

Automatic multi-band arc detection

Gregor Seidel

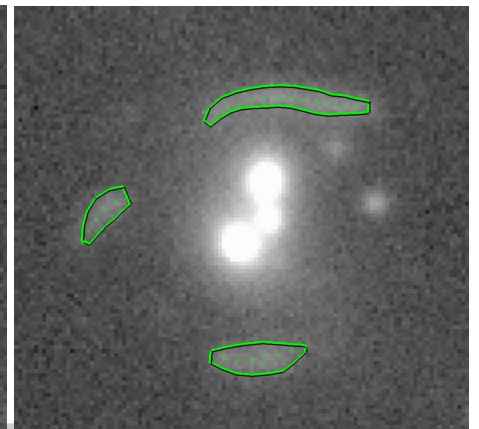
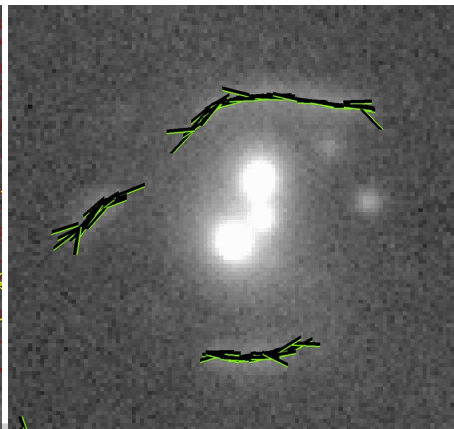
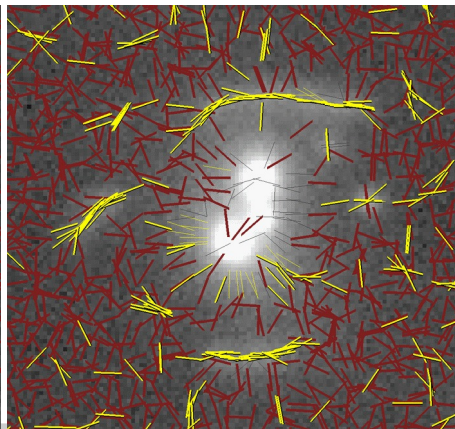
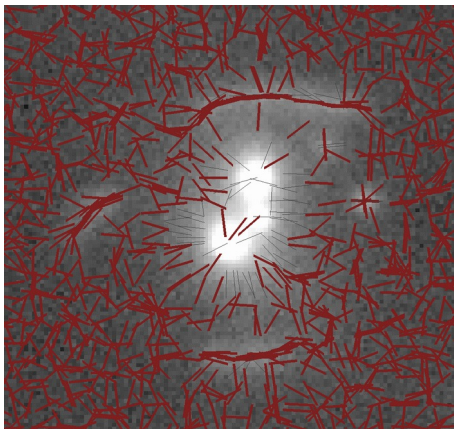
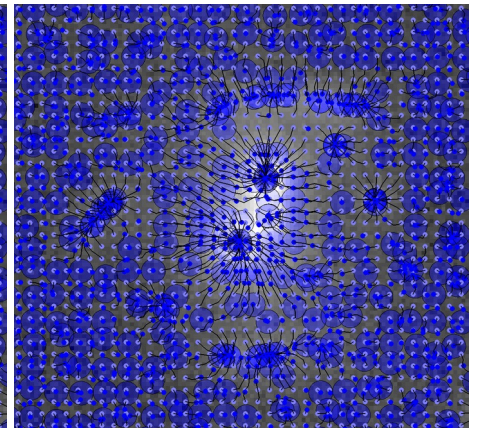
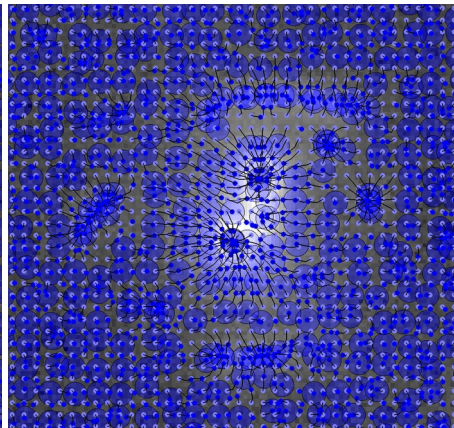
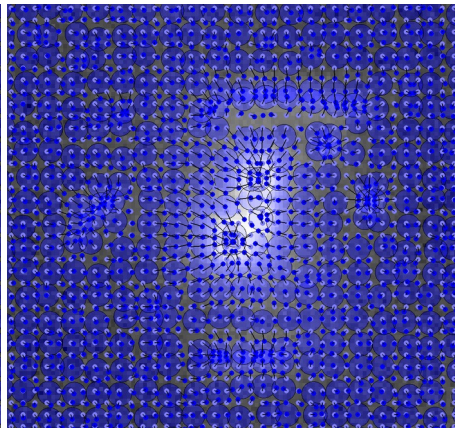
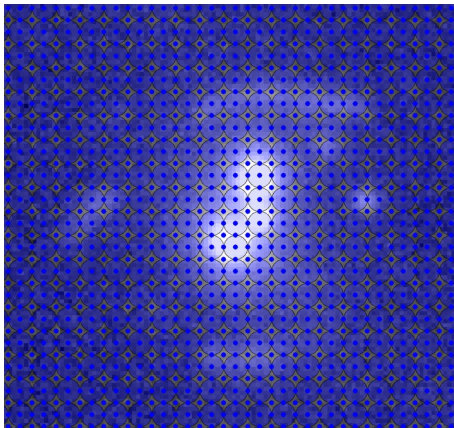
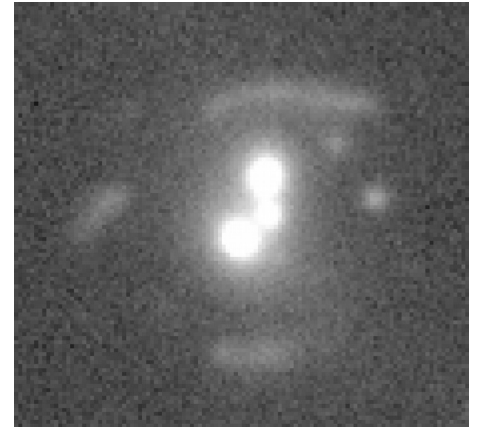
Heidelberg, MPIA

collaborators:

Matteo Maturi, Sebastian Mizera

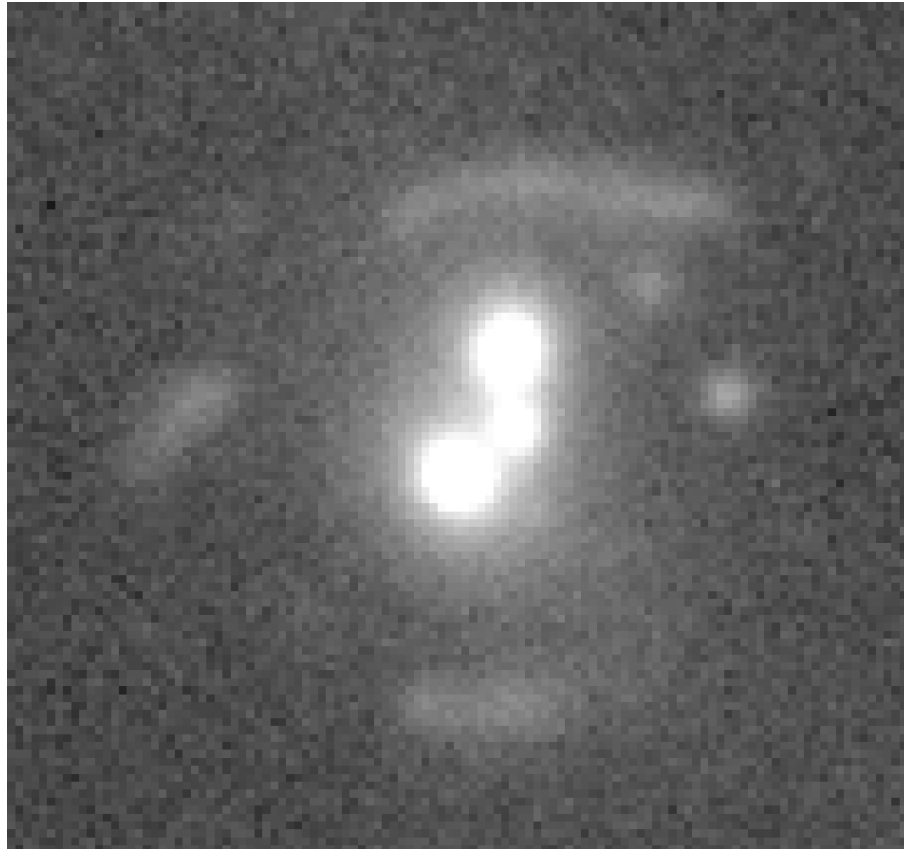
Finding arcs in 1 band

- plain CARS image
- initial cell displacement
- coherent feature detection and segmentation



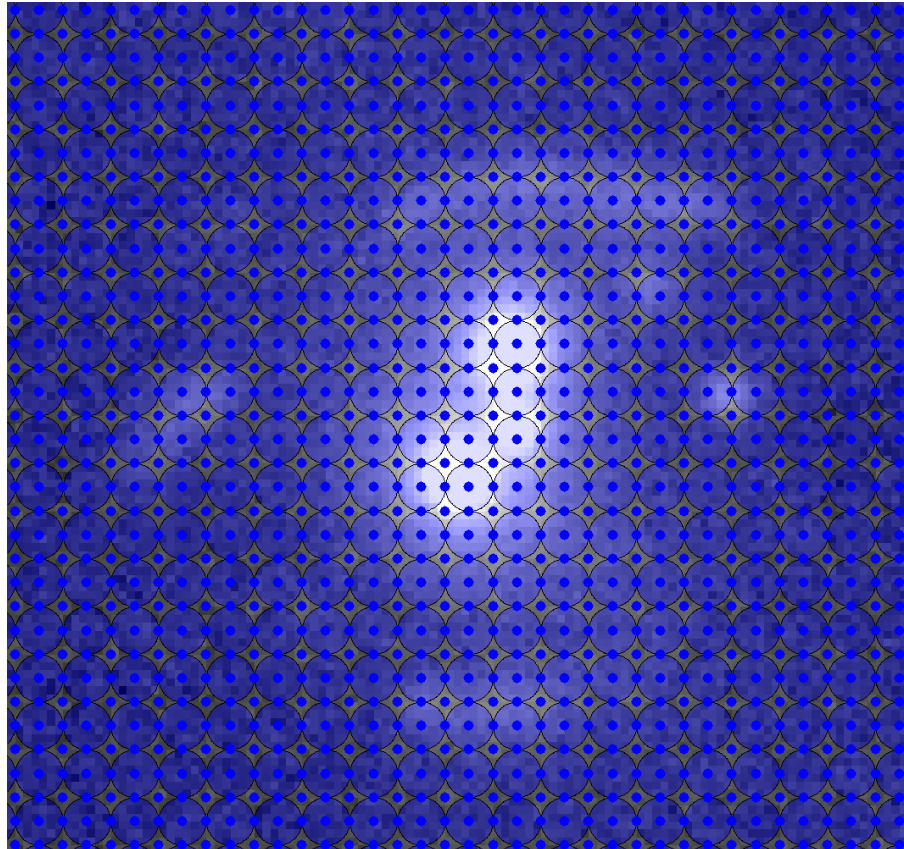
Finding arcs in 1 band

- plain (CARS) image
- initial cell displacement
- coherent feature detection and segmentation



