

# Cancer Detection via Electrical Impedance Tomography and PDE Constrained Optimal Control in Sobolev Spaces

Ugur G. Abdulla

Okinawa Institute of Science and Technology  
Okinawa, Japan

ISCO 2023

$$Q \in \mathbb{R}^n$$

$Q \in \mathbb{R}^n$  Electrical conductivity tensor  $A(x) = (a_{ij}(x))_{ij=1}^n$ ,  $x \in Q$

$Q \in \mathbb{R}^n$  Electrical conductivity tensor  $A(x) = (a_{ij}(x))_{i,j=1}^n$ ,  $x \in Q$   
 $(E_l)_{l=1}^m$ ,

$Q \in \mathbb{R}^n$  Electrical conductivity tensor  $A(x) = (a_{ij}(x))_{i,j=1}^n$ ,  $x \in Q$   
 $(E_l)_{l=1}^m$ ,  $Z := (Z_l)_{l=1}^m \in \mathbb{R}_+^m$

$Q \in \mathbb{R}^n$  Electrical conductivity tensor  $A(x) = (a_{ij}(x))_{ij=1}^n$ ,  $x \in Q$   
 $(E_l)_{l=1}^m$ ,  $Z := (Z_l)_{l=1}^m \in \mathbb{R}_+^m$   $I := (I_l)_{l=1}^m \in \mathbb{R}^m$  is called *current pattern*

$Q \in \mathbb{R}^n$  Electrical conductivity tensor  $A(x) = (a_{ij}(x))_{i,j=1}^n$ ,  $x \in Q$   
 $(E_l)_{l=1}^m$ ,  $Z := (Z_l)_{l=1}^m \in \mathbb{R}_+^m$   $I := (I_l)_{l=1}^m \in \mathbb{R}^m$  is called *current pattern*

$$\sum_{l=1}^m I_l = 0$$

$Q \in \mathbb{R}^n$  Electrical conductivity tensor  $A(x) = (a_{ij}(x))_{i,j=1}^n$ ,  $x \in Q$   
 $(E_l)_{l=1}^m$ ,  $Z := (Z_l)_{l=1}^m \in \mathbb{R}_+^m$   $I := (I_l)_{l=1}^m \in \mathbb{R}^m$  is called *current pattern*

$$\sum_{l=1}^m I_l = 0$$

$U := (U_l)_{l=1}^m \in \mathbb{R}^m$  – induced constant voltage on electrodes

$Q \in \mathbb{R}^n$  Electrical conductivity tensor  $A(x) = (a_{ij}(x))_{i,j=1}^n$ ,  $x \in Q$   
 $(E_l)_{l=1}^m$ ,  $Z := (Z_l)_{l=1}^m \in \mathbb{R}_+^m$   $I := (I_l)_{l=1}^m \in \mathbb{R}^m$  is called *current pattern*

$$\sum_{l=1}^m I_l = 0$$

$U := (U_l)_{l=1}^m \in \mathbb{R}^m$  – induced constant voltage on electrodes

$$\sum_{l=1}^m U_l = 0$$

# EIT Mathematical Model

Electrostatic potential  $u : Q \rightarrow \mathbb{R}$  & boundary voltages  $U$  on  $(E_l)_{l=1}^m$

# EIT Mathematical Model

Electrostatic potential  $u : Q \rightarrow \mathbb{R}$  & boundary voltages  $U$  on  $(E_l)_{l=1}^m$

$$-\sum_{i,j=1}^n (a_{ij}(x)u_{x_j})_{x_i} = 0, \quad x \in Q$$

# EIT Mathematical Model

Electrostatic potential  $u : Q \rightarrow \mathbb{R}$  & boundary voltages  $U$  on  $(E_l)_{l=1}^m$

$$-\sum_{i,j=1}^n (a_{ij}(x)u_{x_j})_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

# EIT Mathematical Model

Electrostatic potential  $u : Q \rightarrow \mathbb{R}$  & boundary voltages  $U$  on  $(E_l)_{l=1}^m$

$$-\sum_{i,j=1}^n (a_{ij}(x)u_{x_j})_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

$$u(x) + Z_l \frac{\partial u(x)}{\partial \mathcal{N}} = U_l, \quad x \in E_l, \quad l = \overline{1, m}$$

