



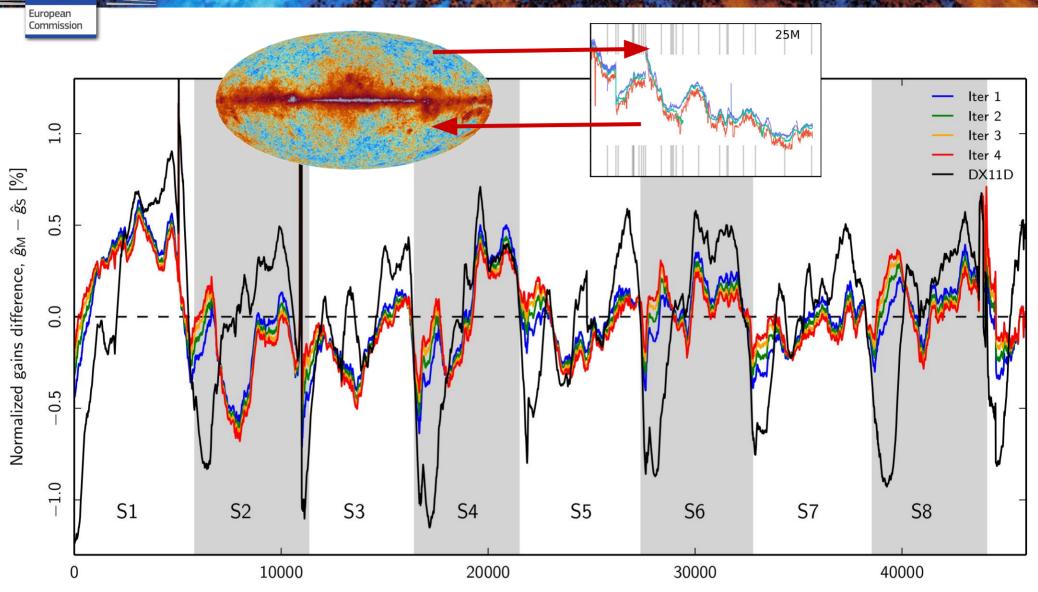
Systematics and degeneracies in CMB observations and the importance of global analysis

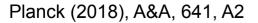


"CMB systematics and calibration focus workshop", November 30, 2020



Critical question: How well do we really know the gain?