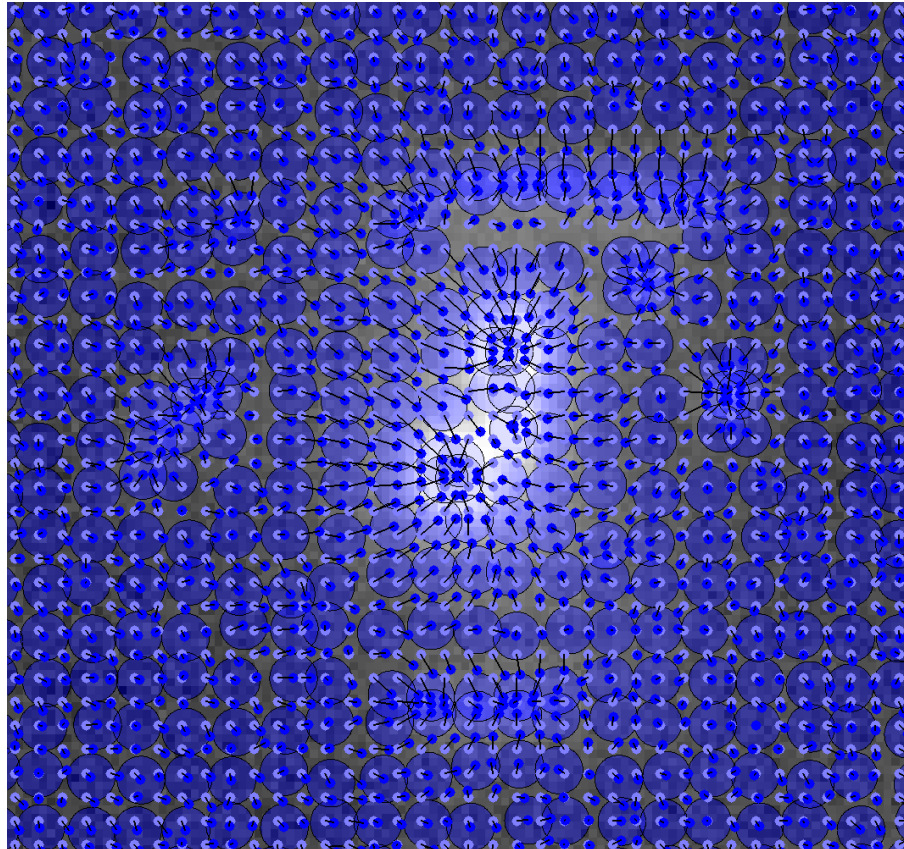
Finding arcs in 1 band

- plain (CARS) image
- **initial cell displacement**
- coherent feature detection and segmentation



Finding arcs in 1 band

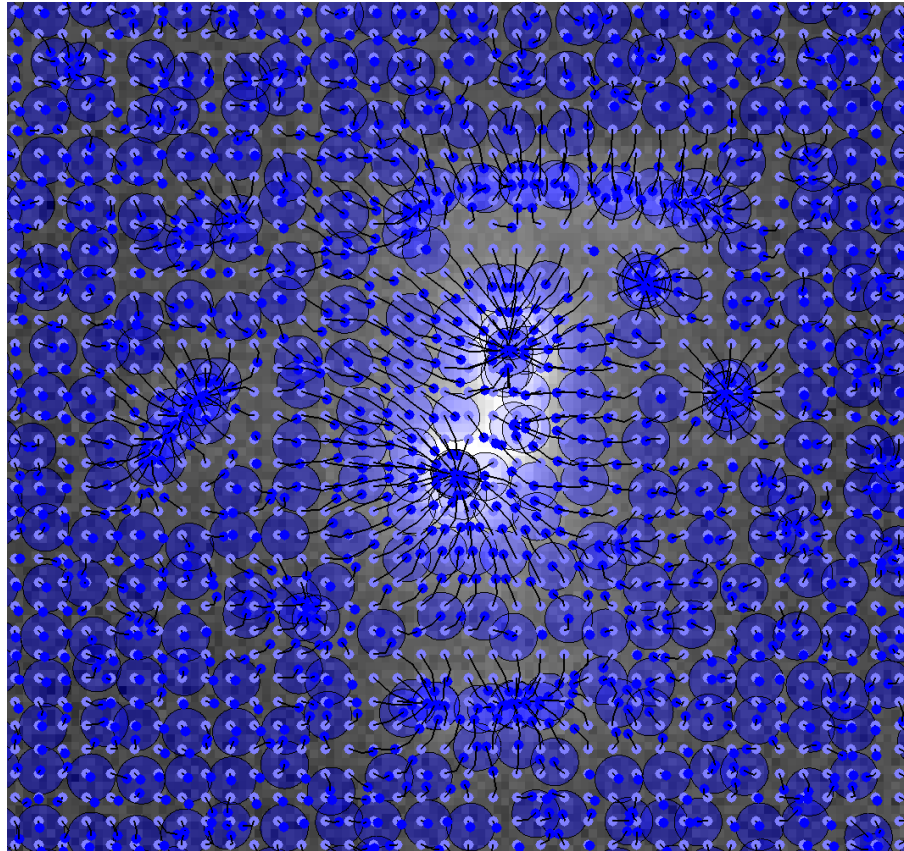
- plain (CARS) image
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1st moments

Finding arcs in 1 band

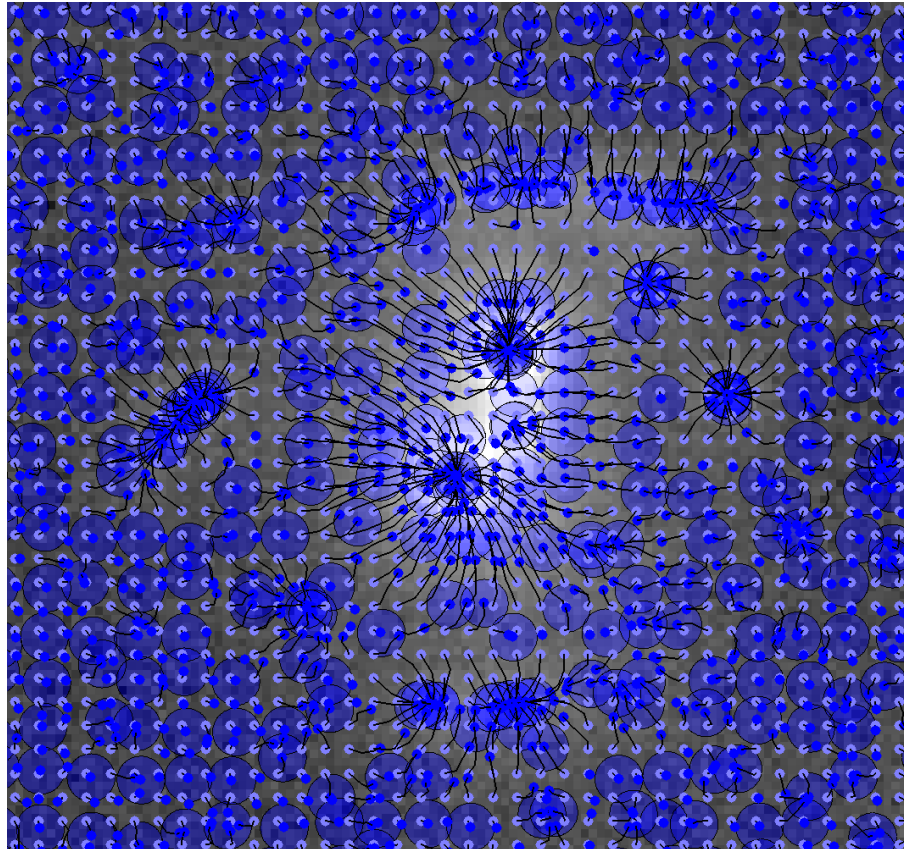
- plain (CARS) image
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1st moments