Electrostatic potential  $u : Q \rightarrow \mathbb{R}$  & boundary voltages  $U$  on  $(E_l)_{l=1}^m$

$$-\sum_{i,j=1}^n (a_{ij}(x)u_{x_j})_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

$$u(x) + Z_l \frac{\partial u(x)}{\partial \mathcal{N}} = U_l, \quad x \in E_l, \quad l = \overline{1, m}$$

$$\int_{E_l} \frac{\partial u(x)}{\partial \mathcal{N}} ds = I_l, \quad l = \overline{1, m}$$

# EIT Mathematical Model

Electrostatic potential  $u : Q \rightarrow \mathbb{R}$  & boundary voltages  $U$  on  $(E_l)_{l=1}^m$

$$-\sum_{i,j=1}^n (a_{ij}(x)u_{x_j})_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

$$u(x) + Z_l \frac{\partial u(x)}{\partial \mathcal{N}} = U_l, \quad x \in E_l, \quad l = \overline{1, m}$$

$$\int_{E_l} \frac{\partial u(x)}{\partial \mathcal{N}} ds = I_l, \quad l = \overline{1, m}$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = \sum_{i,j} a_{ij}(x)u_{x_j} \nu^i$$

# EIT Mathematical Model

Electrostatic potential  $u : Q \rightarrow \mathbb{R}$  & boundary voltages  $U$  on  $(E_l)_{l=1}^m$

$$-\sum_{i,j=1}^n (a_{ij}(x)u_{x_j})_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

$$u(x) + Z_l \frac{\partial u(x)}{\partial \mathcal{N}} = U_l, \quad x \in E_l, \quad l = \overline{1, m}$$

$$\int_{E_l} \frac{\partial u(x)}{\partial \mathcal{N}} ds = I_l, \quad l = \overline{1, m}$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = \sum_{i,j} a_{ij}(x)u_{x_j} \nu^i$$

$$\sum_{i,j=1}^n a_{ij}(x)\xi_i\xi_j \geq \mu \sum_{i=1}^n \xi_i^2, \quad \forall \xi \in \mathbb{R}^n; \quad \mu > 0.$$

**EIT Problem:** *Given electrical conductivity tensor  $A$ , electrode contact impedance vector  $Z$ , and electrode current pattern  $I$  it is required to find electrostatic potential  $u$  and electrode voltages  $U$ :*

$$(A, Z, I) \longrightarrow (u, U)$$

**EIT Problem:** Given electrical conductivity tensor  $A$ , electrode contact impedance vector  $Z$ , and electrode current pattern  $I$  it is required to find electrostatic potential  $u$  and electrode voltages  $U$ :

$$(A, Z, I) \longrightarrow (u, U)$$

- ▶ K.-S. Cheng, D. Isaacson, J.C. Newell and D.G. Gisser, Electrode models for electric current computed tomography, *IEEE Trans. Biomed. Engrg.*, 3, **36**, 1989, 918-924.
- ▶ E. Somersalo, M. Cheney and D. Isaacson, Existence and uniqueness for electrode models for electric current computed tomography, *SIAM Journal on Applied Mathematics*, **52** (1992), 1023–1040.

**Inverse EIT Problem:** *Given electrode contact impedance vector  $Z$ , electrode current pattern  $I$  and boundary electrode measurement  $U^*$ , it is required to find electrostatic potential  $u$  and electrical conductivity tensor  $A$ .*

**Inverse EIT Problem:** Given electrode contact impedance vector  $Z$ , electrode current pattern  $I$  and boundary electrode measurement  $U^*$ , it is required to find electrostatic potential  $u$  and electrical conductivity tensor  $A$ .

- ▶ A.P. Calderon, On an inverse boundary value problem, in *Seminar on Numerical Analysis and Its Applications to Continuum Physics*, Soc. Brasileira de Matematica, Rio de Janeiro, (1980), 65–73.

**Inverse EIT Problem:** Given electrode contact impedance vector  $Z$ , electrode current pattern  $I$  and boundary electrode measurement  $U^*$ , it is required to find electrostatic potential  $u$  and electrical conductivity tensor  $A$ .

- ▶ A.P. Calderon, On an inverse boundary value problem, in *Seminar on Numerical Analysis and Its Applications to Continuum Physics, Soc. Brasileira de Matematica, Rio de Janeiro*, (1980), 65–73.
- ▶ U.G. Abdulla, V. Bukshynov, S. Seif, Cancer Detection through Electrical Impedance Tomography and Optimal Control Theory: Theoretical and Computational Analysis, *Mathematical Biosciences and Engineering*, **18**, 4(2021), 4834-4859.
- ▶ U.G. Abdulla, S.Seif, Discretization and Convergence of the EIT Optimal Control Problem in Sobolev Spaces with Dominating Mixed Smoothness, *Contemporary Mathematics*, Volume **784**, 2023.

