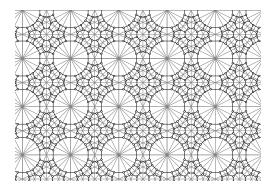
Tits Cone Intersections & Applications



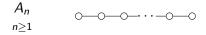
Michael Wemyss

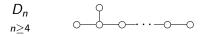
www.maths.gla.ac.uk/~mwemyss

Plan of Talk

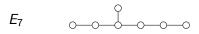
- 1. ADE Dynkin diagrams, and their extended versions. Hyperplane arrangements and friends.
- 2. Application 1: Kleinian singularities, and partial McKay.
- 3. Application 2: Flopping contractions, mutation, and stability conditions. (plus: what is the picture on the first slide?)

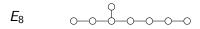
ADE Dynkin Diagrams





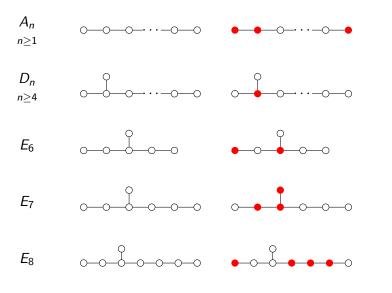






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ADE Dynkin Diagrams + choice of nodes



Construction

Input

- Any choice of ADE Dynkin diagram Δ ,
- and any choice of nodes $\mathcal{J} \subseteq \Delta$.

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Now, each such Δ has an associated *root system*. This is just a real vector space $\mathbb{R}^{|\Delta|}$, with basis given by the nodes, together with some *reflecting hyperplanes*.

This does not depend on the choice \mathcal{J} .

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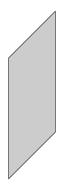
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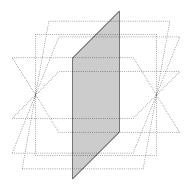
Aim

Want something similar, but which also depends on \mathcal{J} .

The root system has a basis given by the nodes. Thus, the choice \mathcal{J} gives *some* of these, so a *subspace* $\mathbb{R}^{|\mathcal{J}|}$. Picture for $|\mathcal{J}| = 2$ is:

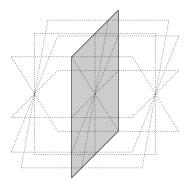


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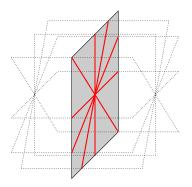
The reflecting hyperplanes slice the subspace

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We *intersect* the reflecting hyperplanes with the subspace

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We intersect the reflecting hyperplanes with the subspace

Output

A finite collection of (red) hyperplanes, written $Cone(\mathcal{J})$.

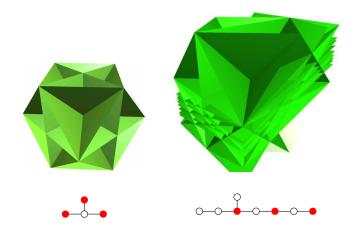
Some Examples





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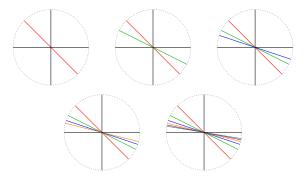
Some Examples



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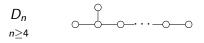
Theorem (Iyama–W)

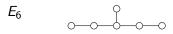
Consider any $\mathcal{J} \subseteq \Delta$ with Δ ADE Dynkin and $|\mathcal{J}| = 2$. Then, up to changing the slopes of the lines, $Cone(\mathcal{J})$ is one of:

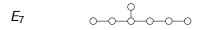


The number of chambers is 6, 8, 10, 12 and 16 respectively.