Finding arcs in 1 band

- plain (CARS) image
- **initial cell displacement**
- coherent feature detection and segmentation



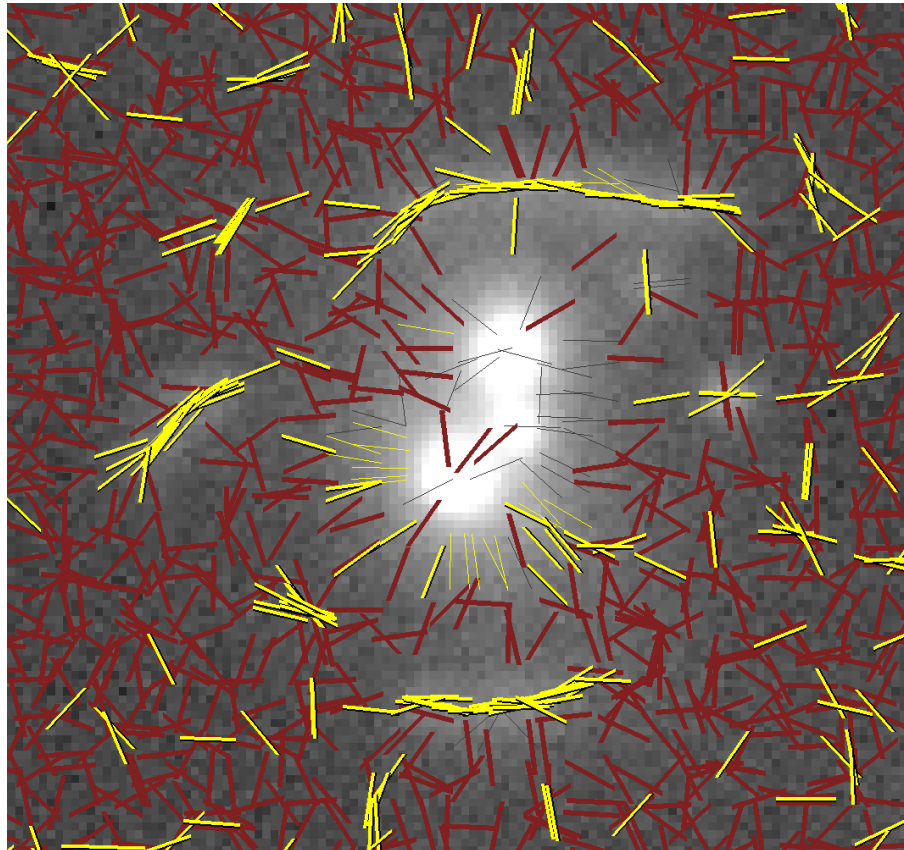
1st moments

Finding arcs in 1 band

- plain (CARS) image
- initial cell displacement
- **coherent feature detection** and segmentation

cell coherency:

$$c^{kl} = e^k e^l \max\left(0, 1 - \frac{|(x^k - x^l) \times e^k|}{d}\right)$$

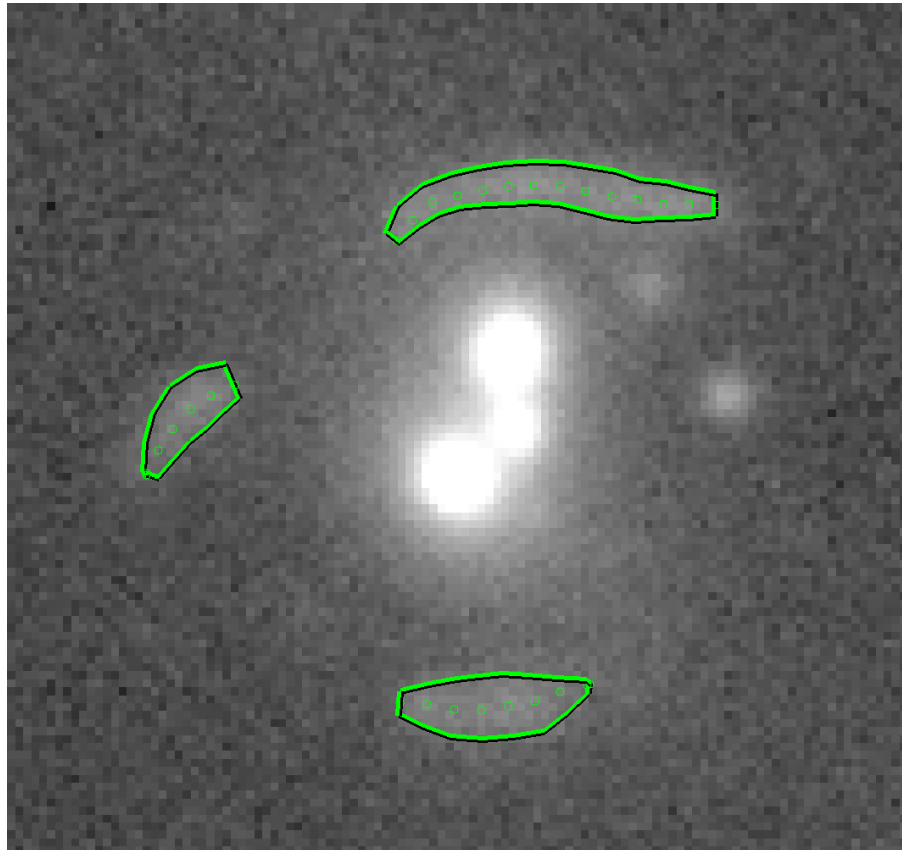


2nd moments,
ellipticity

$$\chi = \frac{Q_{11} - Q_{22} + 2iQ_{12}}{Q_{11} + Q_{22}}$$

Finding arcs in 1 band

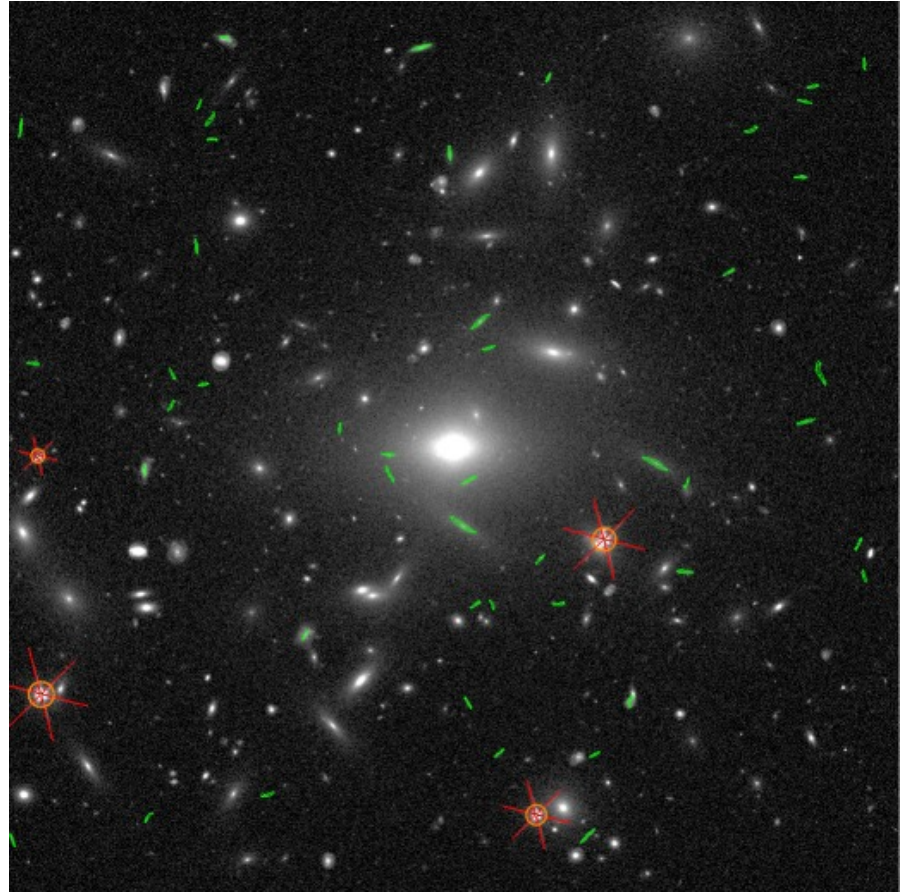
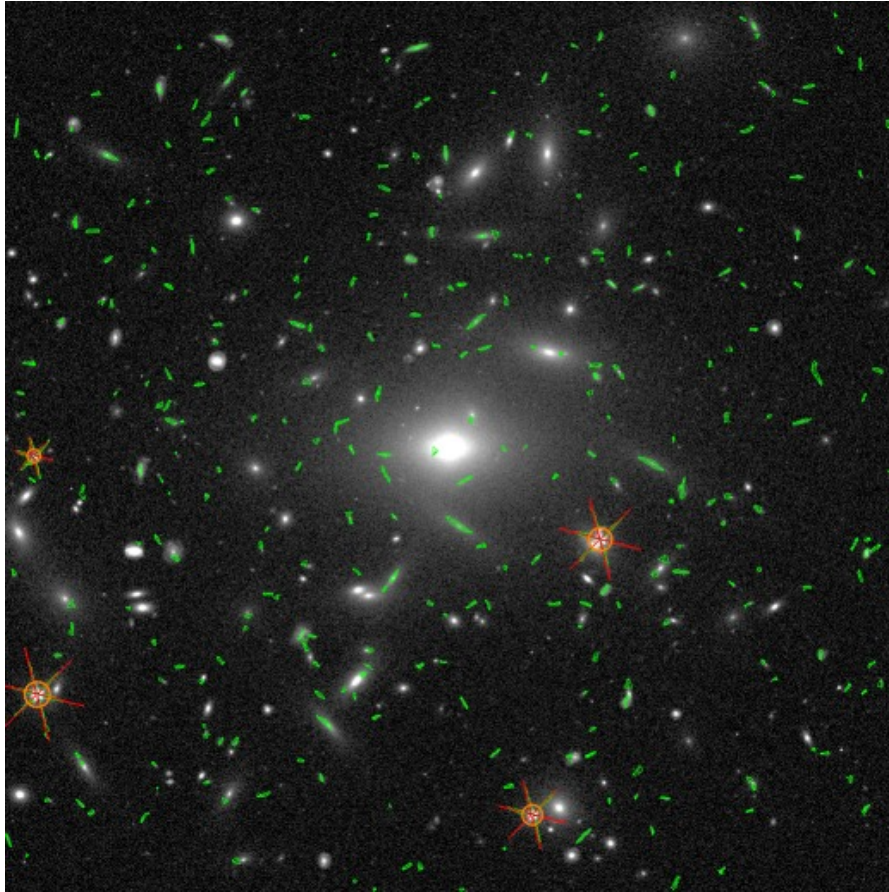
- plain (CARS) image
- initial cell displacement
- coherent feature detection and **segmentation**



Active Contour
Segmentation

(Kass et al. 1988)