# Optimal Control Problem

# Optimal Control Problem

$$\mathcal{J}(v) = \sum_{l=1}^m \left| \int_{E_l} \frac{U_l - u(x)}{Z_l} ds - I_l \right|^2 + \beta |U - U^*|^2 \rightarrow \min$$

# Optimal Control Problem

$$\mathcal{J}(v) = \sum_{l=1}^m \left| \int_{E_l} \frac{U_l - u(x)}{Z_l} ds - I_l \right|^2 + \beta |U - U^*|^2 \rightarrow \min$$

$$V_R = \left\{ v = (A, U) \in \left( L_\infty(Q; \mathbb{M}^{n \times n}) \cap H^\epsilon(Q; \mathbb{M}^{n \times n}) \right) \times \mathbb{R}^m \mid \sum_{l=1}^m U_l = 0, \right. \\ \left. \|A\|_{L_\infty} + \|A\|_{H^\epsilon} + |U| \leq R, \xi^T A \xi \geq \mu |\xi|^2, \forall \xi \in \mathbb{R}^n, \mu > 0 \right\}$$

# Optimal Control Problem

$$\mathcal{J}(v) = \sum_{l=1}^m \left| \int_{E_l} \frac{U_l - u(x)}{Z_l} ds - I_l \right|^2 + \beta |U - U^*|^2 \rightarrow \min$$

$$V_R = \{v = (A, U) \in (L_\infty(Q; \mathbb{M}^{n \times n}) \cap H^\epsilon(Q; \mathbb{M}^{n \times n})) \times \mathbb{R}^m \mid \sum_{l=1}^m U_l = 0,$$

$$\|A\|_{L_\infty} + \|A\|_{H^\epsilon} + |U| \leq R, \quad \xi^T A \xi \geq \mu |\xi|^2, \quad \forall \xi \in \mathbb{R}^n, \quad \mu > 0\}$$

$$- \sum_{i,j=1}^n (a_{ij}(x) u_{x_j})_{x_i} = 0, \quad x \in Q$$

# Optimal Control Problem

$$\mathcal{J}(v) = \sum_{l=1}^m \left| \int_{E_l} \frac{U_l - u(x)}{Z_l} ds - I_l \right|^2 + \beta |U - U^*|^2 \rightarrow \min$$

$$V_R = \{v = (A, U) \in (L_\infty(Q; \mathbb{M}^{n \times n}) \cap H^\epsilon(Q; \mathbb{M}^{n \times n})) \times \mathbb{R}^m \mid \sum_{l=1}^m U_l = 0,$$

$$\|A\|_{L_\infty} + \|A\|_{H^\epsilon} + |U| \leq R, \quad \xi^T A \xi \geq \mu |\xi|^2, \quad \forall \xi \in \mathbb{R}^n, \quad \mu > 0\}$$

$$- \sum_{i,j=1}^n (a_{ij}(x) u_{x_j})_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

# Optimal Control Problem

$$\mathcal{J}(v) = \sum_{l=1}^m \left| \int_{E_l} \frac{U_l - u(x)}{Z_l} ds - I_l \right|^2 + \beta |U - U^*|^2 \rightarrow \min$$

$$V_R = \{v = (A, U) \in (L_\infty(Q; \mathbb{M}^{n \times n}) \cap H^\epsilon(Q; \mathbb{M}^{n \times n})) \times \mathbb{R}^m \mid \sum_{l=1}^m U_l = 0,$$

$$\|A\|_{L_\infty} + \|A\|_{H^\epsilon} + |U| \leq R, \quad \xi^T A \xi \geq \mu |\xi|^2, \quad \forall \xi \in \mathbb{R}^n, \quad \mu > 0\}$$

$$- \sum_{i,j=1}^n (a_{ij}(x) u_{x_j})_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

$$u(x) + Z_l \frac{\partial u(x)}{\partial \mathcal{N}} = U_l, \quad x \in E_l, \quad l = \overline{1, m}$$

# Optimal Control Problem with Increased Input Data

$$U^1 = U, I^1 = I, U^j = (U_j, \dots, U_m, U_1, \dots, U_{j-1}), j = 2, \dots, m$$

