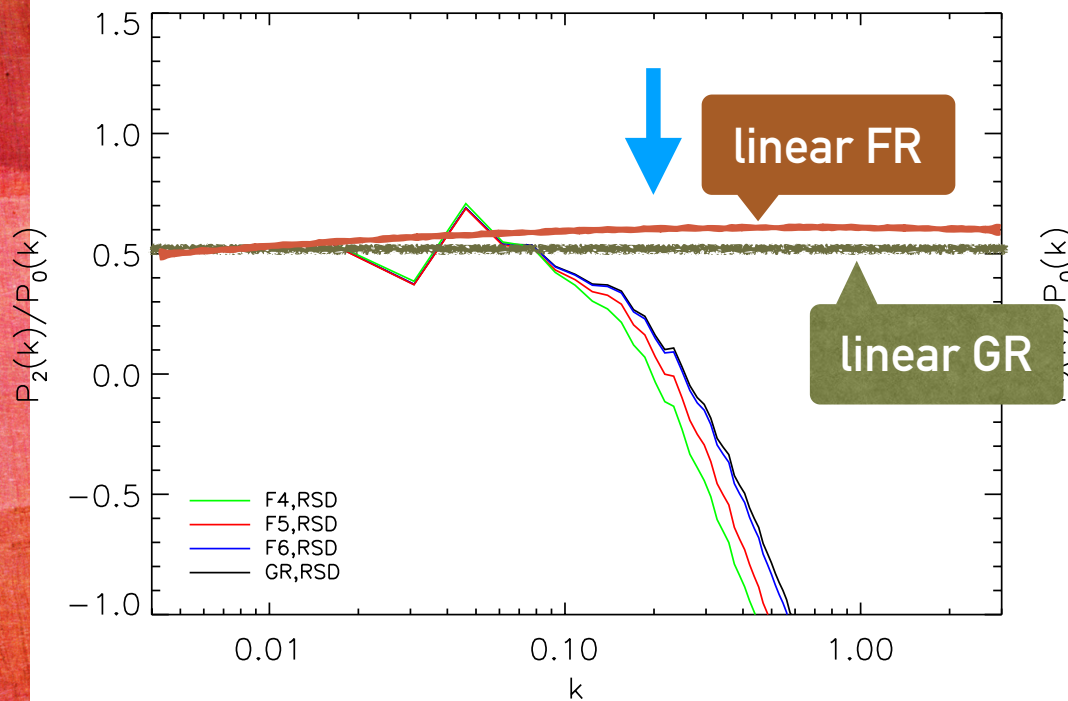
$$\mathbf{P}_2(\mathbf{k})/\mathbf{P}_0(\mathbf{k}) \rightarrow \beta$$