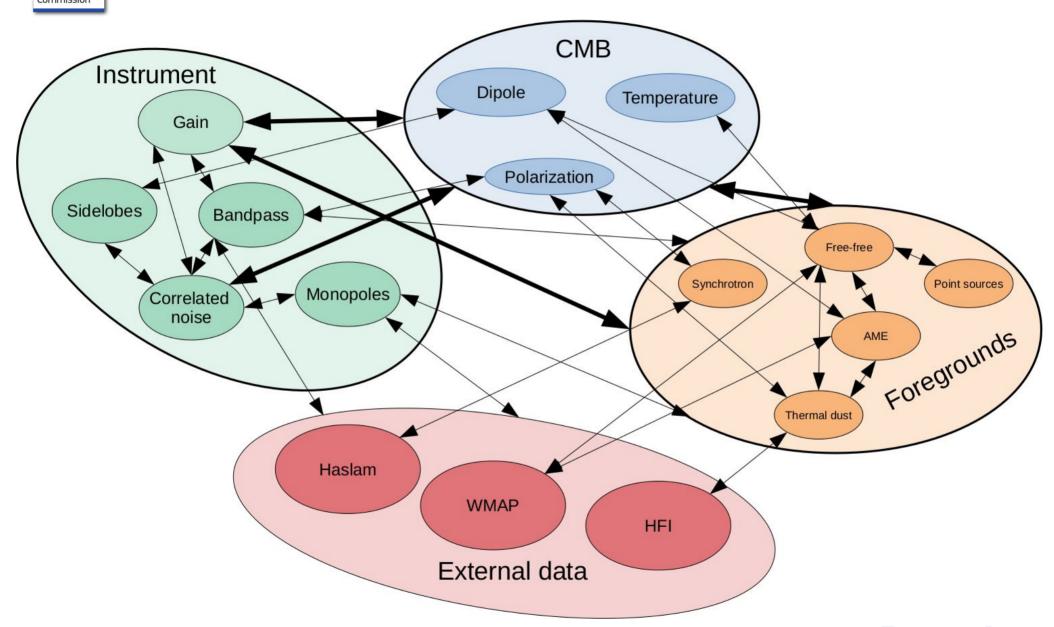




Pointing ID

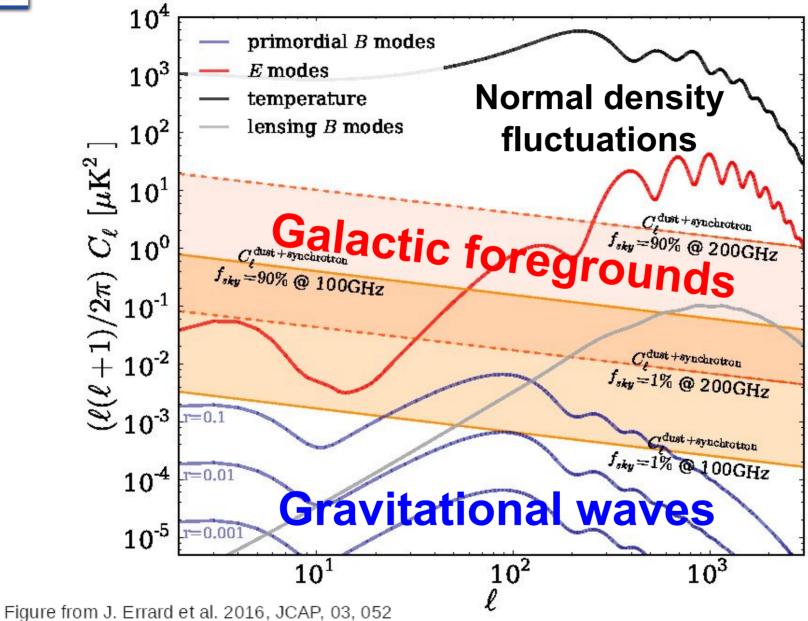


"Planck LFI dependency map"





