

Status Report

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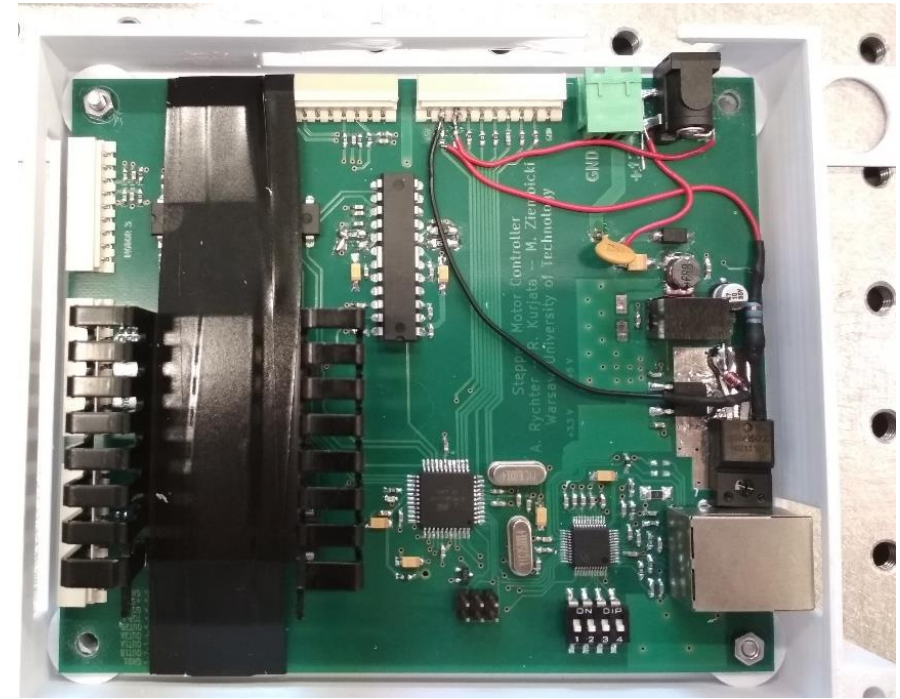
16.11.2018

Uniform stage

- Problems come from the digitalizer
- We can correct the data
- We don't have aluminium for reflectors

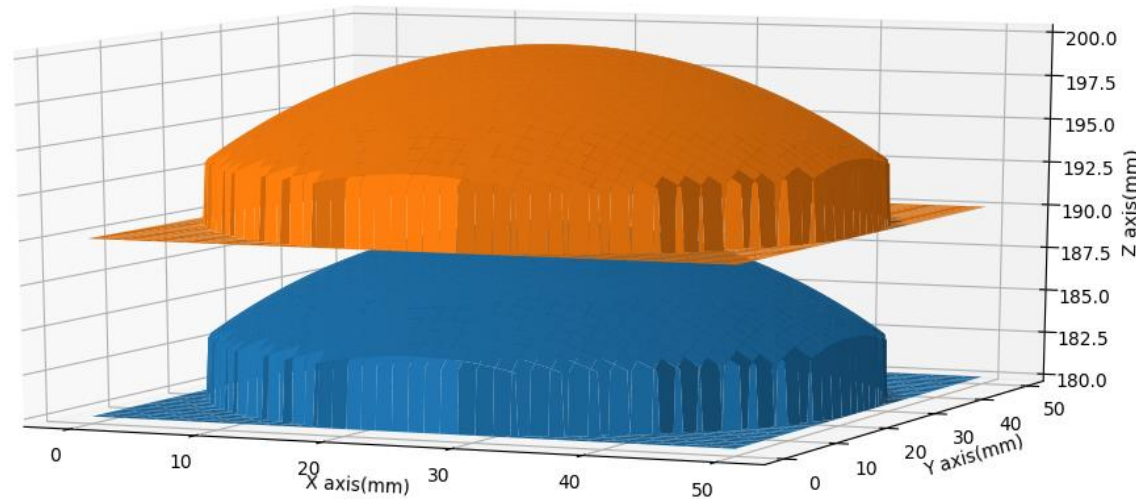
New problems with motorized station

- On Wednesday Izumi-san encountered a problem with communication with the controller
- I have checked if main microcontroller is ok
- We don't know how looks communication controller (another microcontroller)



Position scan correction

- I have created small script to create better position scan – now distance between PMT and colimator will be the same in each position



Plans for the next week

- Solve the problem of communication with motorized station
- Take measurements with uniform stage
- Find some aluminium reflectors in Japan