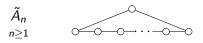


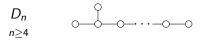


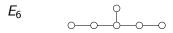


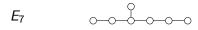


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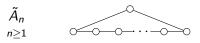


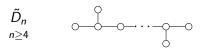


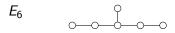


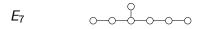


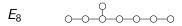
 E_8

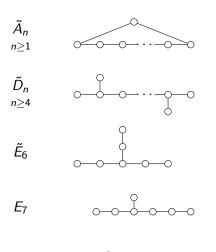


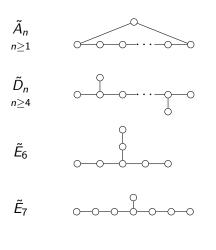




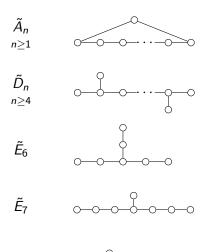




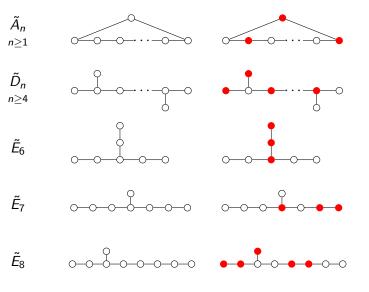




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Better: extended ADE Dynkin Diagrams + choice of nodes



Tits Cone Intersections

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- Any choice of extended ADE Dynkin diagram Δ_{aff} ,
- and any choice of nodes $\mathcal{K} \subseteq \Delta_{\text{aff}}$.

Tits Cone Intersections

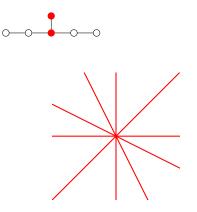
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A similar story as to before, intersecting now inside the Tits Cone (instead of the root system) gives an *infinite* hyperplane arrangement, written Level(\mathcal{K}).

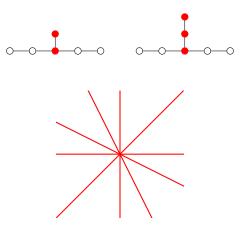
This lives in $\mathbb{R}^{|\mathcal{K}|-1}$.

Finite Inside Infinite



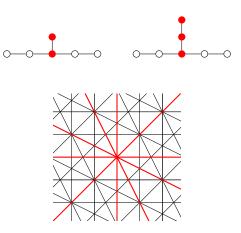
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Finite Inside Infinite



May as well develop the infinite theory; finite theory comes for free.

Labels and Wall Crossing

Question

How to calculate these intersection hyperplane arrangements?

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The key is what we actually do is the following:

- ► Every chamber is labelled by a pair (w, J), where w is an element in some group, and J is a subset of nodes.
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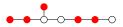
The rule is a bit technical, but it allows us to start anywhere, and iterate. The rule is also important for geometric applications.

Number of wall crossings = number of red nodes in subset.

To cross one of these walls, choose red node. Temporarily delete *all other* red nodes, apply Dynkin involution, then put back in the deleted vertices.

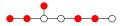
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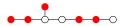
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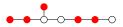
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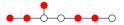
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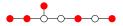




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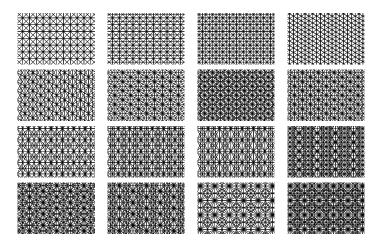


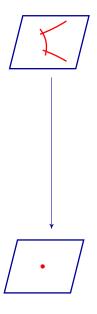
Theorem (Iyama–W)

If $\mathcal{K} \subseteq \Delta_{aff}$ satisfies $|\mathcal{K}| = 3$, then up to changing the slopes of some of the hyperplanes, Level(\mathcal{K}) is one of:

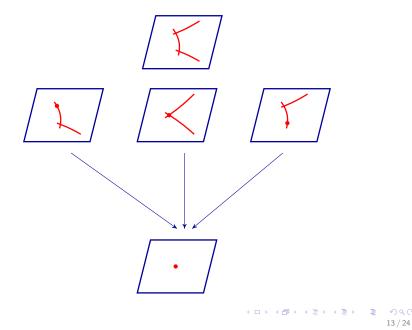
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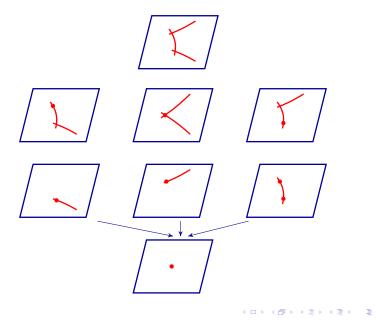
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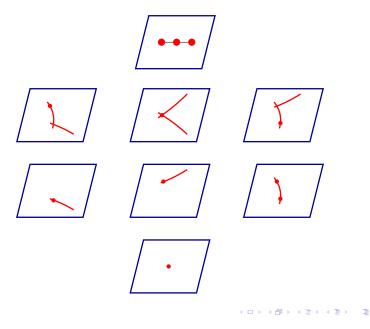


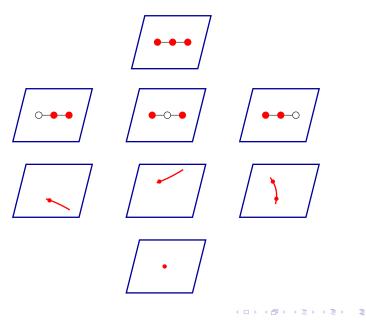


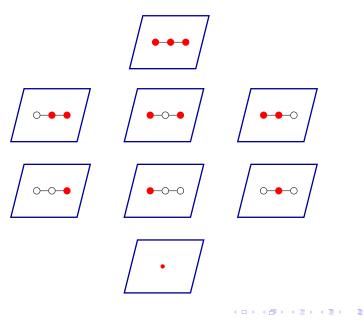
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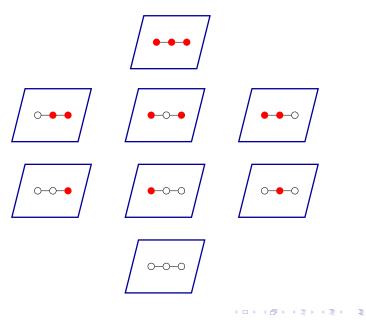












So: crepant partial resolutions $\longleftrightarrow X_{\mathcal{J}}$ for some $\mathcal{J} \subseteq \Delta$.

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If I and \mathcal{J} are related via the wall crossing rule, then X_J and X_J are derived equivalent.

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Conjecture

 $X_{\mathcal{I}}$ and $X_{\mathcal{J}}$ are derived equivalent $\iff \mathcal{I}$ and \mathcal{J} can be linked by a finite sequence of wall crossings, up to symmetries of the graph.

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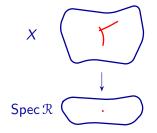
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Theorem (Iyama–W)

Conjecture (\Leftarrow) always holds. Further, (\Rightarrow) holds for all types except possibly D_n with $n \ge 8$.

Application 2: Dimension Three

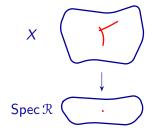
Consider now three-dimensional multi-curve flops, which are pictorially:



where X is smooth. Smoothness is not important, all statements later hold more generally, with tweaks.