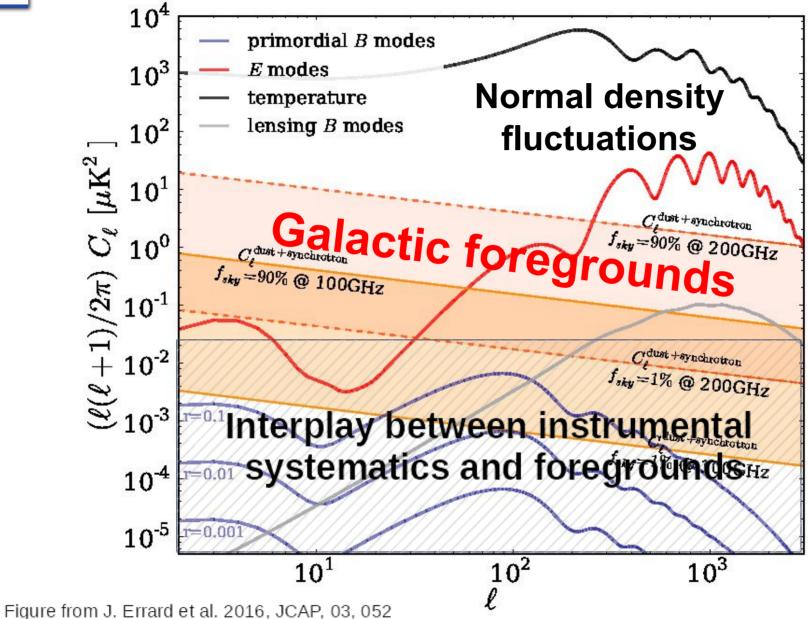










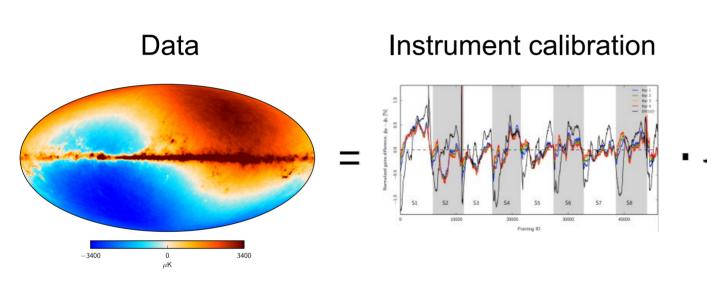




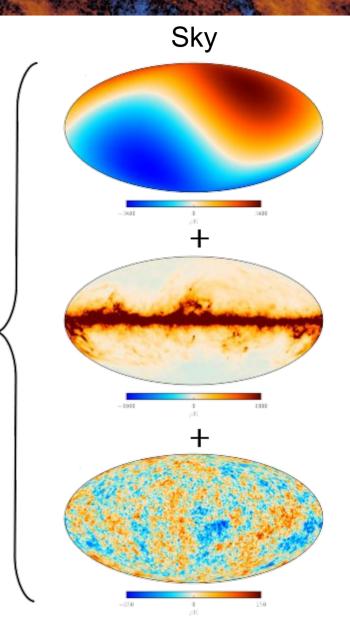




Need to know the instrument to measure the sky...



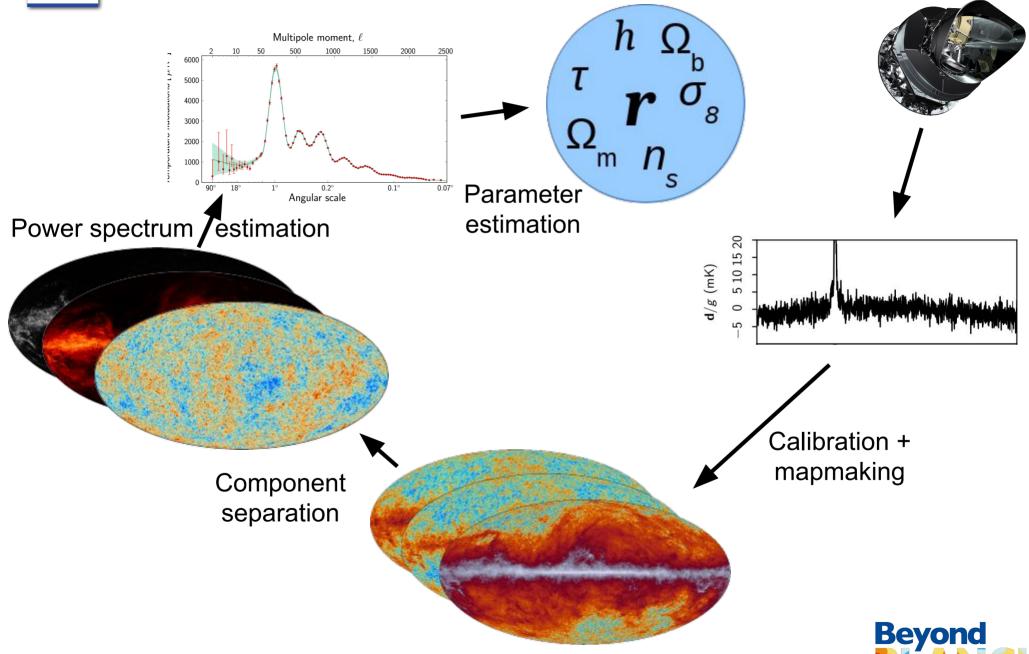
... but also need to know the sky in order to calibrate the instrument!