# Multipole moments ratio

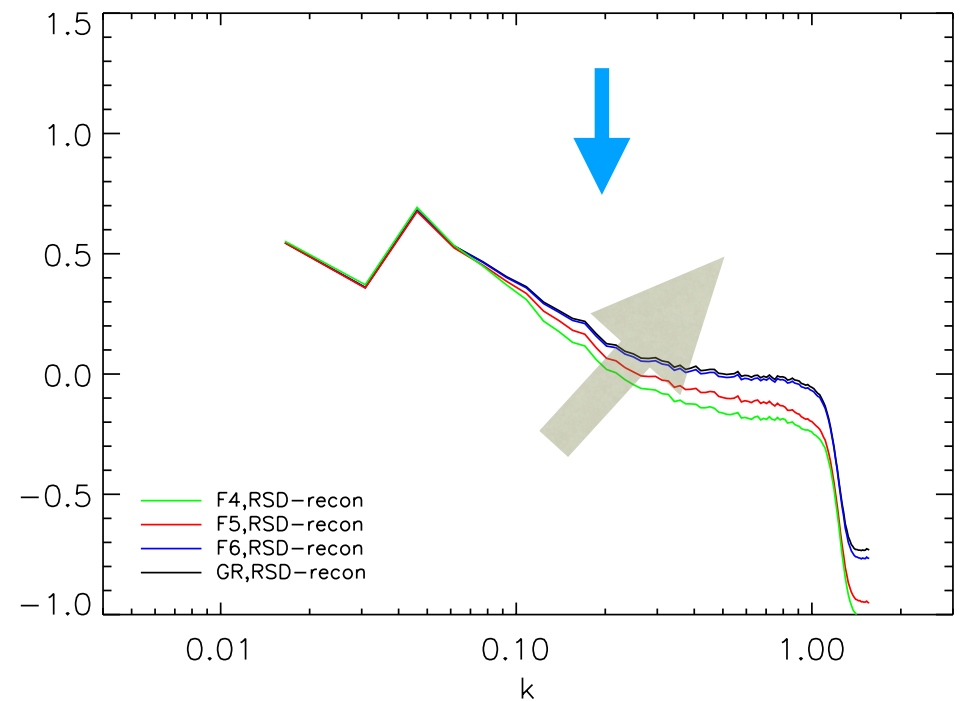
$$P_2(k)/P_0(k)$$

0.2



simulated

0.2

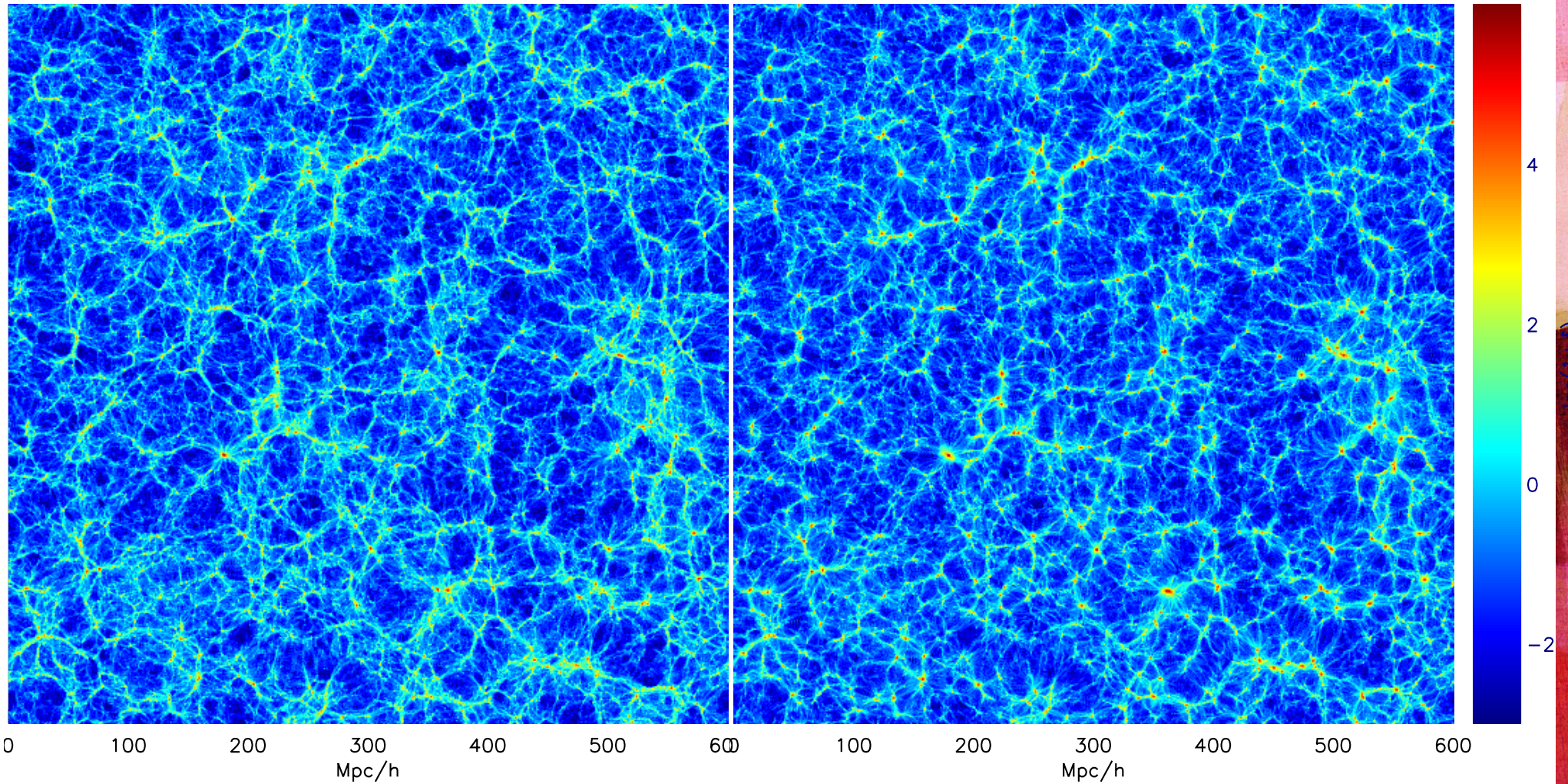


reconstructed



# Constrained simulation

---



Original  
Simulation

Constrained  
Simulation



