Status Report

22.11.2018

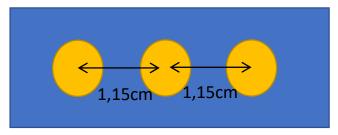
Adam Klekotko

Motorized Station

- Problem solved we have cleared EEPROM (microcontroller memory) and we have set the connections settings permanently (static IP, Gateway, netmask and broadcast)
- Newer version of the python script

Uniformity Light Measurement

- Benjamin have found a problem which produced this bump this is software issue so after reparing code we can analyze data
- 21.11.2018 after Izumi-san measurements, I set up a uniformity stand
- I've made several measurements to prove uniformity fitting is bad (also looks that intensity was too low) so we have to take new data today or maybe try with new software



Plans for the next week

- Take reflector measuremnts and analyze them
- We received new LED fiber so check if it will reduce/eliminate this ring problem
- Improve motorized station and check results of new scan map file –
 python script which implements correction of Z coordinates