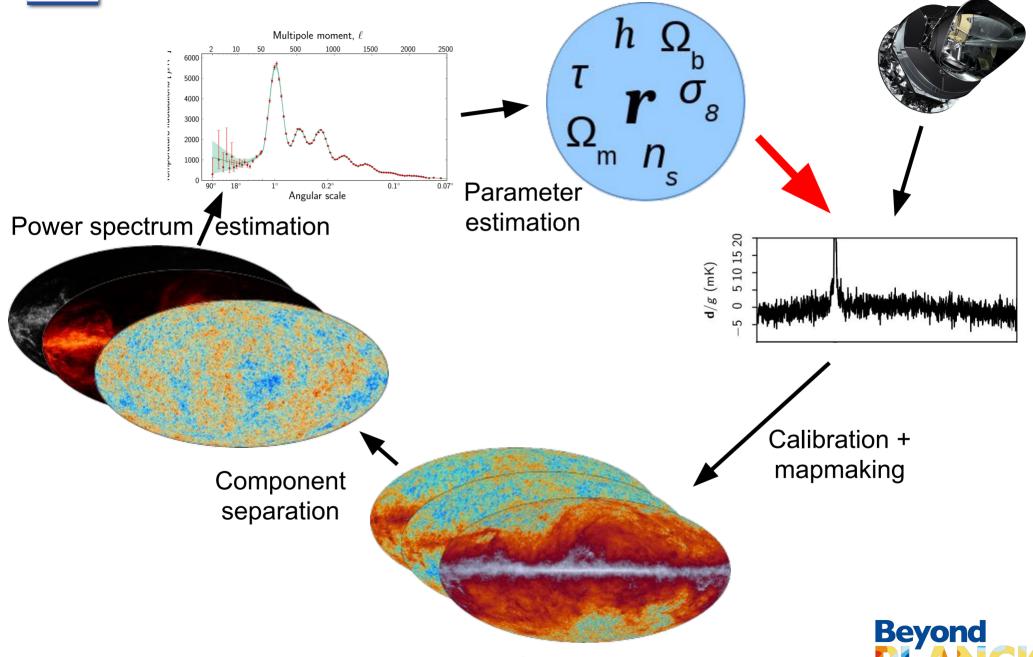


Classic CMB analysis



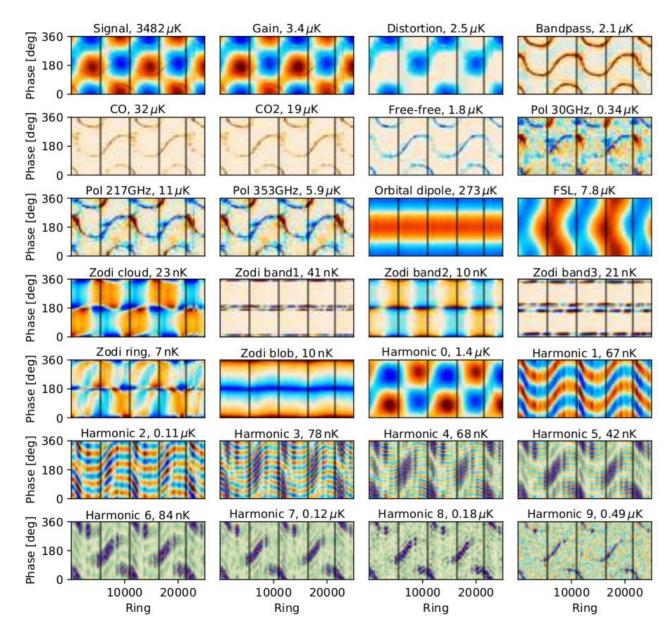


End-to-end iterative analysis





NPIPE (Planck PR4) and SROLL2



NPIPE = Joint low-level calibration and mapmaking through generalized linear regression of TOD templates

SROLL2 (Delouis et al. 2019) is a similar initiative, adopting a different gain+ADC model





Starting point for BeyondPlanck

Could we solve some of the outstanding issues with Planck LFI 2018 by:

- 1. speeding up the iteration process, and perform hundreds of component separation + calibration iterations, not just four?
- 2. break internal Planck-specific degeneracies using external data, in particular WMAP?

The name BeyondPlanck was chosen to

- recognize that this work builds on, and is a natural continuation of, the official Planck analysis effort
- emphasize that this involves not only Planck, but also other data sets





Main goals for BeyondPlanck

Main goals of the BeyondPlanck project:

- Implement an end-to-end analysis framework for current and future CMB experiments using Planck experience
- Demonstrate this framework with Planck LFI data
- Make software and results publicly available under an OpenSource license





The BeyondPlanck pipeline in one slide

1. Write down an explicit parametric model for the observed data:

$$d_{j,t} = g_{j,t} \mathsf{P}_{tp,j} \left[\mathsf{B}^{\mathrm{symm}}_{pp',j} \sum_{c} \mathsf{M}_{cj}(\beta_{p'}, \Delta^{j}_{\mathrm{bp}}) a^{c}_{p'} + \mathsf{B}^{\mathrm{asymm}}_{j,t} \left(s^{\mathrm{orb}}_{j} + s^{\mathrm{fsl}}_{t} \right) \right] + n^{\mathrm{corr}}_{j,t} + n^{\mathrm{w}}_{j,t}.$$