# Optimal Control Problem with Increased Input Data

$$U^1 = U, I^1 = I, U^j = (U_j, \dots, U_m, U_1, \dots, U_{j-1}), j = 2, \dots, m$$

$$\mathcal{K}(v) = \sum_{j=1}^m \sum_{l=1}^m \left| \int_{E_l} \frac{U_l^j - u^j(x)}{Z_l} ds - I_l^j \right|^2 + \beta |U - U^*|^2 \rightarrow \min \quad (0.1)$$

$$u^j = u^j(\cdot; A, U^j) \in H^1(Q), j = 1, \dots, m$$

# Optimal Control Problem with Increased Input Data

$$U^1 = U, I^1 = I, U^j = (U_j, \dots, U_m, U_1, \dots, U_{j-1}), j = 2, \dots, m$$

$$\mathcal{K}(v) = \sum_{j=1}^m \sum_{l=1}^m \left| \int_{E_l} \frac{U_l^j - u^j(x)}{Z_l} ds - I_l^j \right|^2 + \beta |U - U^*|^2 \rightarrow \min \quad (0.1)$$

$$u^j = u^j(\cdot; A, U^j) \in H^1(Q), j = 1, \dots, m$$

$$- \sum_{i,j=1}^n (a_{ij}(x) u_{x_j}^j)_{x_i} = 0, \quad x \in Q$$

# Optimal Control Problem with Increased Input Data

$$U^1 = U, I^1 = I, U^j = (U_j, \dots, U_m, U_1, \dots, U_{j-1}), j = 2, \dots, m$$

$$\mathcal{K}(v) = \sum_{j=1}^m \sum_{l=1}^m \left| \int_{E_l} \frac{U_l^j - u^j(x)}{Z_l} ds - I_l^j \right|^2 + \beta |U - U^*|^2 \rightarrow \min \quad (0.1)$$

$$u^j = u^j(\cdot; A, U^j) \in H^1(Q), j = 1, \dots, m$$

$$-\sum_{i,j=1}^n (a_{ij}(x) u_{x_j}^j)_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u^j(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

# Optimal Control Problem with Increased Input Data

$$U^1 = U, I^1 = I, U^j = (U_j, \dots, U_m, U_1, \dots, U_{j-1}), j = 2, \dots, m$$

$$\mathcal{K}(v) = \sum_{j=1}^m \sum_{l=1}^m \left| \int_{E_l} \frac{U_l^j - u^j(x)}{Z_l} ds - I_l^j \right|^2 + \beta |U - U^*|^2 \rightarrow \min \quad (0.1)$$

$$u^j = u^j(\cdot; A, U^j) \in H^1(Q), j = 1, \dots, m$$

$$- \sum_{i,j=1}^n (a_{ij}(x) u_{x_j}^j)_{x_i} = 0, \quad x \in Q$$

$$\frac{\partial u^j(x)}{\partial \mathcal{N}} = 0, \quad x \in \partial Q - \bigcup_{l=1}^m E_l$$

$$u^j(x) + Z_l \frac{\partial u^j(x)}{\partial \mathcal{N}} = U_l^j, \quad x \in E_l, l = \overline{1, m}$$

# Theorem on Fréchet Differentiability

The functional  $\mathcal{K}(v)$  is differentiable on  $V_R$  in the sense of Fréchet and the Fréchet gradient  $\mathcal{K}'(\sigma, U) = \left( \mathcal{K}'_A(A, U), \mathcal{K}'_U(A, U) \right) \in \mathcal{L}' \times \mathbb{R}^m$  is

$$\mathcal{K}'_A(A, U) = - \left( \sum_{j=1}^m \psi_{x_p}^j u_{x_q}^j \right)_{p,q=1}^n,$$

$$\mathcal{K}'_U(A, U) = \left( \sum_{j=1}^m \sum_{l=1}^m 2 \left[ \int_{E_l} \frac{U_l^j - u_j}{Z_l} ds - I_l^j \right] \int_{E_l} \frac{\delta_{l, \theta_{kj}} - w^{\theta_{kj}}(s)}{Z_l} ds \right)_{k=1}^m$$

where  $\psi^j(\cdot)$ ,  $j = 1, \dots, m$ , be a solution of the adjointed PDE problem with  $u(\cdot)$ ,  $U$  and  $I$  replaced with  $u^j(\cdot)$ ,  $U^j$ ,  $I^j$  respectively, and

$$\theta_{kj} = \begin{cases} k - j + 1, & \text{if } j \leq k, \\ m + k - j + 1, & \text{if } j > k. \end{cases}$$