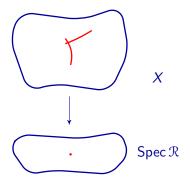
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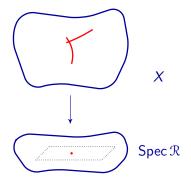
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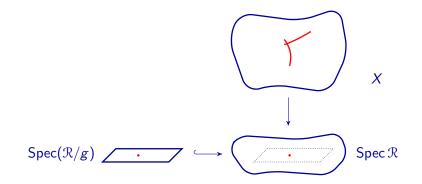


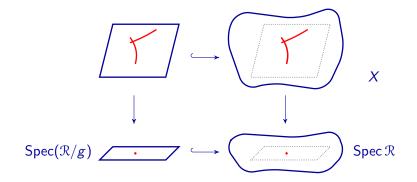
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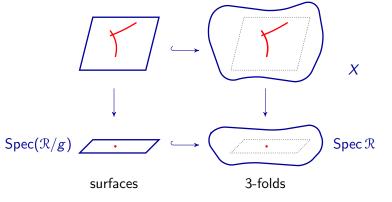
- Classification.
- Invariants, curve counting.
- Derived categories and stability conditions.
- Symmetries: derived autoequivalences.
- Noncommutative resolutions.

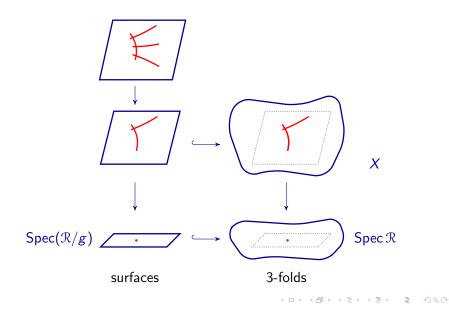


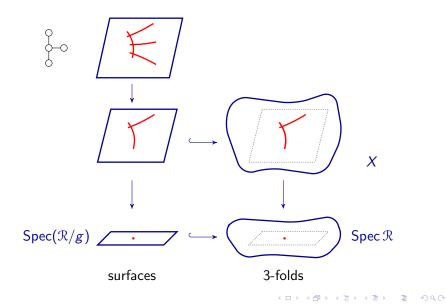


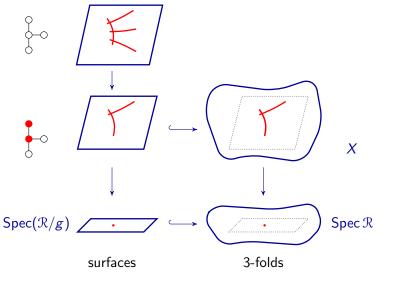


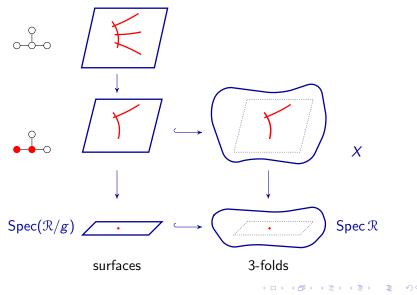






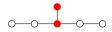






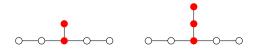
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As before, from this we can always just add in the extended vertex:



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Start of talk: the left one gives us a finite hyperplane arrangement \mathcal{H} , the right hand one gives us an infinite arrangement \mathcal{H}_{aff} .

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Start of talk: the left one gives us a finite hyperplane arrangement \mathcal{H} , the right hand one gives us an infinite arrangement \mathcal{H}_{aff} .

Question

What do these combinatorics have to do with $X \to \operatorname{Spec} \mathfrak{R}$?

Answer

...many things! I'll focus here on noncommutative resolution aspects, then move to autoequivalences and stability conditions.

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Just rings and modules. Consider $\mathcal R$ as in previous slide.

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Just rings and modules. Consider $\ensuremath{\mathcal{R}}$ as in previous slide.

For finite story, interested in those finitely generated $\mathcal R\text{-}\mathsf{modules}\ M$ such that

- *M* is Cohen–Macaulay, namely $Ext^{i}_{\mathcal{R}}(M, \mathcal{R}) = 0$ for all i > 0.
- *M* is rigid, namely $Ext^{1}_{\mathcal{R}}(M, M) = 0$.
- ► *M* is maximal with respect to the above property.