Let ω = {all free parameters}

2. Derive the joint posterior distribution with Bayes' theorem:

$$P(\omega \mid \boldsymbol{d}) = \frac{P(\boldsymbol{d} \mid \omega)P(\omega)}{P(\boldsymbol{d})} \propto \mathcal{L}(\omega)P(\omega).$$

3. Map out $P(\omega \mid d)$ with standard Markov Chain Monte Carlo (MCMC) methods





The BeyondPlanck data model

Data

 $d_{j,t}$

Bandpass

Sidelobe pickup

White noise

W

$$\omega \equiv \{g, \Delta_{\text{bp}}, \boldsymbol{n}_{\text{corr}}, \boldsymbol{a}_i, \beta_i, C_{\ell}, \ldots\}$$

$$+\sum_{j=1} a_{\rm src}^{j} \left(\frac{1}{v_{0,\rm src}}\right)$$

Point sources





The posterior distribution

$$P(\omega \mid d) = \frac{P(d \mid \omega)P(\omega)}{P(d)} \propto \mathcal{L}(\omega)P(\omega).$$
Gaussian noise

$$\mathcal{L}(\omega) = \frac{e^{-\frac{1}{2}(\boldsymbol{d} - \boldsymbol{s}(\omega))^t N_{\text{wn}}^{-1}(\boldsymbol{d} - \boldsymbol{s}(\omega))}}{\sqrt{|N_{\text{wn}}|}}$$

•
$$P(f_{knee})$$
 = lognorm(DPC, 0.1)

•
$$P(\beta_{synch}) = -3.1 \pm 0.1$$

•
$$P(T_{dust})$$
 = $\delta(T_{dust} - T_{dust, HFI})$
• $P(a_{ff})$ = $N(a_{ff,Planck}, \sigma^2_{l,ff})$

•
$$P(a_{ff})$$
 = $N(a_{ff,Planck}, \sigma^2_{/ff})$

•
$$P(a_{ame}) = N(\alpha \cdot m_{857}, \sigma^2_{l,ame})$$





How to sample from big distributions?



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Gibbs sampling

From Wikipedia, the free encyclopedia

In statistics, **Gibbs sampling** or a **Gibbs sampler** is a Markov chain Monte Carlo (MCMC) algorithm for obtaining a sequence of observations which are approximated from a specified multivariate probability distribution, when direct sampling is difficult. This sequence can be used to approximate the joint distribution (e.g., to generate a histogram of the distribution); to approximate the marginal distribution of one of the variables, or some subset of the variables (for example, the unknown parameters or latent variables); or to compute an integral (such as the expected value of one of the variables). Typically, some of the variables correspond to observations whose values are known, and hence do not need to be sampled.

Part of a series on **Bayesian statistics**



Theory

Admissible decision rule

Bayesian efficiency

Bayesian probability

Probability interpretations

Bayes' theorem • Bayes factor

Bayesian inference • Bayesian network •

Prior • Posterior • Likelihood

Conjugate prior • Posterior predictive

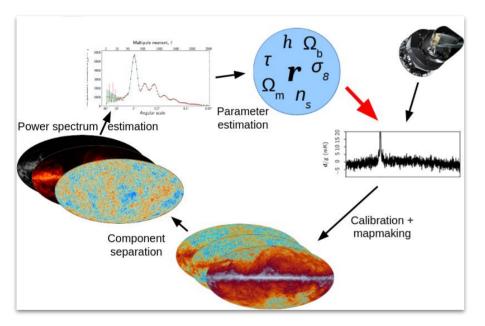
Hyperparameter • Hyperprior





The BeyondPlanck Gibbs sampler

What we want to do:



