

Multiplane Lensing: Theory and Applications

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Setup

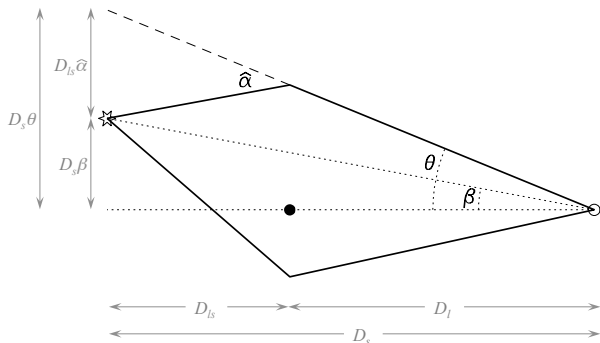
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Standard geometry



Euclidean geometry in a plane:

$$D_s \beta = D_s \theta - D_{ls} \hat{\alpha}(\theta)$$

$$\beta = \theta - \alpha(\theta) \quad \text{where } \alpha = \frac{D_{ls}}{D_s} \hat{\alpha}$$

Extend to FRW cosmology by using angular diameter distances.

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Standard theory

Scaled gravitational potential:

$$\nabla^2 \phi = 2\kappa$$

Time delay:

$$\tau(\mathbf{x}; \mathbf{x}_s) = \frac{1+z_l}{c} \frac{D_l D_s}{D_{ls}} \left[\frac{1}{2} |\mathbf{x} - \mathbf{x}_s|^2 - \phi(\mathbf{x}) \right]$$

Fermat's principle $\nabla_{\mathbf{x}} \tau = 0$ gives lens equation:

$$\mathbf{x}_s = \mathbf{x} - \nabla \phi(\mathbf{x})$$

Distortion/magnification from Jacobian:

$$\mu = \left(\frac{\partial \mathbf{x}_s}{\partial \mathbf{x}} \right)^{-1} = \begin{bmatrix} 1 - \phi_{xx} & -\phi_{xy} \\ -\phi_{xy} & 1 - \phi_{yy} \end{bmatrix}^{-1}$$

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Convergence and shear

Matrix of second derivatives:

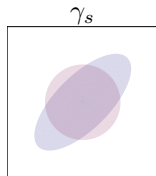
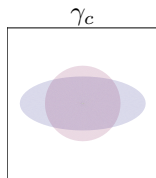
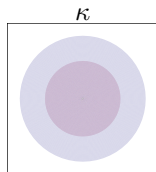
$$\begin{aligned}\mathbf{\Gamma} &= \begin{bmatrix} \phi_{xx} & \phi_{xy} \\ \phi_{xy} & \phi_{yy} \end{bmatrix} \\ &= \begin{bmatrix} \kappa + \gamma_c & \gamma_s \\ \gamma_s & \kappa - \gamma_c \end{bmatrix} \\ &= \kappa \mathbf{I} + \begin{bmatrix} \gamma_c & \gamma_s \\ \gamma_s & -\gamma_c \end{bmatrix}\end{aligned}$$

where

$$\kappa = \frac{1}{2} (\phi_{xx} + \phi_{yy})$$

$$\gamma_c = \frac{1}{2} (\phi_{xx} - \phi_{yy})$$

$$\gamma_s = \phi_{xy}$$



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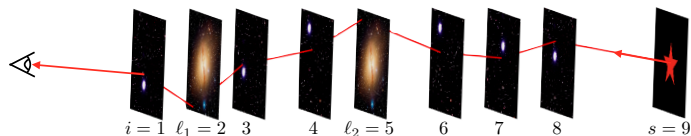
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Multiple scattering

Light rays probably suffer multiple deflections:



(Figure: McCully et al. 2014)

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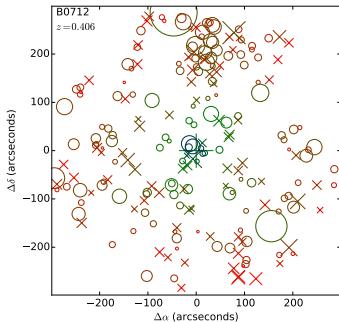
How can we handle “external” effects?

“Direct” approach:

- ▶ find galaxies and groups along the line of sight
- ▶ build them into 3-d lens models

(Williams et al. 2006; Momcheva et al. 2006; Wong et al. 2011;

McCully thesis; McCully et al. in prep.)



“Corrective” approach:

- ▶ fit for external shear
- ▶ calibrate external convergence statistically
- ▶ apply κ_{ext} as posterior correction (mass sheet transformation)

(papers by Collett, Fassnacht, Greene, Hilbert, Suyu, et al.)