In the lingo, 'maximal rigid objects in the category $\mathrm{CM}\mathcal{R}'.$

Remarkably, below it will turn out that there are only finitely many such maximal rigid objects. Thus, for the infinite arrangement story, we need (infinitely!) more.

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► *M* is modifying, namely End_R(*M*) satisfies Ext¹_R(End_R(*M*), R) = 0

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In the lingo, 'maximal modifying modules'. These are the building blocks of *noncommutative resolutions*.

Main Theorem (Iyama–W)

Suppose that $X \to \operatorname{Spec} \mathcal{R}$ is a flopping contraction. Associate $\mathcal{J} \subseteq \Delta$ by slicing, which gives a finite arrangement \mathcal{H} and an infinite arrangement \mathcal{H}_{aff} .

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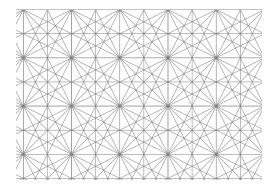
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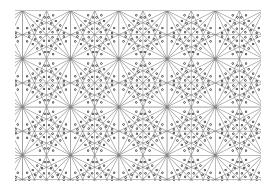
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...in particular, we get a *complete* classification of noncommutative resolutions in this setting!

In the opening slide:

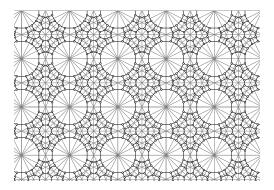


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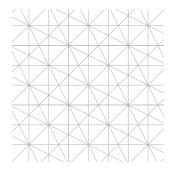


The dots are those $M \in \operatorname{ref} \mathcal{R}$ which give NCCRs. The edges connecting dots are the *mutations* of these; the above is really a picture of the exchange graph.

To have such highly regular structure is very unusual.

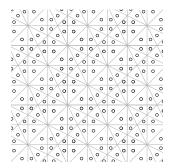
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The *mutation functors* lift the above combinatorial statements. Consider the following groupoid:



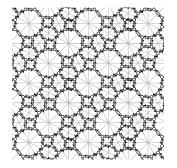
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with relations give by identifying shortest paths. This is called the *Deligne groupoid*.

There is another way to build a groupoid. By last theorem:

- Each chamber has associated M, thus $D^{b}(\text{mod End}_{\mathcal{R}}(M))$.
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Theorem (Iyama–W)

There exists a functor from the Deligne groupoid to the groupoid described above.

Corollary (Iyama–W)

 $\pi_1(\mathbb{C}^n \setminus (\mathcal{H}_{\mathsf{aff}})_{\mathbb{C}}) \text{ acts on } \mathsf{D}^\mathsf{b}(\mathsf{coh}\, X).$

And categorify again...

Consider the following two subcategories of $D^{b}(\operatorname{coh} X)$.

$$\mathcal{C} = \{ \mathcal{F} \in \mathsf{D}^{\mathsf{b}}(\operatorname{coh} X) \mid \mathbf{R}f_* \mathcal{F} = 0 \}$$
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Theorem (Hirano–W)

Given flopping contraction $X \to \operatorname{Spec} \mathcal{R}$, associate finite \mathcal{H} and infinite $\mathcal{H}_{\operatorname{aff}}$ by slicing. Then the forgetful maps

$$\begin{aligned} \mathrm{Stab}^{\circ} \mathcal{C} &\to \mathbb{C}^n \backslash \mathcal{H}_{\mathbb{C}} \\ \mathrm{Stab}_n^{\circ} \mathcal{D} &\to \mathbb{C}^n \backslash (\mathcal{H}_{\mathsf{aff}})_{\mathbb{C}} \end{aligned}$$

are regular covering maps. The first is universal.

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Autoequivalences of the last slide are the deck transformations.