# Gradient Method in a Banach Space

$$\tilde{a}_{ij}^{N+1}(x) = a_{ij}^N(x) + \alpha_N \psi_{x_i}^N u_{x_j}^N, \quad i, j = 1, \dots, n,$$

# Gradient Method in a Banach Space

$$\tilde{a}_{ij}^{N+1}(x) = a_{ij}^N(x) + \alpha_N \psi_{x_i}^N u_{x_j}^N, \quad i, j = 1, \dots, n,$$

$$\begin{aligned} \tilde{U}_k^{N+1} = U_k^N - \alpha_N \left[ \sum_{l=1}^m 2 \left( \int_{E_l} \frac{U_l^N - u^N(s)}{Z_l} ds - I_l \right) \int_{E_l} \frac{1}{Z_l} (\delta_{lk} - w_k^N(s)) ds \right. \\ \left. + 2\beta(U_k^N - U_k^*) \right], \quad k = 1, \dots, m. \end{aligned}$$

# Gradient Method in a Banach Space

$$\tilde{a}_{ij}^{N+1}(x) = a_{ij}^N(x) + \alpha_N \psi_{x_i}^N u_{x_j}^N, \quad i, j = 1, \dots, n,$$

$$\begin{aligned} \tilde{U}_k^{N+1} = U_k^N - \alpha_N \left[ \sum_{l=1}^m 2 \left( \int_{E_l} \frac{U_l^N - u^N(s)}{Z_l} ds - I_l \right) \int_{E_l} \frac{1}{Z_l} (\delta_{lk} - w_k^N(s)) ds \right. \\ \left. + 2\beta(U_k^N - U_k^*) \right], \quad k = 1, \dots, m. \end{aligned}$$

$$a_{ij}^{N+1}(x) = \begin{cases} \mu, & \text{if } \tilde{a}_{ij}^{N+1}(x) \leq \mu, \\ \tilde{a}_{ij}^{N+1}(x), & \text{if } \mu \leq \tilde{a}_{ij}^{N+1}(x) \leq R, \\ R, & \text{if } \tilde{a}_{ij}^{N+1}(x) > R. \end{cases}$$

$$U_k^{N+1} = \tilde{U}_k^{N+1} - \frac{1}{m} \sum_{k=1}^m \tilde{U}_k^{N+1} \quad k = 1, \dots, m$$

# Discretization via Finite Differences

$$\mathcal{J}_h([v]_h) = \sum_{l=1}^m \left( \sum_{A(\hat{E}_{lh})} \Gamma_{l\alpha} \frac{U_l - u_\alpha}{Z_l} - I_l \right)^2 + \beta |U - U^*|^2 \rightarrow \min$$

# Discretization via Finite Differences

$$\mathcal{J}_h([v]_h) = \sum_{l=1}^m \left( \sum_{A(\hat{E}_{lh})} \Gamma_{l\alpha} \frac{U_l - u_\alpha}{Z_l} - I_l \right)^2 + \beta |U - U^*|^2 \rightarrow \min$$

$$F_h^R := \left\{ [v]_h = ([\sigma]_h, U) \mid \sum_{l=1}^m U_l = 0, \|[\sigma]_h\|_{\tilde{H}^1(Q_h)}^2 + |U|_{\mathbb{R}^m}^2 \leq R^2, \right. \\ \left. \sigma_\alpha \geq \sigma_0 > 0, \forall \alpha \in A(Q_h) \right\}$$

# Discretization via Finite Differences

$$\mathcal{J}_h([v]_h) = \sum_{l=1}^m \left( \sum_{A(\hat{E}_{lh})} \Gamma_{l\alpha} \frac{U_l - u_\alpha}{Z_l} - I_l \right)^2 + \beta |U - U^*|^2 \rightarrow \min$$

$$F_h^R := \left\{ [v]_h = ([\sigma]_h, U) \mid \sum_{l=1}^m U_l = 0, \|[\sigma]_h\|_{\tilde{H}^1(Q_h)}^2 + |U|_{\mathbb{R}^m}^2 \leq R^2, \right. \\ \left. \sigma_\alpha \geq \sigma_0 > 0, \forall \alpha \in A(Q_h) \right\}$$

$$h^n \sum_{A(Q_h^+)} \sigma_\alpha \sum_{i=1}^n u_{\alpha x_i} \eta_{\alpha x_i} + \sum_{l=1}^m \frac{1}{Z_l} \sum_{A(\hat{E}_{lh})} \Gamma_{l\alpha} u_\alpha \eta_\alpha + J_h([u]_h, [\eta]_h) \\ = \sum_{l=1}^m \frac{U_l}{Z_l} \sum_{A(\hat{E}_{lh})} \Gamma_{l\alpha} \eta_\alpha$$