Select likely arcs by shape & flux

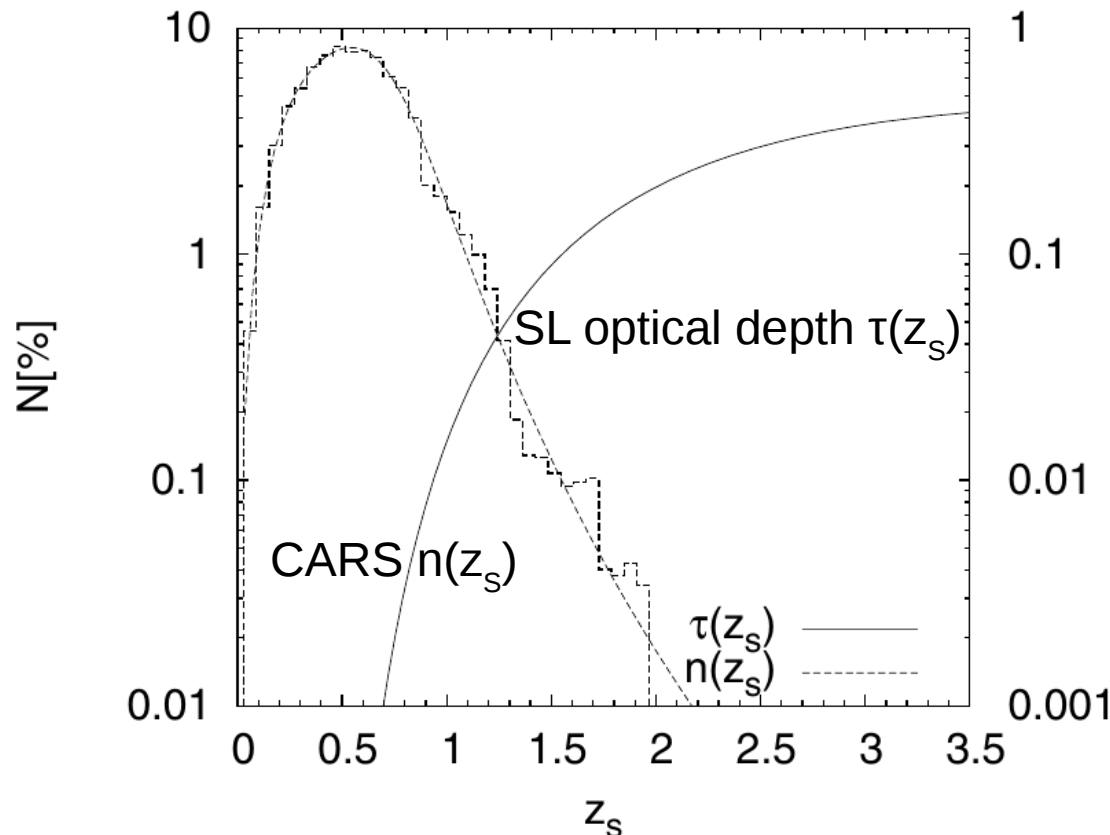


- local brightness distribution, length, length-to-width & brightness filters can remove a large fraction of spurious detections
- COSMOS: depending on initial settings, ~98% less spurious

Select likely arcs by colour

with Matteo Maturi & Sebastian Mizera

Lensing optical depth $\tau_d(z_s) = \frac{1}{4\pi D_s^2} \int_0^{z_s} \int_0^\infty N(m, z) \sigma_d(m, z, z_s) dz dm$



Lensing cross-section

$$\sigma_d(z_s) = \left(\frac{D_s}{D_l} \theta_0 \right)^2 \int_{A_{LW>d}} \frac{d^2 x}{|\mu(x)|}$$

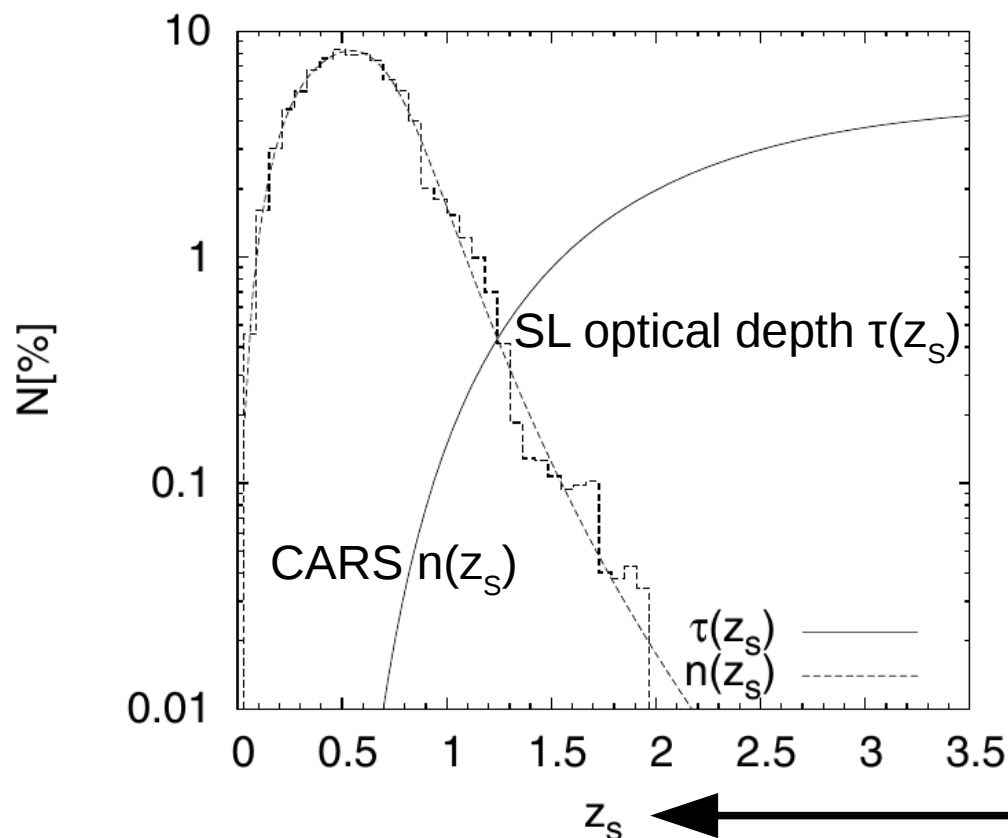
Sheth & Tormen differential mass function

$$N(m, z)$$

Select likely arcs by colour

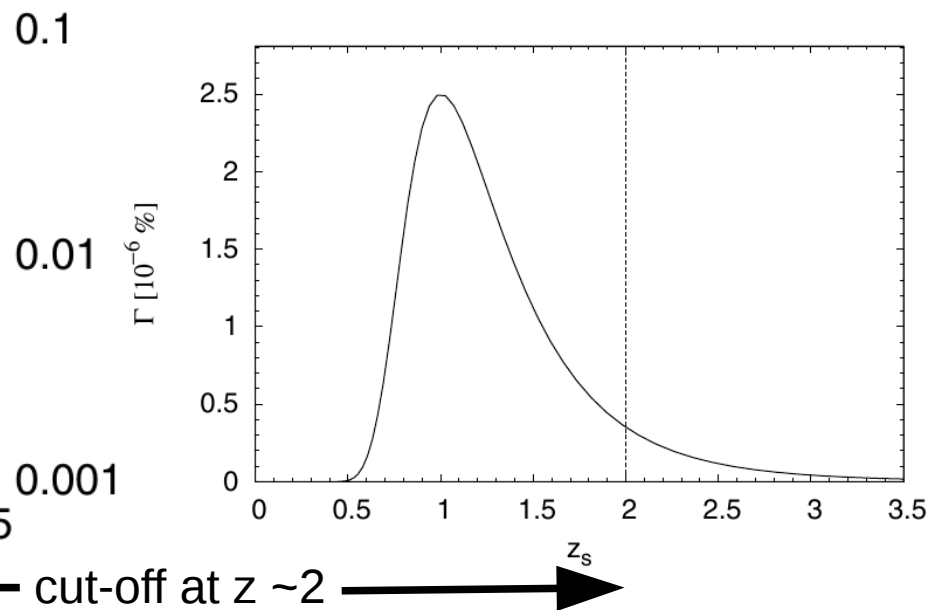
with Matteo Maturi & Sebastian Mizera

Lensing optical depth $\tau_d(z_s) = \frac{1}{4\pi D_s^2} \int_0^{z_s} \int_0^\infty N(m, z) \sigma_d(m, z, z_s) dz dm$