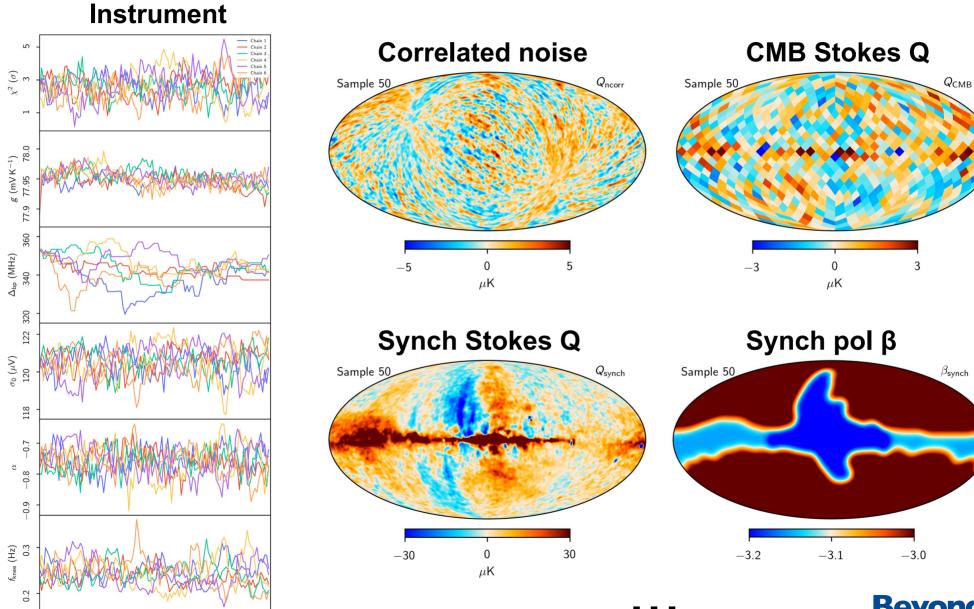
How we actually do it:

$$egin{aligned} oldsymbol{g} &\leftarrow P(oldsymbol{g} &\mid oldsymbol{d}, & \xi_n, \Delta_{\mathrm{bp}}, oldsymbol{a}, \beta, C_\ell) \ oldsymbol{n}_{\mathrm{corr}} &\leftarrow P(oldsymbol{n}_{\mathrm{corr}} \mid oldsymbol{d}, oldsymbol{g}, & \xi_n, \Delta_{\mathrm{bp}}, oldsymbol{a}, \beta, C_\ell) \ eta_n &\leftarrow P(\xi_n &\mid oldsymbol{d}, oldsymbol{g}, oldsymbol{n}_{\mathrm{corr}}, & \Delta_{\mathrm{bp}}, oldsymbol{a}, \beta, C_\ell) \ \Delta_{\mathrm{bp}} &\leftarrow P(\Delta_{\mathrm{bp}} \mid oldsymbol{d}, oldsymbol{g}, oldsymbol{n}_{\mathrm{corr}}, \xi_n, \Delta_{\mathrm{bp}}, & A_{\mathrm{bp}}, A_{\mathrm{corr}}, \delta, \lambda_{\mathrm{bp}}, A_{\mathrm{bp}}, A_{\mathrm{corr}}, \delta, \lambda_{\mathrm{bp}}, A_{\mathrm{bp}}, A_{\mathrm{corr}}, \delta, \lambda_{\mathrm{bp}}, A_{\mathrm{bp}}, A_{\mathrm{bp$$





