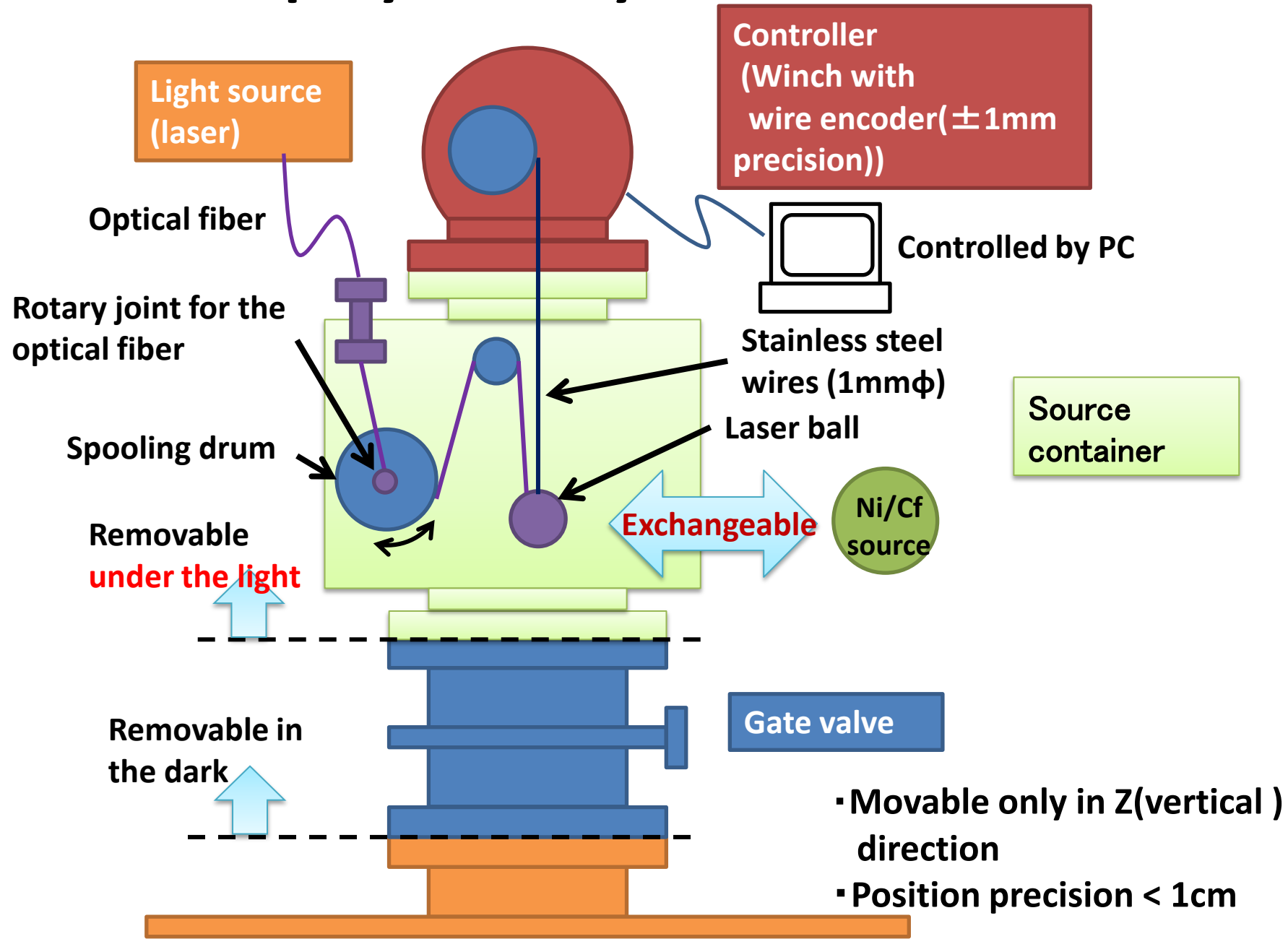


# **New source deployment system for SK as an R&D of HK calibration**

**Atsumu Suzuki**  
**Kobe University**

- **Some calibration works of SK are done manually in the dark.**
- **▪ Deployment system using a winch with wire encoder controlled by PC**
  - Work under the light as much as possible**  
**(figure in the next page)**
- **This work is also R&D for HK calibration system.**