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Multiplane lensing: Formalism

Lens equation: trace light ray “backwards”

$$\mathbf{x}_j = \mathbf{x}_1 - \sum_{i=1}^{j-1} \beta_{ij} \boldsymbol{\alpha}_i(\mathbf{x}_i)$$

Time delay:

$$T = \sum_{i=1}^{s-1} \tau_{i i+1} \left[\frac{1}{2} |\mathbf{x}_{i+1} - \mathbf{x}_i|^2 - \beta_{i i+1} \phi_i(\mathbf{x}_i) \right]$$

Note:

$$\beta_{ij} = \frac{D_{ij} D_s}{D_j D_{is}} \quad \text{and} \quad \tau_{ij} = \frac{1 + z_i}{c} \frac{D_i D_j}{D_{ij}}$$

(e.g., Schneider et al. 1992; Petters et al. 2001; McCully et al. 2014)

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Tidal approximation

Most planes are perturbative, so treat them with a Taylor series:

$$\phi_i(\mathbf{x}) = \cancel{\phi_{i0}} + \cancel{\alpha_{i0}^t \mathbf{x}} + \frac{1}{2} \mathbf{x}^t \mathbf{\Gamma}_{i0} \mathbf{x} + \dots$$

Then:

$$\alpha_i(\mathbf{x}) = \mathbf{\Gamma}_{i0} \mathbf{x} + \dots$$

$$\mathbf{\Gamma}_i(\mathbf{x}) = \mathbf{\Gamma}_{i0} + \dots$$

If we drop higher-order terms, this defines the tidal approximation.

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Single plane

Suppose we have one main lens galaxy (ℓ) plus many tidal terms, all in one plane:

$$\begin{aligned}\mathbf{x}_s &= \mathbf{x} - \sum_{i \neq \ell} \mathbf{\Gamma}_i \mathbf{x} - \alpha_\ell(\mathbf{x}) \\ &= (\mathbf{I} - \mathbf{\Gamma}_{\text{tot}}) \mathbf{x} - \alpha_\ell(\mathbf{x})\end{aligned}$$

Remarks:

- ▶ external convergence and shear go into the \mathbf{x} term
- ▶ convergence adds as a scalar, but shear adds as a tensor:

$$\mathbf{\Gamma}_{\text{tot}} = \left(\sum_{i \neq \ell} \kappa_i \right) \mathbf{I} + \sum_{i \neq \ell} \begin{bmatrix} \gamma_{ci} & \gamma_{si} \\ \gamma_{si} & -\gamma_{ci} \end{bmatrix}$$

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Single plane

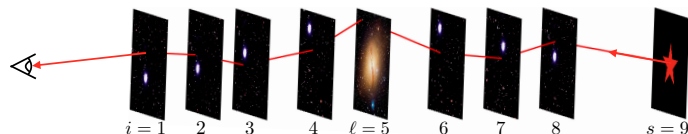
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One “main” plane, many tidal planes



Let the main lens galaxy be in plane l . The mapping to this plane has a sum over **foreground** tidal planes:

$$\mathbf{x}_l = \mathbf{x}_1 - \sum_{i=1}^{l-1} \beta_{il} \Gamma_i \mathbf{x}_i = \mathbf{x}_1 - \sum_{i=1}^{l-1} \beta_{il} \left(\mathbf{x}_1 - \sum_{j=1}^{i-1} \beta_{ji} \Gamma_j \mathbf{x}_j \right)$$

All terms on RHS are linear in \mathbf{x} , so we can write

$$\mathbf{x}_l = \mathbf{B}_l \mathbf{x}_1 \quad \text{where} \quad \mathbf{B}_l = \mathbf{I} - \sum_{i=1}^{l-1} \beta_{ij} \Gamma_i \mathbf{B}_i$$

(e.g., Schneider et al. 1992; McCully et al. 2014)

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One “main” plane

Work through remaining planes, obtain lens equation:

$$\mathbf{x}_s = \mathbf{B}_s \mathbf{x}_1 - \mathbf{C}_{\ell s} \alpha_\ell (\mathbf{B}_\ell \mathbf{x}_1)$$

Propagation between source, main lens, and observer is described by **tensors** that are sums over tidal planes:

$$\mathbf{B}_j = \mathbf{I} - \sum_{i=1, i \neq \ell}^{j-1} \beta_{ij} \Gamma_i \mathbf{B}_i \quad (\text{observer to } j)$$

$$\mathbf{C}_{\ell j} = \beta_{\ell j} \mathbf{I} - \sum_{i=\ell+1}^{j-1} \beta_{ij} \Gamma_i \mathbf{C}_{\ell i} \quad (\text{lens to } j)$$