Main product: Ensemble of full sample sets



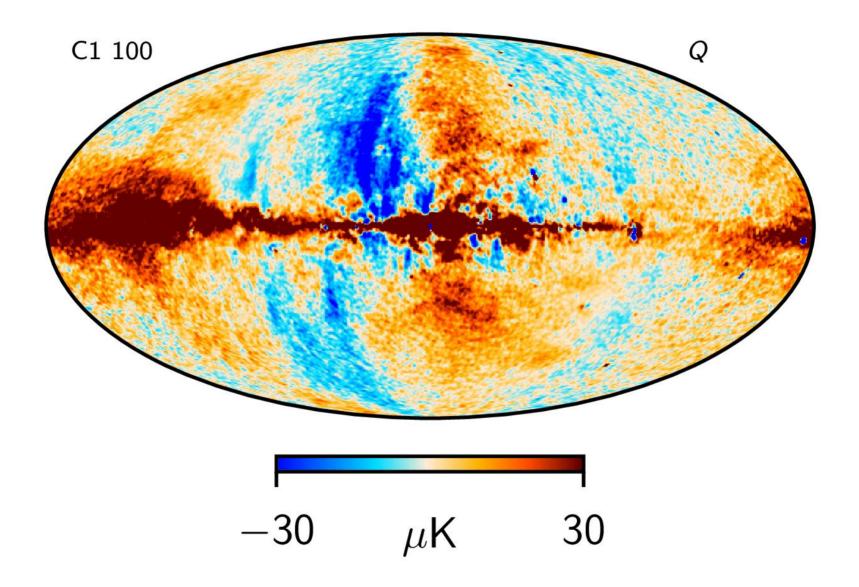


100

Gibbs iteration

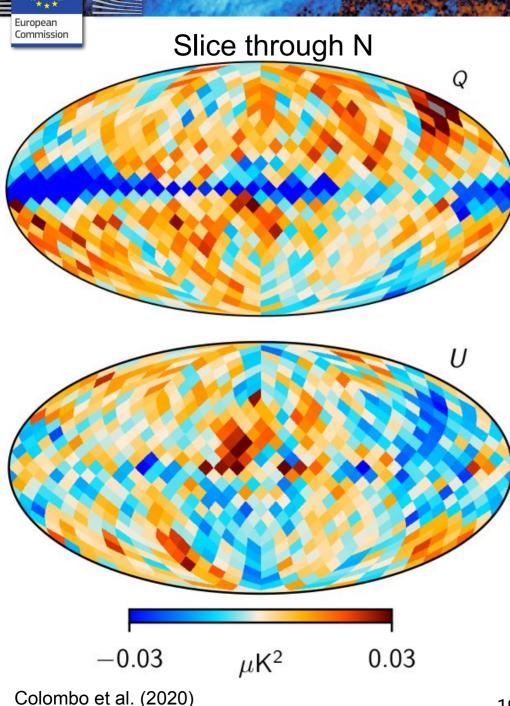


Frequency maps: 30 GHz Stokes Q





Sample-based low-l likelihood



Compute low-resolution CMB map and covariance matrix directly from samples:

$$\hat{\mathbf{s}}_{\text{CMB}} = \left\langle \mathbf{s}_{\text{CMB}}^{i} \right\rangle$$

$$\mathsf{N} = \left\langle (\mathbf{s}_{\text{CMB}}^{i} - \hat{\mathbf{s}}_{\text{CMB}})(\mathbf{s}_{\text{CMB}}^{i} - \hat{\mathbf{s}}_{\text{CMB}})^{t} \right\rangle$$

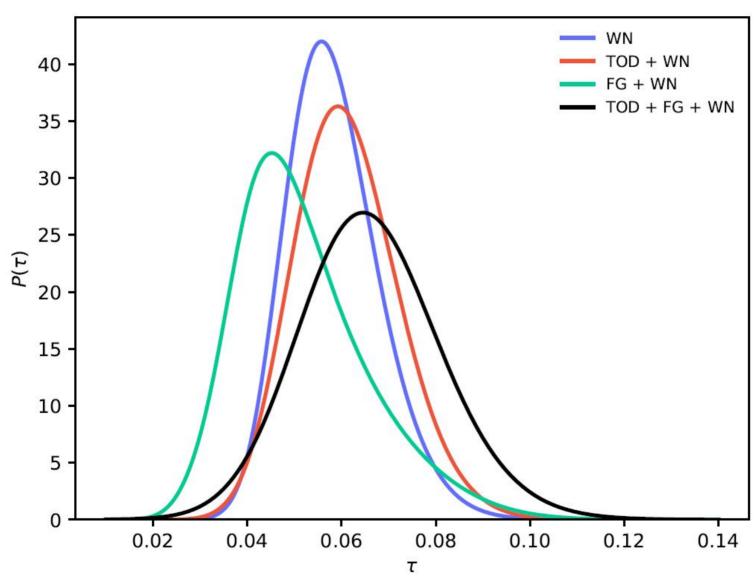
This is the first time uncertainties from gain, bandpass and a fine-grained foreground model have been consistently propagated into CMB low-l likelihood inputs

$$P(C_{\ell} \mid \hat{\mathbf{s}}_{\text{CMB}}) \propto \frac{e^{-\frac{1}{2}\hat{\mathbf{s}}_{\text{CMB}}^{t}(S(C_{\ell}) + \mathsf{N})^{-1}\hat{\mathbf{s}}_{\text{CMB}}}}{\sqrt{|S(C_{\ell}) + \mathsf{N}|}}$$