# Source Deployment System



# Image of the system

Sources are suspended with 2 wires

- to prevent sources from rotation
- safer considering damage or cutoff of wires

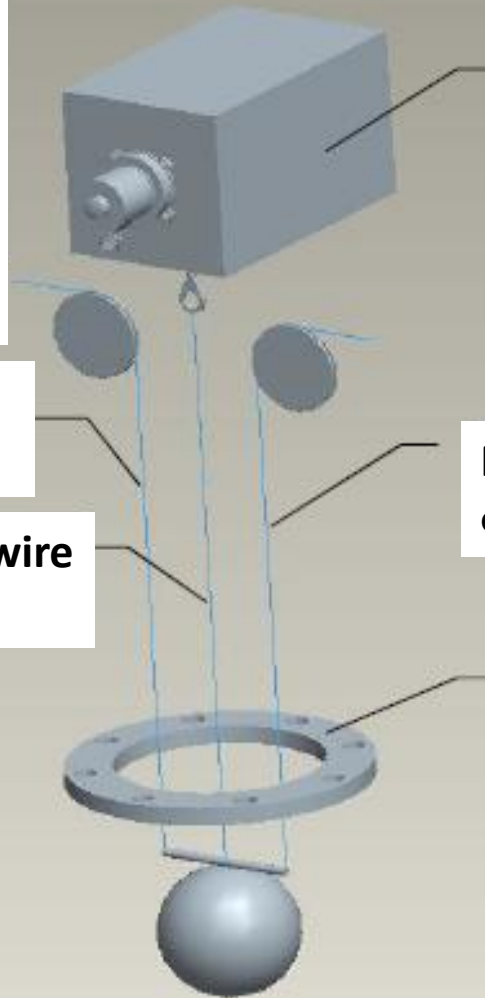
Positioning wire  
 $\phi 1\text{mm}$

Measuring wire  
 $\Phi 1.35\text{mm}$

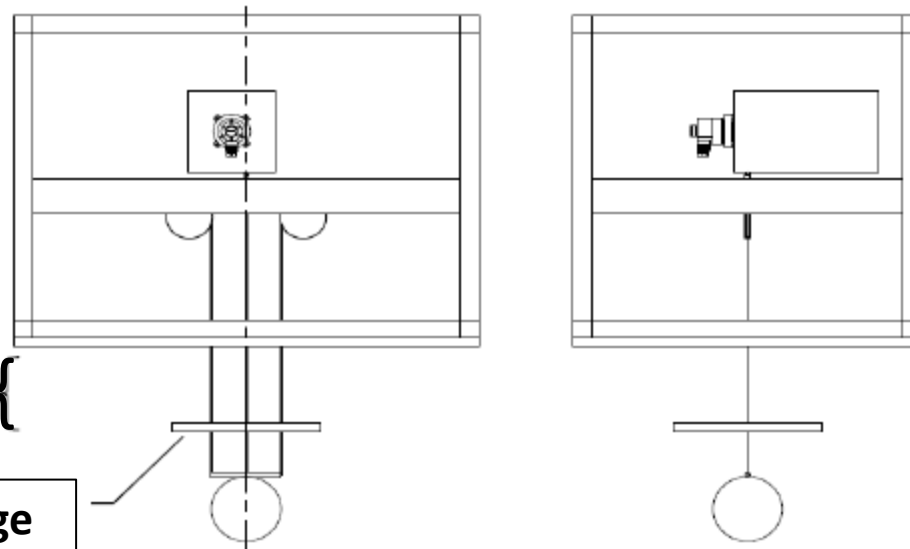
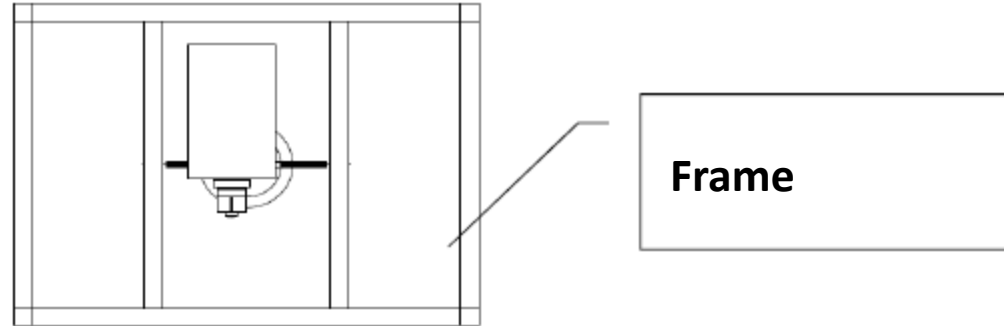
Wire encoder