(e.g., Schneider et al. 1992; McCully et al. 2014)

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Foreground planes: Nonlinear effects

Single main plane lens equation:

$$\mathbf{x}_s = \mathbf{B}_s \mathbf{x}_1 - \mathbf{C}_{\ell s} \alpha_\ell(\mathbf{B}_\ell \mathbf{x}_1)$$

Note:

$$\mathbf{C}_{\ell s}^{-1} \mathbf{x}_s = \mathbf{C}_{\ell s}^{-1} \mathbf{B}_s \mathbf{x}_1 - \alpha_\ell(\mathbf{B}_\ell \mathbf{x}_1)$$

- ▶ first term is effectively a tidal term
- ▶ in second term, having \mathbf{B}_ℓ inside α_ℓ creates **nonlinear effects**

Can we transform away the nonlinear effects? Recall $\mathbf{x}_\ell = \mathbf{B}_\ell \mathbf{x}_1$:

$$\mathbf{C}_{\ell s}^{-1} \mathbf{x}_s = \mathbf{C}_{\ell s}^{-1} \mathbf{B}_s \mathbf{B}_\ell^{-1} \mathbf{x}_\ell - \alpha_\ell(\mathbf{x}_\ell)$$

Looks nice in coordinates in the main lens plane — but we don't observe those coordinates! (Bar-Kana 1996; Schneider 1997; CRK 2003; McCully et al. 2014)

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Lens galaxy at $z_\ell = 0.3$.

Perturber of mass $10^{12} M_\odot$
contributes line-of-sight shear:

$$\mathbf{x}_s = \mathbf{B}_s \mathbf{x}_1 - \mathbf{C}_{\ell s} \boldsymbol{\alpha}_\ell (\mathbf{B}_\ell \mathbf{x}_1)$$

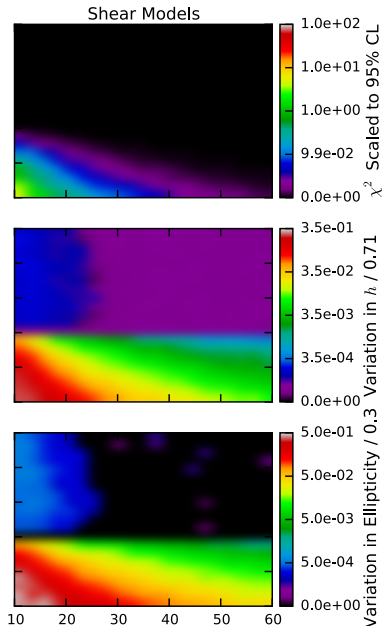
Fit with a simple external shear:

$$\mathbf{x}_s = (\mathbf{I} - \boldsymbol{\Gamma}) \mathbf{x}_1 - \boldsymbol{\alpha}_\ell (\mathbf{x}_1)$$

Vary source position and galaxy orientation, and look at scatter in recovered χ^2 , h , and e .

- ▶ background perturber can be mimicked by external shear
- ▶ foreground perturber cannot

(McCully thesis; McCully et al. in prep.)



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Lessons: I. Nonlinearity

Even if we use the tidal approximation for all perturbers, there are complications due to nonlinearity.

$$\mathbf{x}_s = \mathbf{B}_s \mathbf{x}_1 - \mathbf{C}_{\ell s} \alpha_\ell (\mathbf{B}_\ell \mathbf{x}_1)$$

Direct approach:

- ▶ all planes are built into the lens model
- ▶ planes are calibrated from our observations
- ▶ LOS matrices are computed self-consistently from a 3-d mass model

Corrective approach:

- ▶ three LOS matrices could be calibrated from simulations ... but they would be correlated
- ▶ even then, \mathbf{B}_ℓ must be incorporated into the modeling ... it cannot be applied as a posterior correction

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Lessons: II. Whither κ_{ext} ?

We argued that standard external shear/convergence does not fully account for LOS effects in the lens equation.

The same goes for time delays. Strictly speaking, applying κ_{ext} does not capture all of the LOS effects in time delays and H_0 .

(There **is** a mass sheet transformation [later], but it involves a particular rescaling of the planes. It cannot be used to transform away the planes.)

These are *formal* statements. How important are they in practice?

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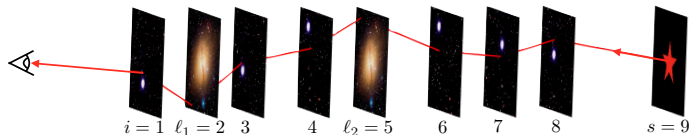
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Multiple “main” planes

Perturbers that are massive and/or projected close to the lens:

- ▶ higher-order terms are non-negligible
- ▶ need to be treated explicitly

Still want to treat other planes as tidal — need hybrid approach.