Uncertainties on the optical depth of reionization



Paradiso et al. (2020)





Computational resource requirements

Ітем		30 GHz	44 GHz	70 GHz	Sum
Data volume					
Uncompressed data volume		761 GB	1633 GB	5 522 GB	7 915 GB
Compressed data volume/RAM requirements		86 GB	178 GB	597 GB	861 GB
Processing time (cost per run)					
TOD initialization/IO time		176 sec	288 sec	753 sec	1217 sec
Other initialization					663 sec
Total initializa					1880 sec
Gibbs sampling si	bbs sampling si				
Data decompre	2.5 Hours/sample				393 sec
TOD projection					330 sec
Sidelobe evalua					480 sec
Orbital dipole	72-core node with 1.5 TB RAM				449 sec
Gain sampling					94 sec
Correlated nois					3138 sec
TOD binning (498 sec	
Loss due to po				502 sec	
Sum of other T				306 sec	
TOD processing cost per sumpre oso see 107 + see 1000 see				6396 sec	
Amplitude sampling, $P(\boldsymbol{a} \mid \boldsymbol{d}, \omega \setminus \boldsymbol{a})$				527 sec	
Spectral index sampling, $P(\beta \mid d, \omega \setminus \beta)$				1080 sec	
Other steps					149 sec
Total cost per sample					8168 sec

- Six independent Gibbs chains of each 200 samples were generated on 6 compute nodes
- Total wall production time for main run was 3 weeks
- Total CPU cost for main run was 220,000 CPU hours
 - For comparison, simulating one single traditional Planck Full Focal Plane 70 GHz realization costs O(10⁴) CPU hours (Planck Collaboration 2016, A&A, 596, A12)



**** ** European Commission

One-minute summary

1. Instrumental and astrophysical uncertainties are intimately coupled!

- Cannot know your instrument without knowing the sky, and cannot know the sky without knowing your instrument
- Assertion: A global instrument+foreground analysis strategy is a strict prerequisite for reaching r ≤ 10⁻², not a "nice-thing-to-have"

2. Know your instrument before commissioning!

- Measure 4π beams, bandpasses, ADCs etc. accurately on ground!
- Develop realistic and practical uncertainty models, and integrate these into your analysis pipeline

3. Degeneracies should be broken by additional data, not "clever algorithms"

- Design your own experiment to have as few "blind spots" as possible
- Use results from earlier experiments -- but do propagate uncertainties properly!

BeyondPlanck has implemented the first integrated end-to-end Bayesian CMB analysis pipeline, called Commander3

- This has been successfully applied to Planck LFI
- Computational costs are competitive with the traditional frequentist/simulation approach



**** * * European Commission

Online resources

BeyondPlanck project

Main webpage: https://beyondplanck.science

Products: https://products.beyondplanck.science

https://pla.esac.esa.int (subset; when papers are accepted)

Papers: https://beyondplanck.science/products/publications

Discussion forum: https://forums.beyondplanck.science

Commander

Source code : https://github.com/cosmoglobe/Commander

Documentation: https://docs.beyondplanck.science

Cosmoglobe

Main webpage: http://cosmoglobe.uio.no

Planck Legacy Archive (selected BeyondPlanck products coming soon)

Link: https://pla.esac.esa.int





The BeyondPlanck collaboration

EU-funded institutions



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"BeyondPlanck"

COMPET-4 program

PI: Hans Kristian Eriksen

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Collaborating projects:

"bits2cosmology"

ERC Consolidator Grant

PI: Hans Kristian Eriksen

Grant no: 772 253

o Period: April 2018 to March 2023

"Cosmoglobe"

• ERC Consolidator Grant

o PI: Ingunn Wehus

o Grant no: 819 478

Period: June 2019 to May 2024







Beyond



Commander

