# Velocity reconstruction

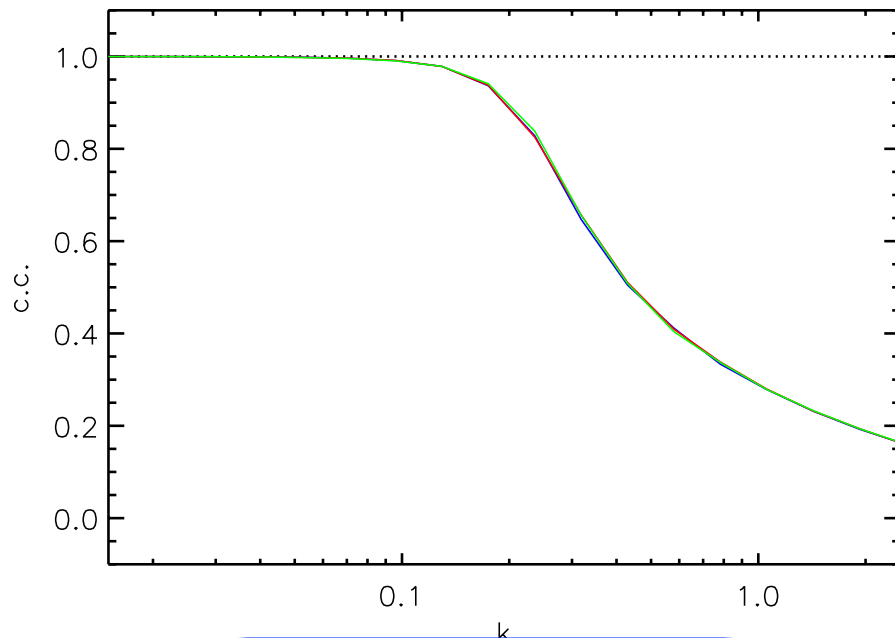
- Standard method: linear continuity equation

$$\mathbf{v}(\mathbf{k}) = aHf \frac{i\mathbf{k}}{k^2} \frac{\delta_S(\mathbf{k})}{b}$$

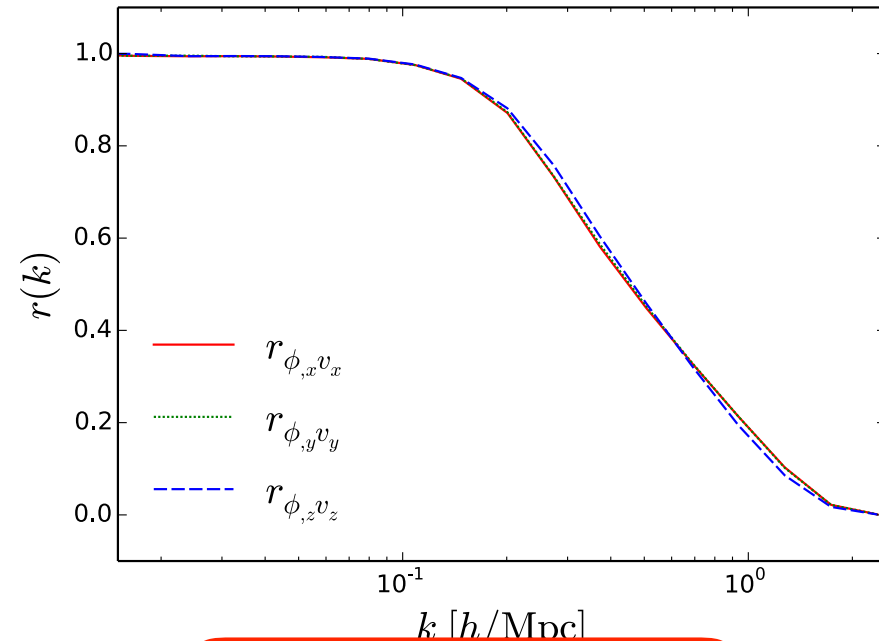
- Our attempts: relation with displacement