Expected arcs from sources at redshift z_s :

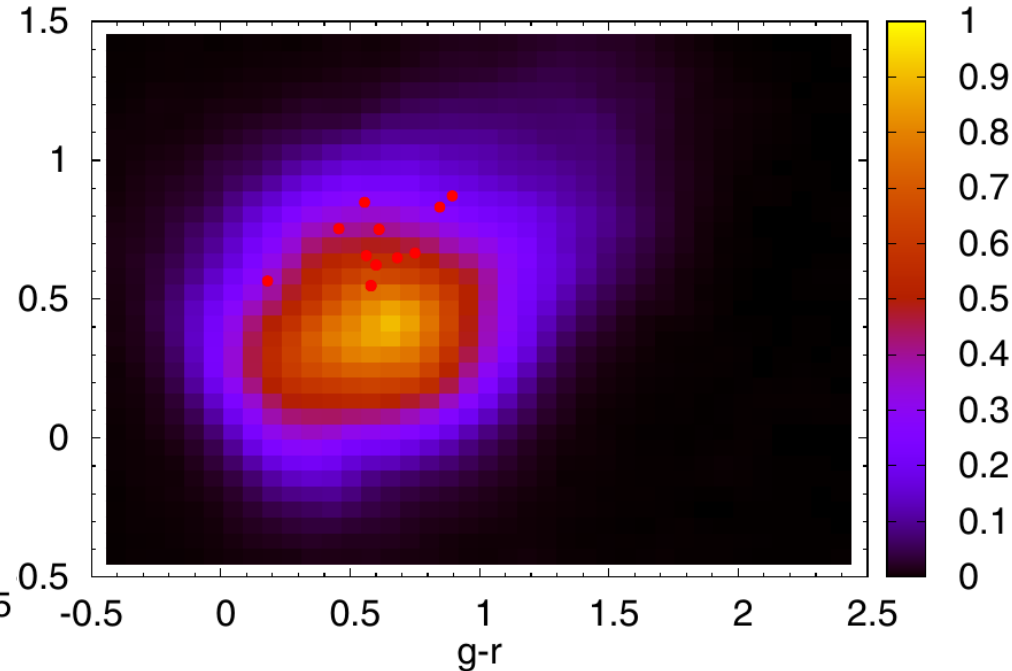
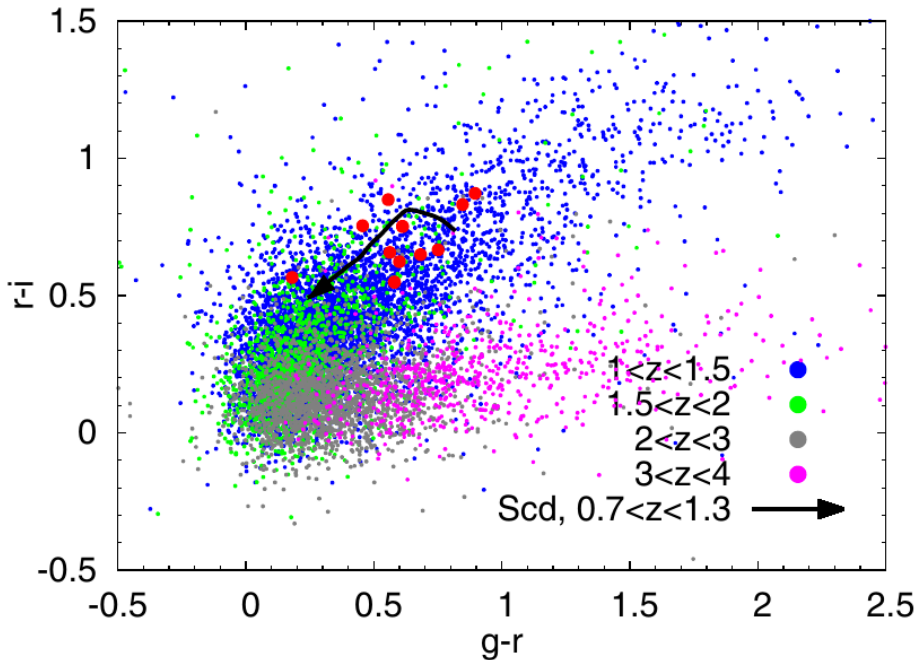
$$\Gamma_d(z_s) = \tau_d(z_s) n(z_s)$$



Select likely arcs by colour

COSMOS galaxies,
Scd Redshift (arrow),
+known candidates in (r-i,g-r)

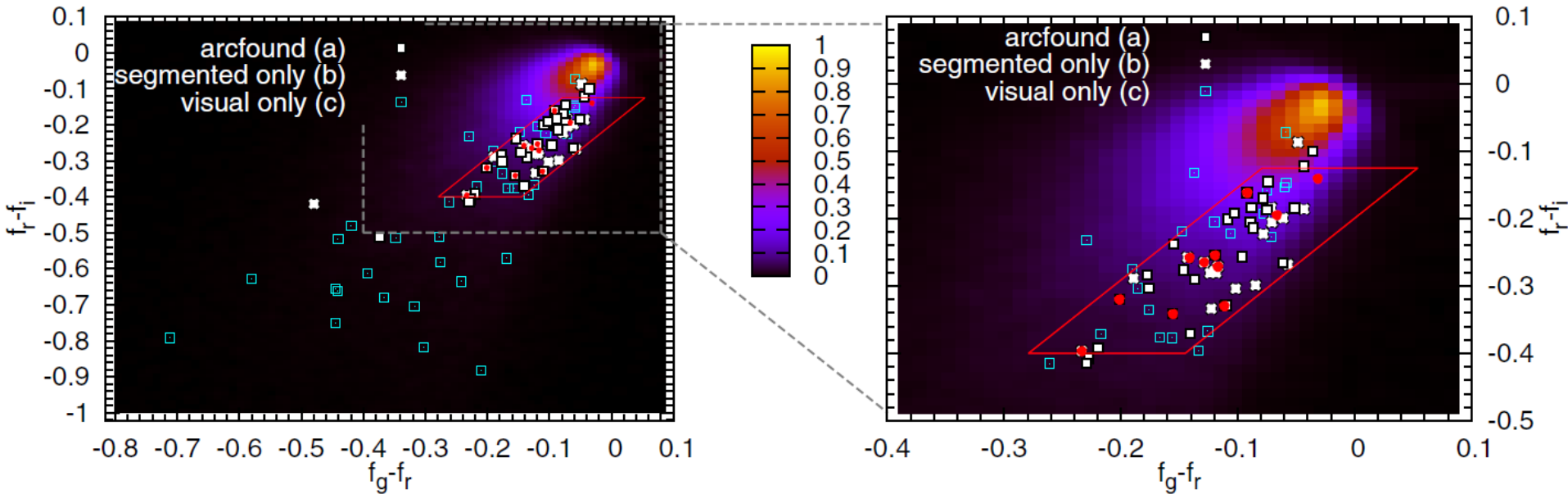
arcfinder detections
+ known candidates in (r-i,g-r)
(A. More 2012, R. Cabanac 2007)



Select likely arcs by colour

arcfinder detections (map) +
known (red) +
arcfinder candidates (white) +
visual candidates (cyan)

$(f_r - f_i, f_g - f_r)$ colour space,
flux instead of magnitudes



- Most spurious detections can be ignored based on colour!