Positioning wire  
 $\phi 1\text{mm}$

200A flange



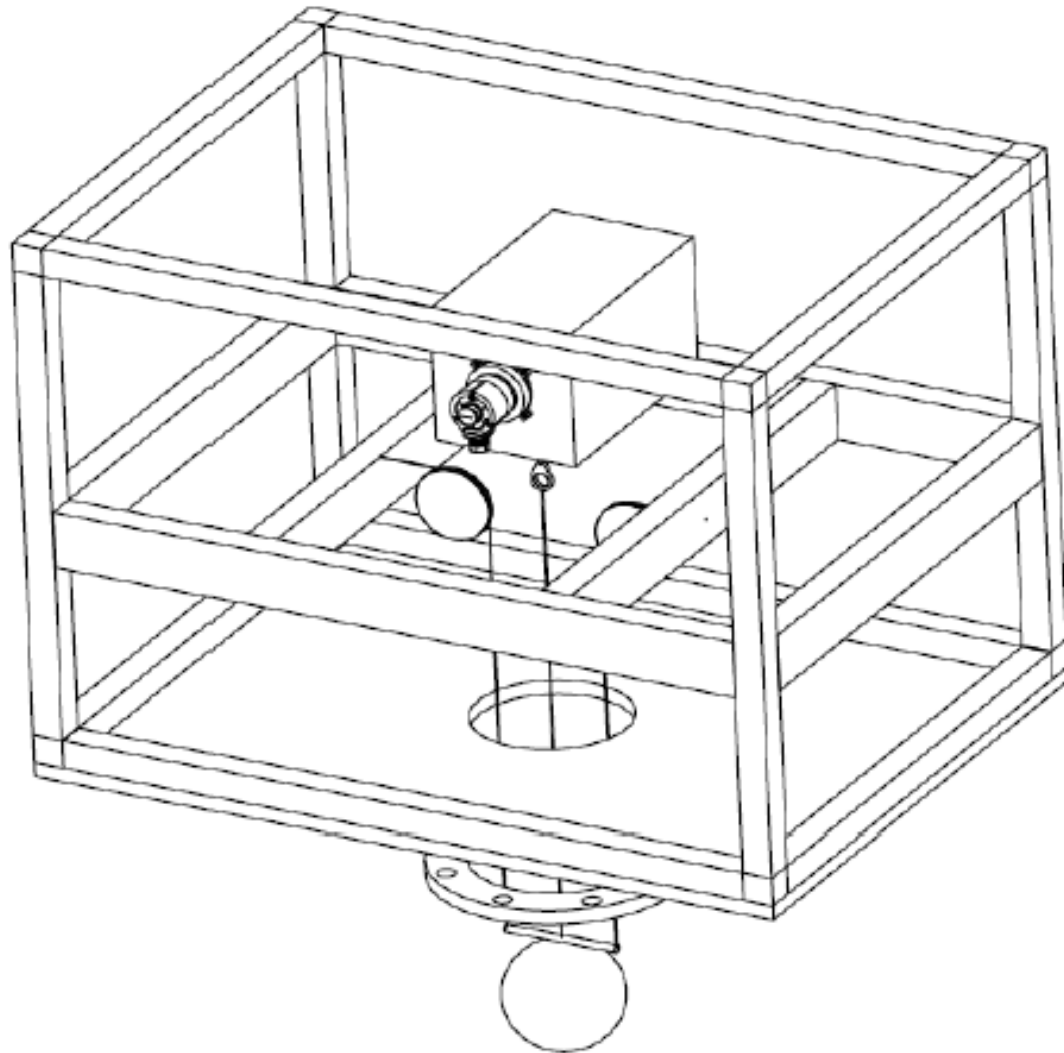
# Front, Top, & Side Views



Gate valve is inserted  
here.

200A flange

# Schematic View



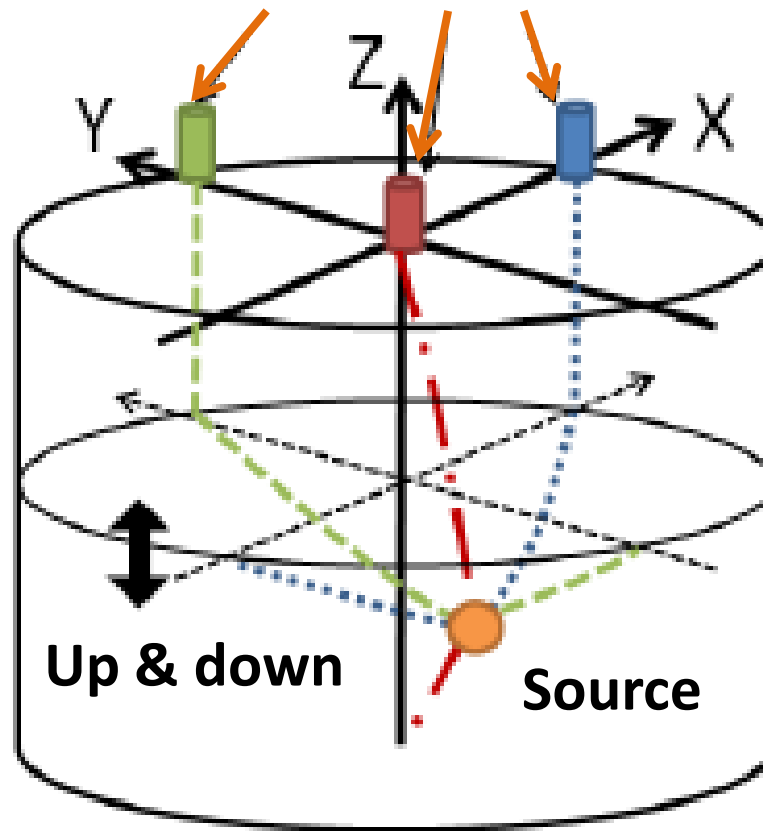
# Schedule

- **FY2014** design & production
- **FY2015**
  - 1<sup>st</sup> half** Test in the air & programming control software
  - 2<sup>nd</sup> half** Total test & use in SK
- **FY2016~** R&D in the HK prototype

# R&D of 3D deployment system in the HK prototype

Since HK is so large, the calibration system should be movable automatically in 3D to reduce time and manpower.

Wire length controllers



# Summary

- We are planning to set a new 1D (z direction) source deployment system in the SK in FY2014 & 2015.
- After that, we will start R&D for 3D system in HK prototype.