$$\mathbf{v} = \frac{d\mathbf{x}}{dt} = \frac{d\Psi}{dt}$$

$$\langle \mathbf{v}(\mathbf{q}) \Psi(\mathbf{q}) \rangle$$



$\mathbf{v}(\mathbf{q})$  v.s.  $\Psi(\mathbf{q})$



$\mathbf{v}(\mathbf{q})$  v.s.  $\Psi_{\text{recon}}(\mathbf{q})$

# Velocity reconstruction

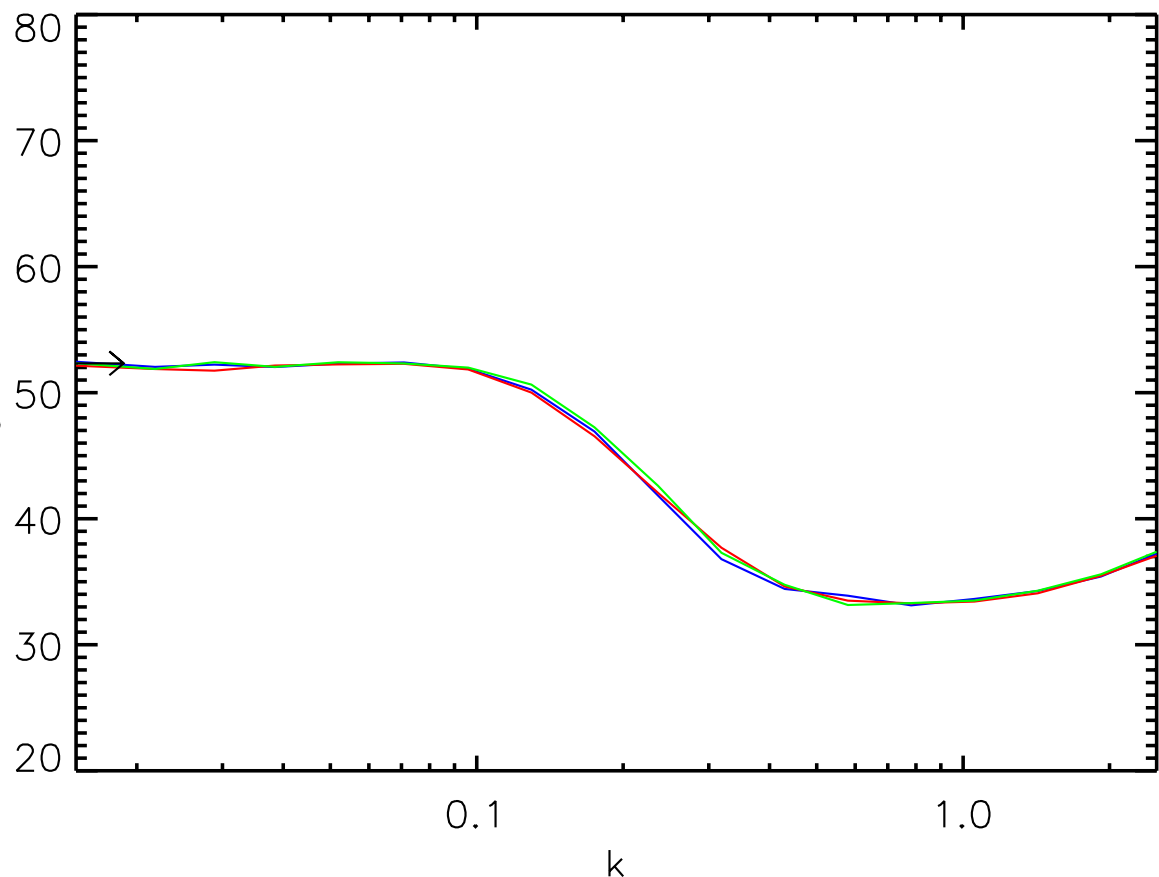
- Use the relation (transfer function) to convert the reconstructed displacement to the reconstructed velocity field.

$$\hat{v} = \frac{\langle \Psi v \rangle}{\langle \Psi \Psi \rangle} * \hat{\Psi}$$