Arbitrary mixture of “main” and tidal planes. Lens equation:

$$\mathbf{x}_i = \mathbf{B}_i \mathbf{x}_1 - \sum_{\ell \in \{\ell_\mu < i\}} \mathbf{C}_{\ell i} \alpha_\ell(\mathbf{x}_\ell)$$

We also worked through time delays...

(McCully et al. 2014; also Schneider 2014)

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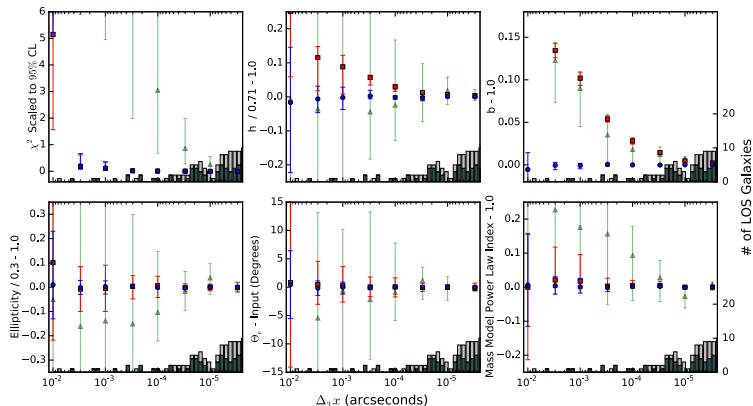
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Quantifying the importance of LOS effects

- ▶ Objective criterion for deciding whether tidal approximation is adequate, based on strength of higher-order terms.
- ▶ Scatter/bias in model results for different ways of treating external effects?



(McCully thesis; McCully, Wong, et al. in prep.)

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Mass sheet transformation: Traditional

Single plane: add uniform sheet and rescale galaxy

$$\alpha'(x) = \lambda\alpha(x) + (1 - \lambda)x$$

This leads to a rescaling of the source plane:

$$x'_s = x - \alpha'(x) = \lambda x - \lambda\alpha(x) = \lambda x_s$$

Such a rescaling cannot be observed unless we know absolute magnifications.

Differential time delays also rescale by λ .

(Falco et al. 1985; and much more)

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Generalized (I)

One main plane plus many tidal planes. Required transformation:

$$\alpha'_\ell(\mathbf{x}_\ell) = \lambda \alpha_\ell(\mathbf{x}_\ell) + (1 - \lambda) \mathbf{C}_{\ell s}^{-1} \mathbf{B}_s \mathbf{B}_\ell^{-1} \mathbf{x}_\ell$$

Differential time delays again rescale by λ .

Note: general case has shear along with a mass sheet.

Key quantity is **effective tidal tensor**,

$$\Gamma_{\text{eff}} = \mathbf{I} - \mathbf{C}_{\ell s}^{-1} \mathbf{B}_s \mathbf{B}_\ell^{-1}$$

In small-shear limit,

$$\Gamma_{\text{eff}} \approx \sum_{i=1, i \neq \ell}^N (1 - \beta) \Gamma_i$$

(McCully et al. 2014; Schneider 2014)

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Generalized (II)

Peter Schneider (1409.0015) found a transformation that applies to multiple main planes, but it has a “curious behavior”:

$$\begin{aligned}\mathbf{x}'_j &= \nu_j \mathbf{x}_j \\ \boldsymbol{\alpha}'_j(\mathbf{x}'_j) &= \lambda \boldsymbol{\alpha}_j(\mathbf{x}_j) + \mathbf{G}_j \mathbf{x}_j\end{aligned}$$

where

	ν_j	\mathbf{G}_j
j odd	1	$(1 - \lambda)\mathcal{D}_j$
j even	λ	$(1 - 1/\lambda)\mathcal{D}_j$

With $0 < \lambda < 1$, we add **positive density to odd planes** and **negative density to even planes**.

Differential time delays again rescale by λ .

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Foreground perturbers create **nonlinear effects**.

- ▶ Image positions in the lens plane are not the same as image position on the sky.

3-d tidal approximation.

- ▶ \mathbf{B}_ℓ (foreground), $\mathbf{C}_{\ell s}$ (background), \mathbf{B}_s (all)
- ▶ effective shear/convergence, $\mathbf{\Gamma}_{\text{eff}} = \mathbf{I} - \mathbf{C}_{\ell s}^{-1} \mathbf{B}_s \mathbf{B}_\ell^{-1}$

Perturbers that are massive and/or projected close to the lens create **higher-order terms**.

- ▶ These perturbers need to be treated explicitly.

Our hybrid framework can handle an arbitrary combination of exact and tidal perturbers.

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