# Convergence of the Method of Finite Differences

The sequence of discrete optimal control problems  $\mathcal{E}_h$  approximates the optimal control problem  $\mathcal{E}$  with respect to functional, i.e.

$$\lim_{h \rightarrow 0} J_{h^*} = J_*$$

# Convergence of the Method of Finite Differences

The sequence of discrete optimal control problems  $\mathcal{E}_h$  approximates the optimal control problem  $\mathcal{E}$  with respect to functional, i.e.

$$\lim_{h \rightarrow 0} J_{h_*} = J_*$$

Interpolation of the discrete control minimizers are

- ▶ is precompact in Tikhonov topology of  $\tilde{H}^1(Q) \times \mathbb{R}^m$  formed with the product of the weak topology of  $\tilde{H}^1(Q)$  and Euclidean topology of  $\mathbb{R}^m$ ;
- ▶ is precompact in Tikhonov topology of  $C^{0,\mu}(\bar{Q}) \times \mathbb{R}^m$ ,  $0 < \mu < \frac{1}{2}$  formed with the product of the strong topology of Hölder space  $C^{0,\mu}(\bar{Q})$  and Euclidean topology of  $\mathbb{R}^m$ ;

and all the corresponding limit points  $v_* = (\sigma_*, U_*)$  are optimal controls.

# Convergence of the Method of Finite Differences

The sequence of discrete optimal control problems  $\mathcal{E}_h$  approximates the optimal control problem  $\mathcal{E}$  with respect to functional, i.e.

$$\lim_{h \rightarrow 0} J_{h_*} = J_*$$

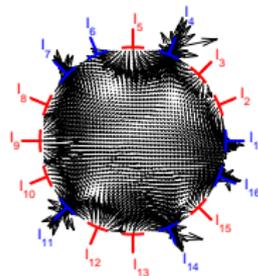
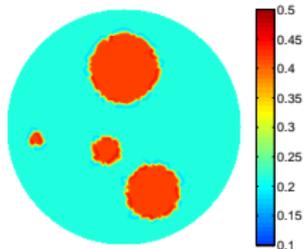
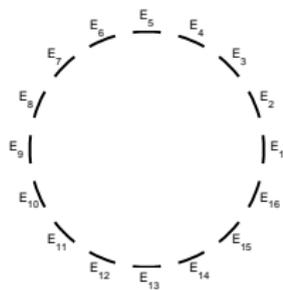
Interpolation of the discrete control minimizers are

- ▶ is precompact in Tikhonov topology of  $\tilde{H}^1(Q) \times \mathbb{R}^m$  formed with the product of the weak topology of  $\tilde{H}^1(Q)$  and Euclidean topology of  $\mathbb{R}^m$ ;
- ▶ is precompact in Tikhonov topology of  $C^{0,\mu}(\bar{Q}) \times \mathbb{R}^m$ ,  $0 < \mu < \frac{1}{2}$  formed with the product of the strong topology of Hölder space  $C^{0,\mu}(\bar{Q})$  and Euclidean topology of  $\mathbb{R}^m$ ;

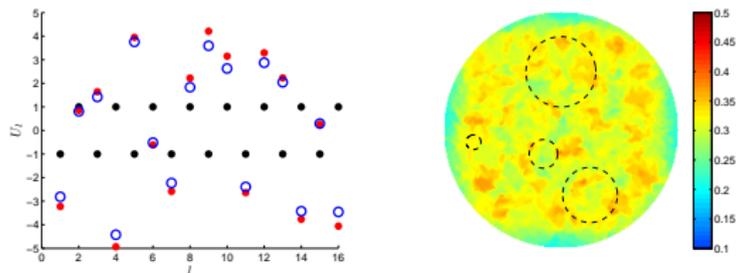
and all the corresponding limit points  $v_* = (\sigma_*, U_*)$  are optimal controls.

- ▶ Multilinear interpolations of the discrete state vectors  $[u([v]_{h',\epsilon})]_{h'}$  converge to the optimal state vector  $u = u(x; v_*)$  weakly in  $H^1(Q)$ , strongly in  $L_2(Q)$ , and almost everywhere on  $Q$ .

# Numerical Results



# Cancer Detection through Electrical Impedance Tomography (EIT) and Optimal Control Theory



# Cancer Detection through Electrical Impedance Tomography (EIT) and Optimal Control Theory