Measured in  
simulation

recon from  
obs

$$\frac{\langle \Psi v \rangle}{\langle \Psi \Psi \rangle}$$



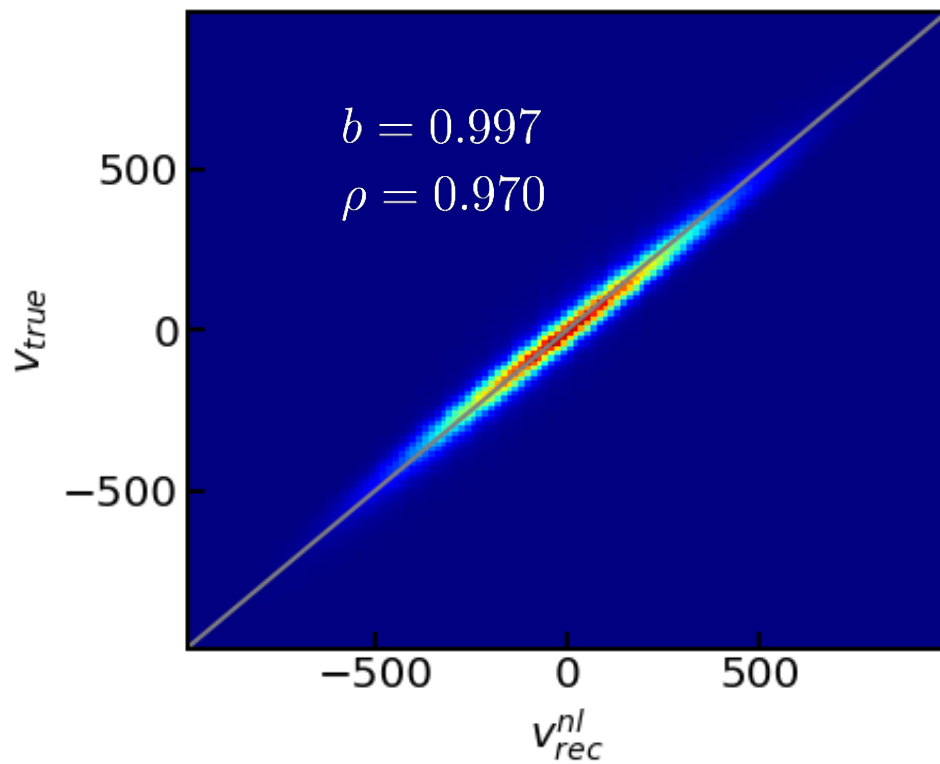


# Velocity reconstruction

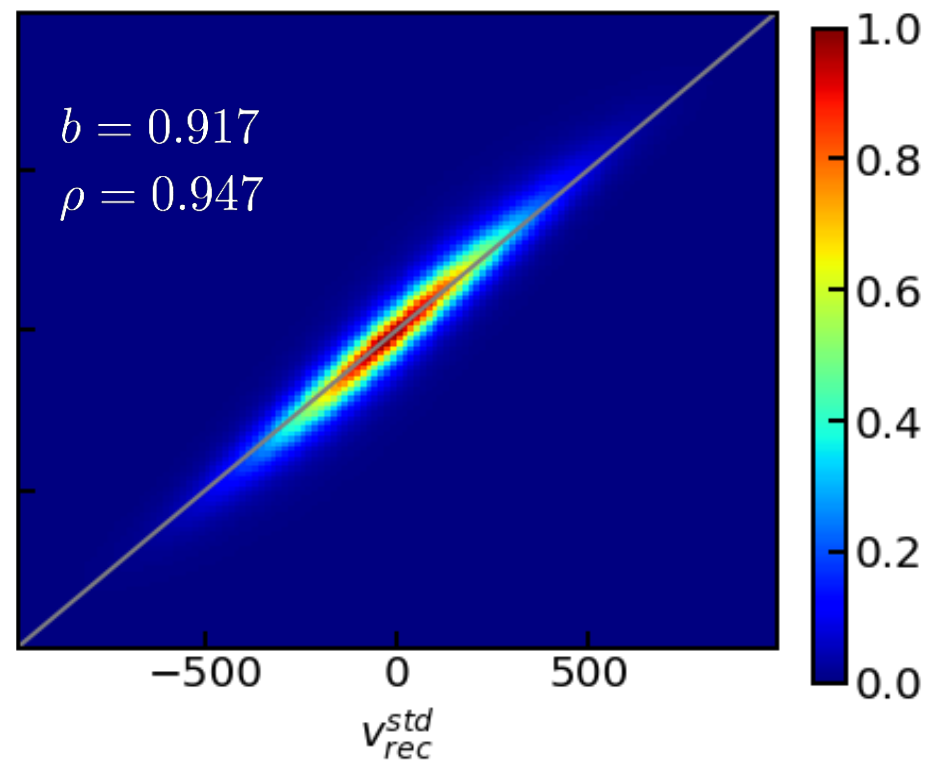
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$$b = 1.040$$