Application to CARS

with Matteo Maturi & Sebastian Mizera (Maturi 2014)

CARS (CFHTLS Archive Research Survey):

- 37 deg², depth $r' = 24.36$, PSF FWHM $< 0.75''$
- about $7 \cdot 10^6$ galaxies

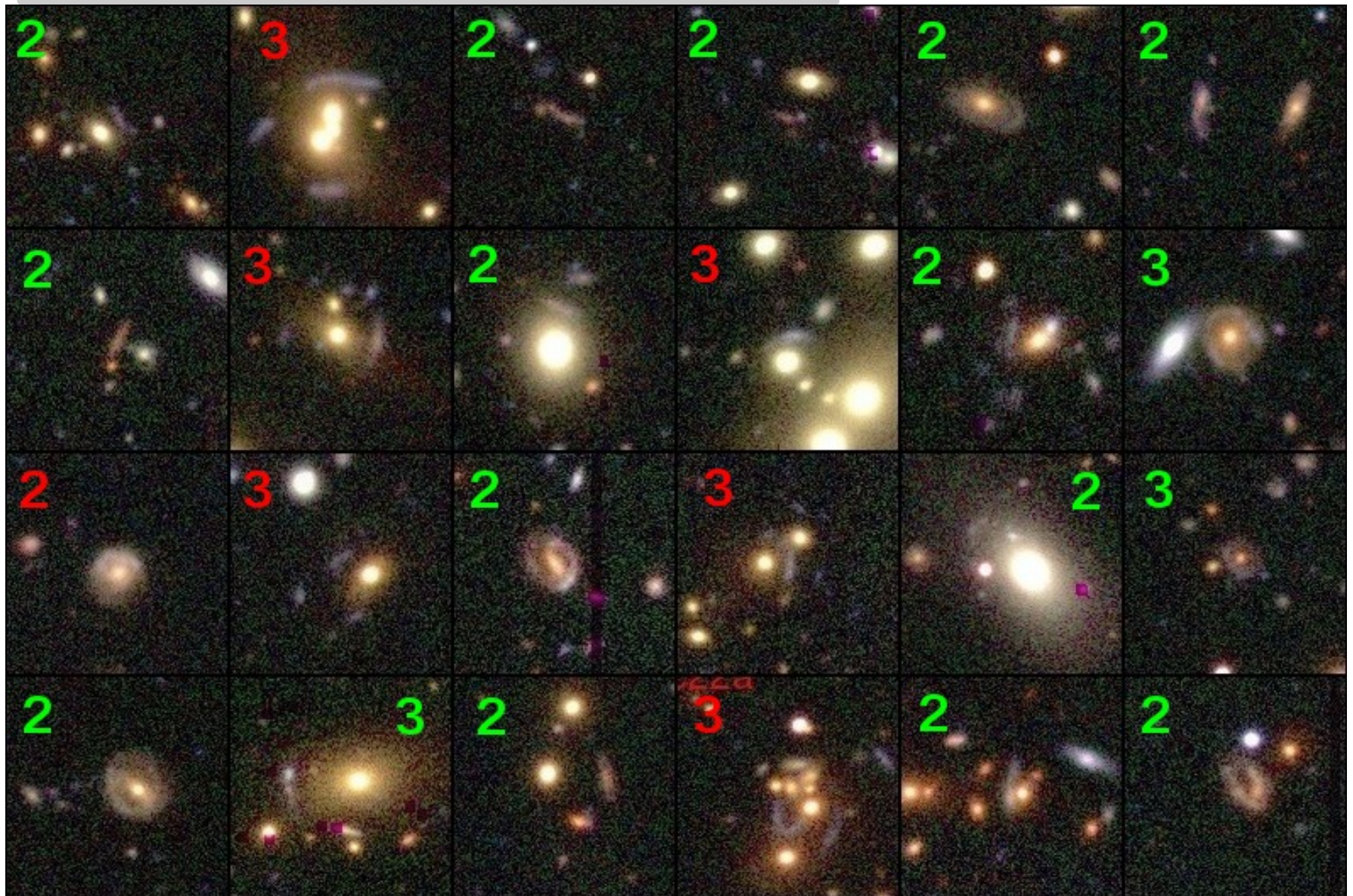
Spurious detections:

- 36026 detections with $L > 3''$ & $L/W > 4$
- 5597 survived colour selection \Rightarrow contamination reduced by ~ 6.4

Arcs:

- 27 known candidates (Cabanac et al. 07, More et al. 12)
- **90 candidates** after visual inspection
- classification: 1 (unlikely) to 3 (very likely)
- 49 candidates detected by automatic arcfinder
- 29 (out of 36026) survived length and L/W criteria: $L > 3''$ & $L/W > 4$
- 24 (out of 5597) survived colour selection
 \Rightarrow 83% completeness of colour cuts

Application to CARS: 24 candidates



Application to CARs: 5 candidates lost



found and segmented by arcfinder, failed colour cut

problems challenges:

colour contamination by background + lens

low signal to noise of colour

Application to CARS: detection failures

visual classification 3
but not detected



dispersed
shallow profile



bright cores



blending



invalid pixels,
scale

Future

- Status:
no a priori information on lens galaxy used
=> spurious detections in the field
- Goal (done for COSMOS): remove detections using catalogues
- Status:
algorithm developed for cluster lenses, applied to galaxy lens search
=> difficult to detect blended arcs
=> colour contamination by background lens
- Goal: galaxy subtraction (use colour, subtract PCA modelled lens)
- Status:
single image detection (stacked g' and r')
=> ignores any colour information for segmentation
- Goal: adapt detection to run simultaneously on multiple bands