Nonlinear Recon.



Standard Recon.



# Conclusion

---

- Nonlinear reconstruction is useful in
  - extracting BAO signal in **low-redshift high-density** survey
  - recovering more linear RSD effect



# To explore

---

- Applying to real data (SDSS MGS, DESI BGS, 21cm IM, etc)
- improvement in differing gravity models ?
  - theoretical supporting for NR ?
  - quantification ( $f\sigma_8$ )
- reconstruction of the initial condition (v.s. HMC)
- velocity reconstruction performance ? (v.s. linear continuity equation)
- correspondence to halo displacement ?



上海交通大学天文系  
DEPARTMENT OF ASTRONOMY AT SJTU

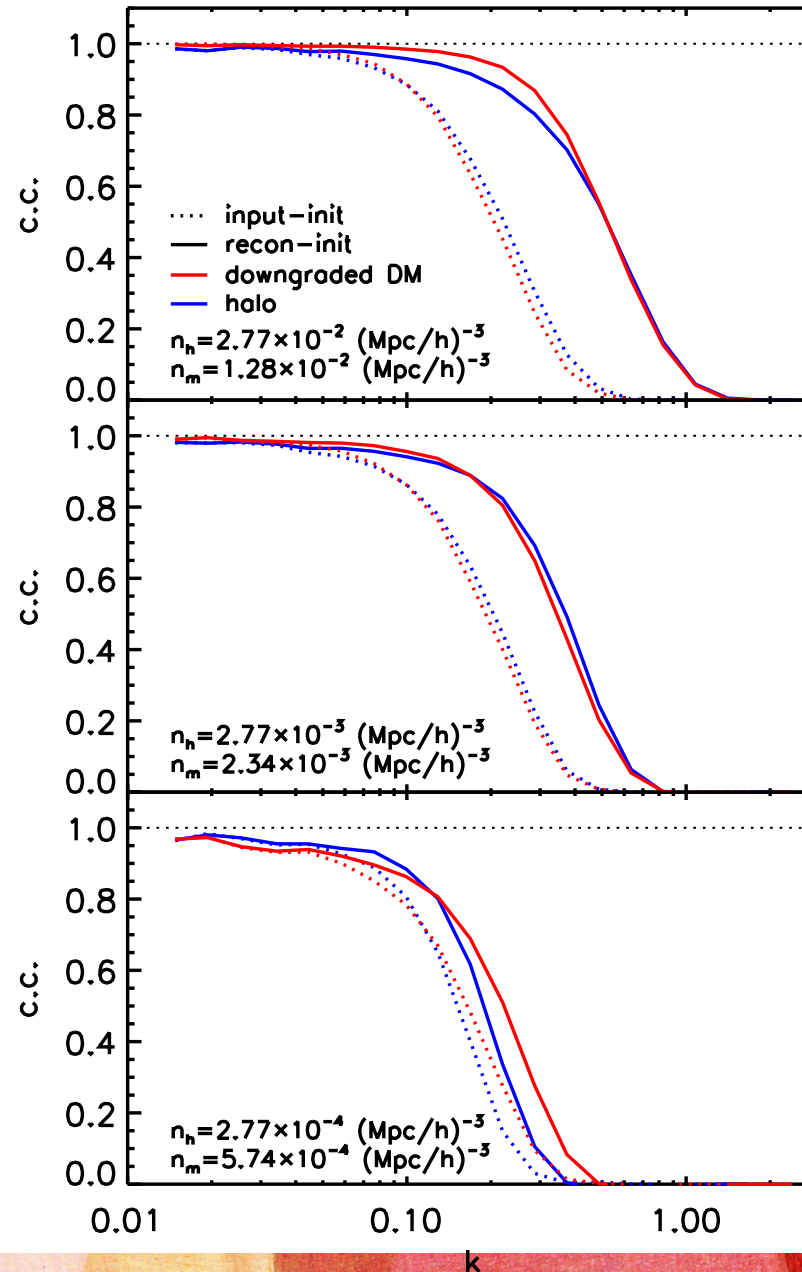
# THANK YOU

ご清聴ありがとうございました



# halo v.s. downgraded DM

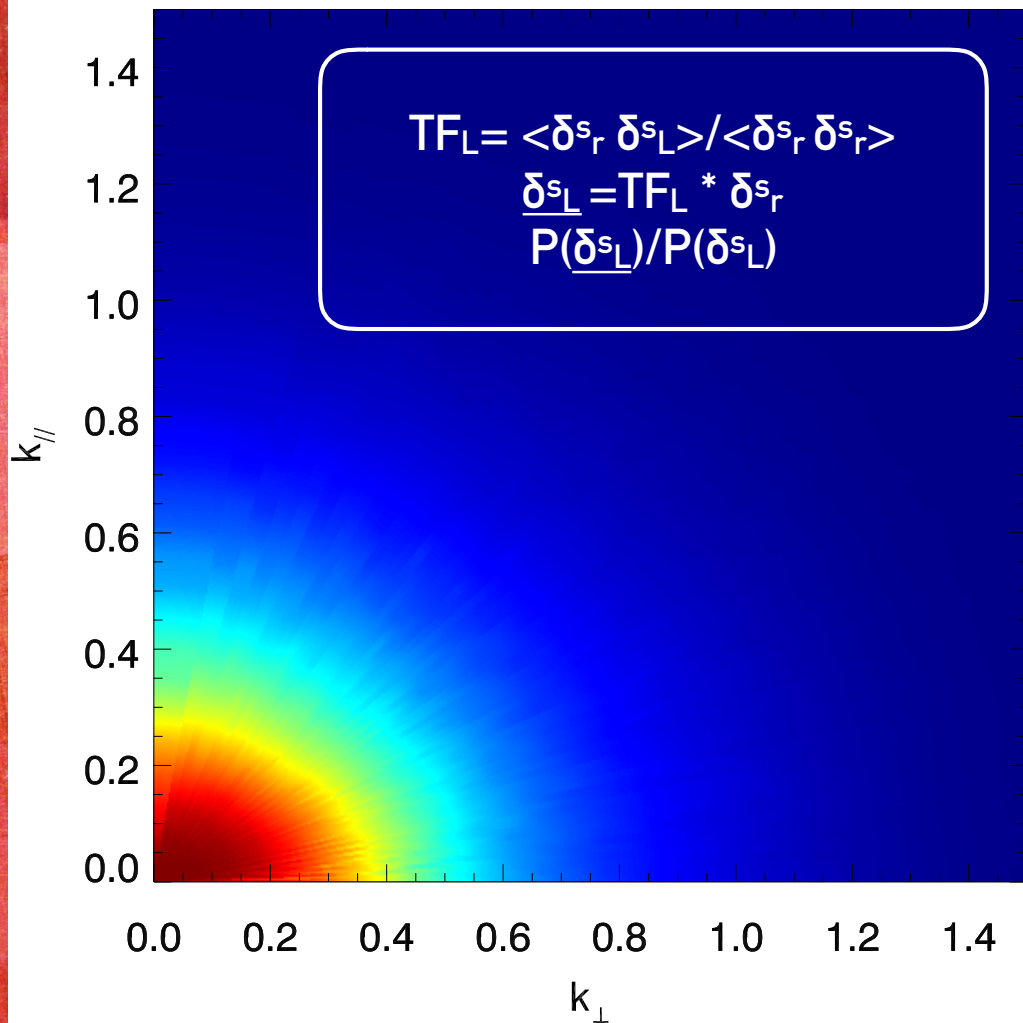
- $n_m = b^2 n_h$
- This downgraded DM sample shares the same effective shot noise as the halo sample
- This result tells us that the main limitation comes from the shot-noise.



Yu et al. (2017)

# modeling of the power spectrum shape by transfer functions

power spectrum shape



power spectrum shape

